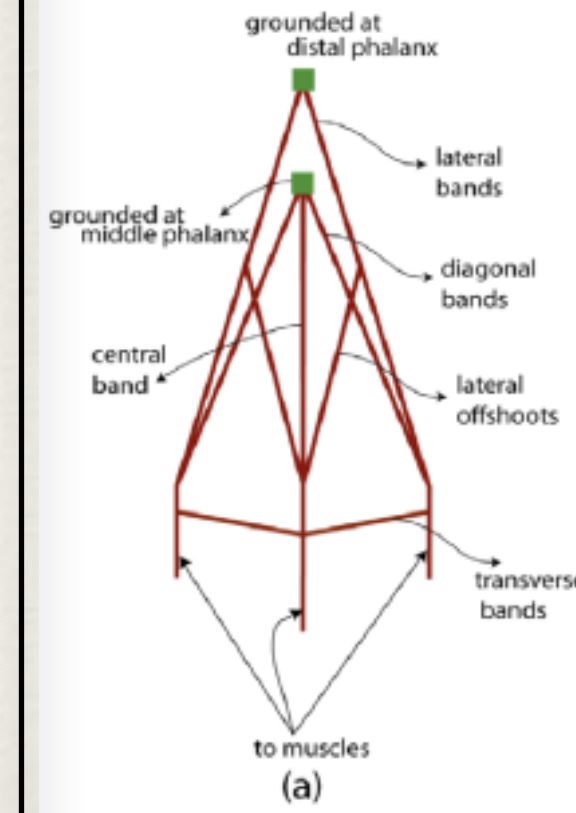
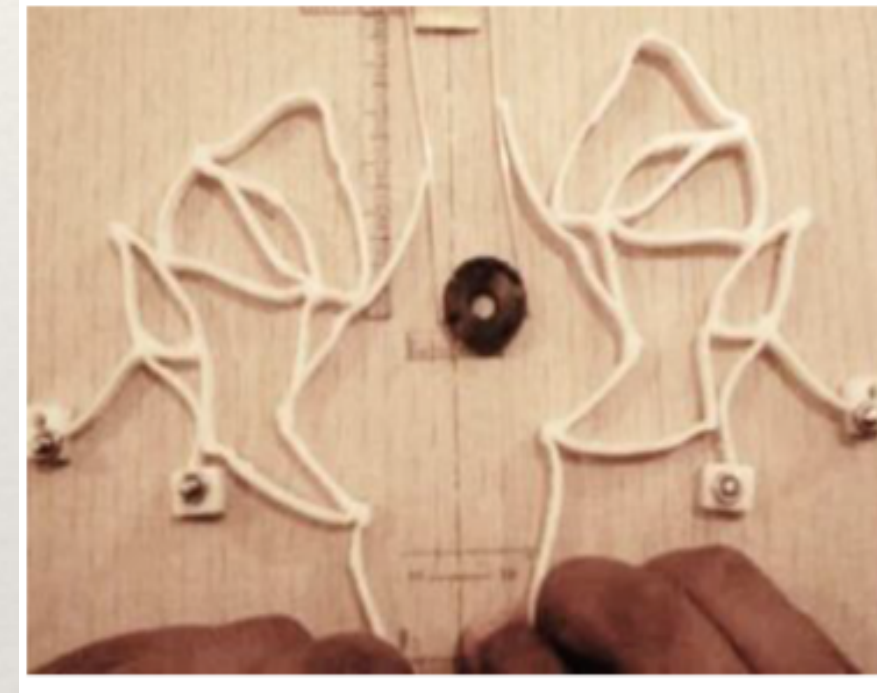
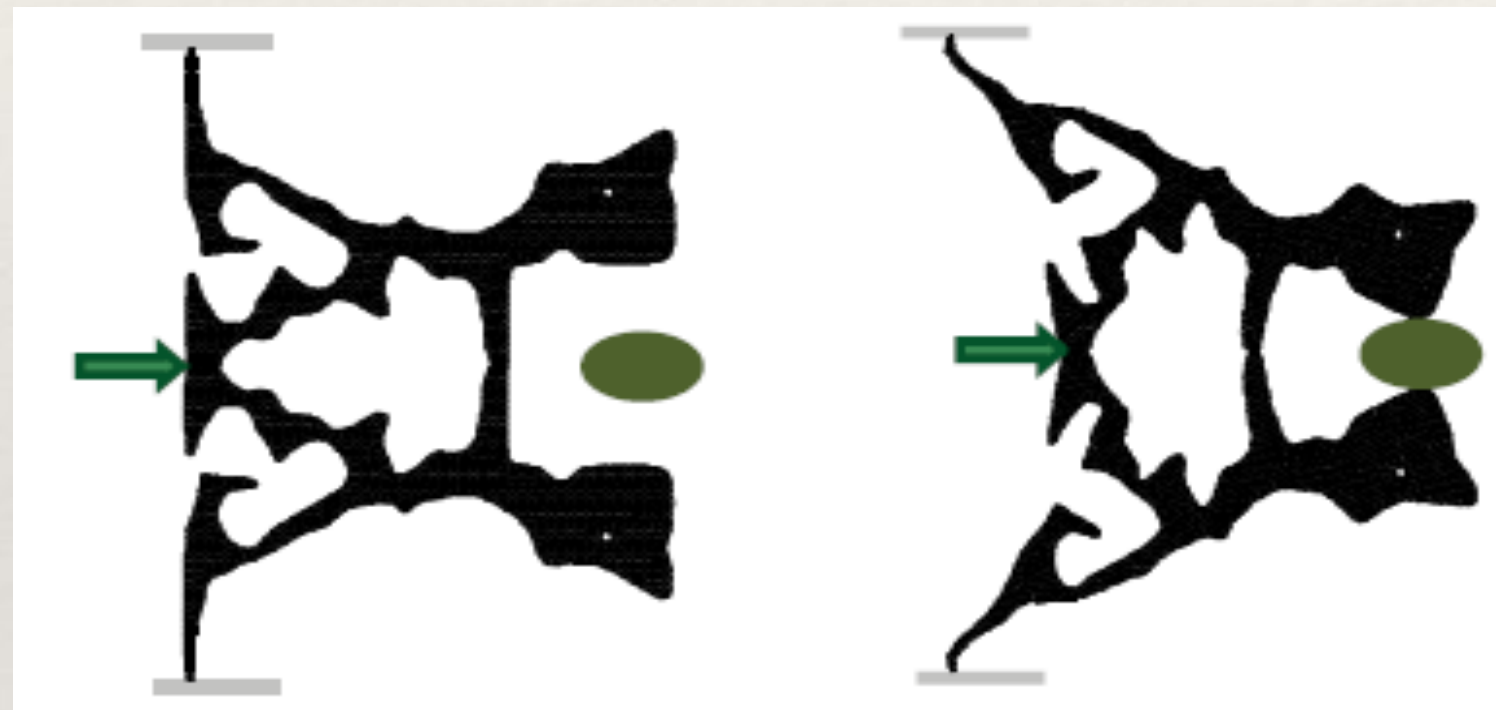
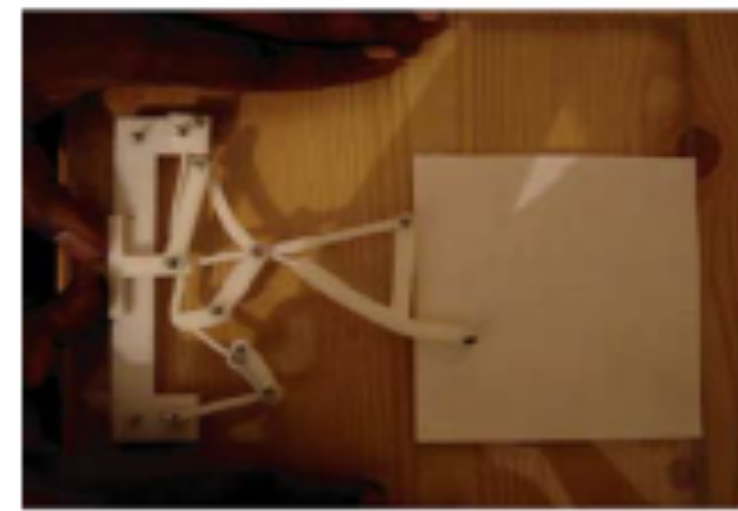
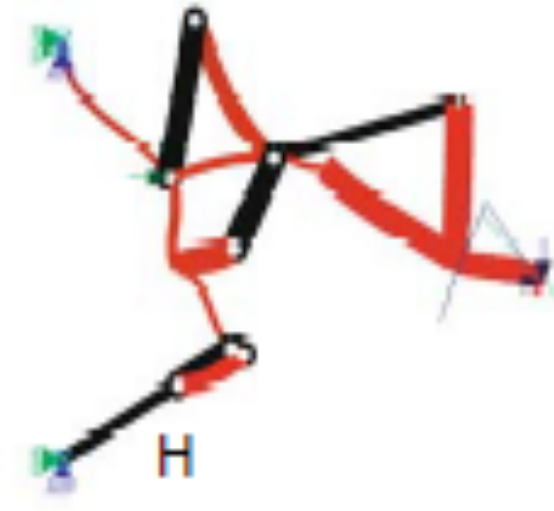
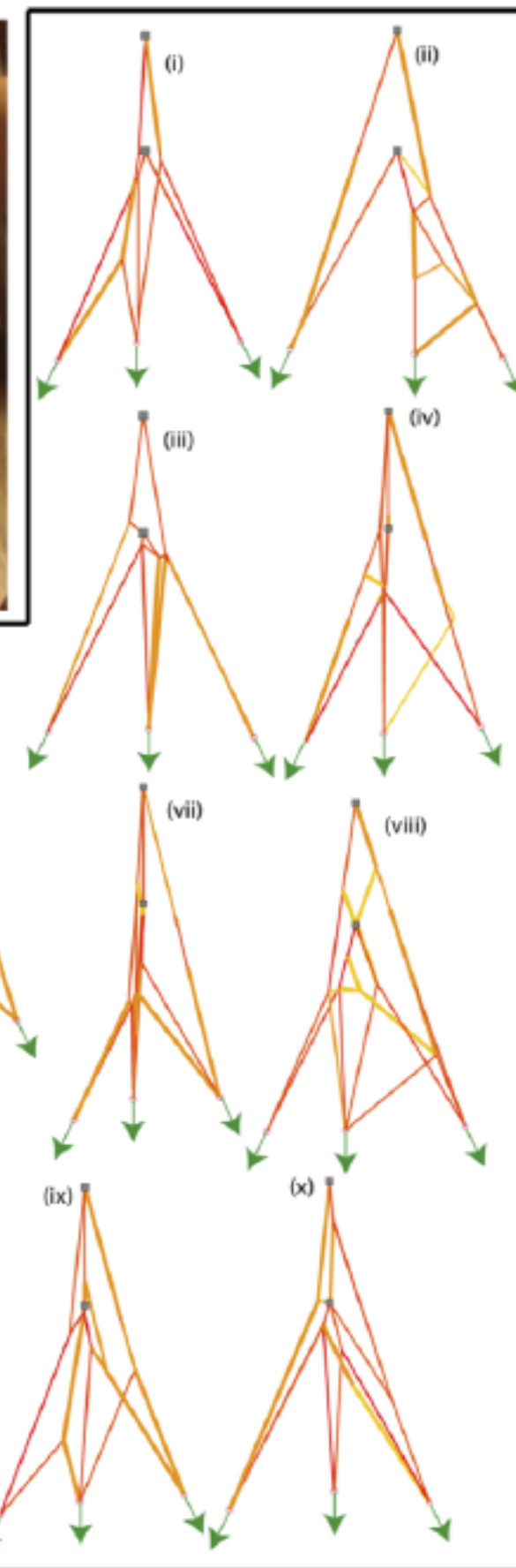




(a)



(b)



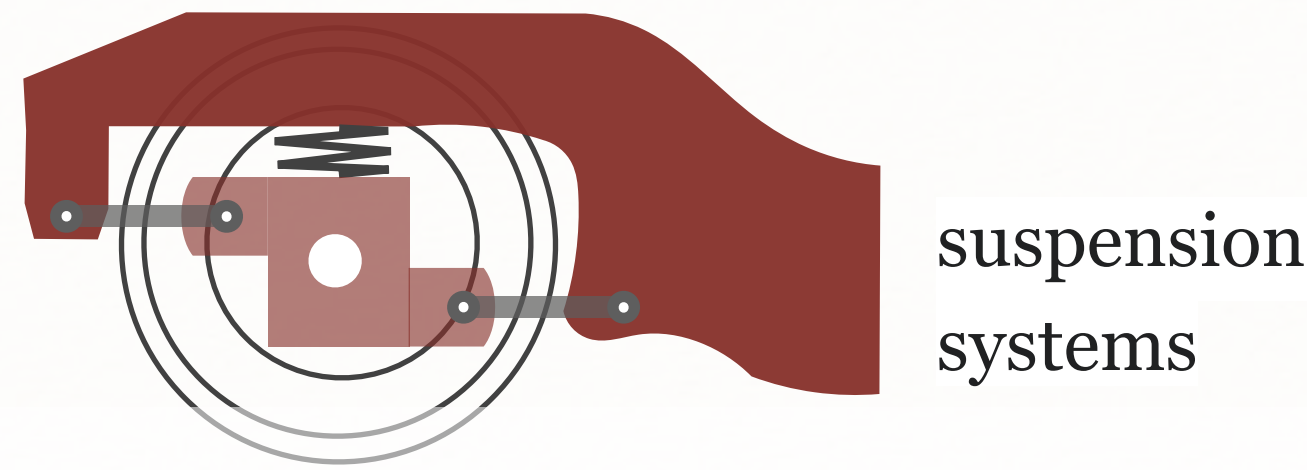
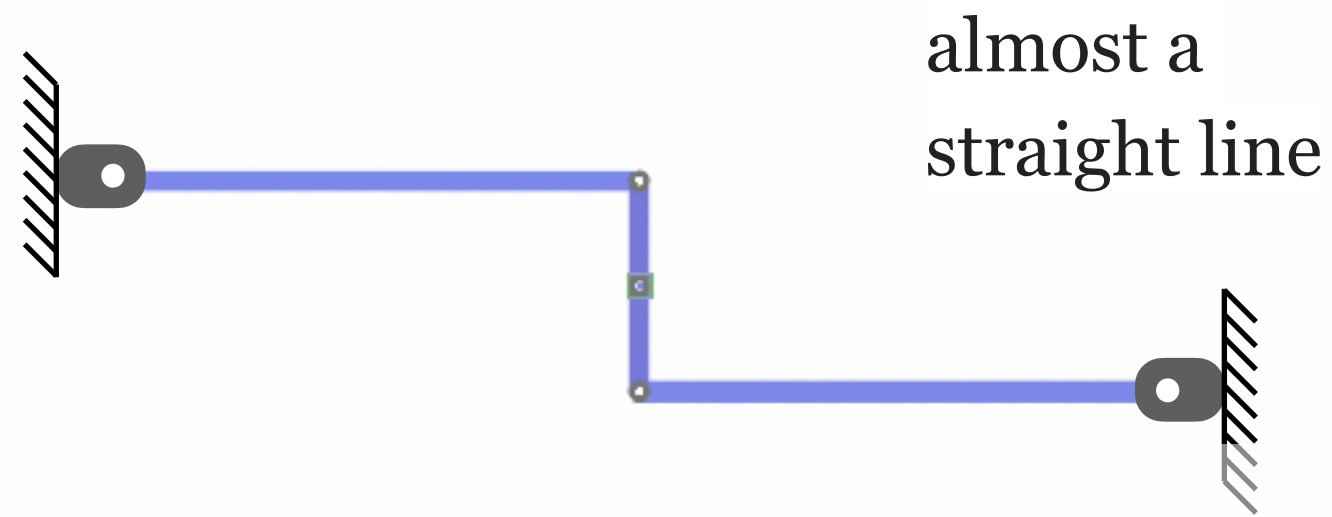
(c)



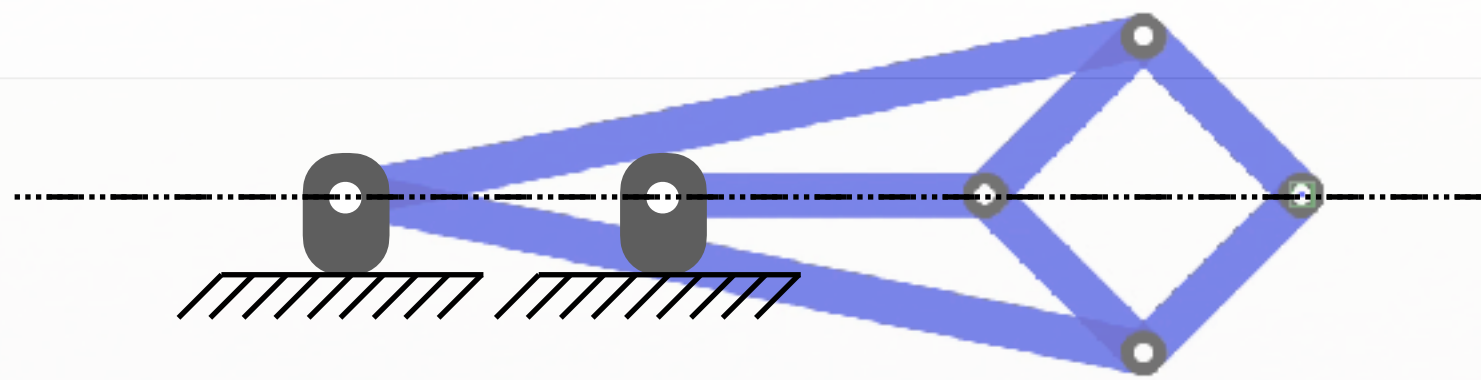
(d)

Compliant Mechanisms (ME 851)

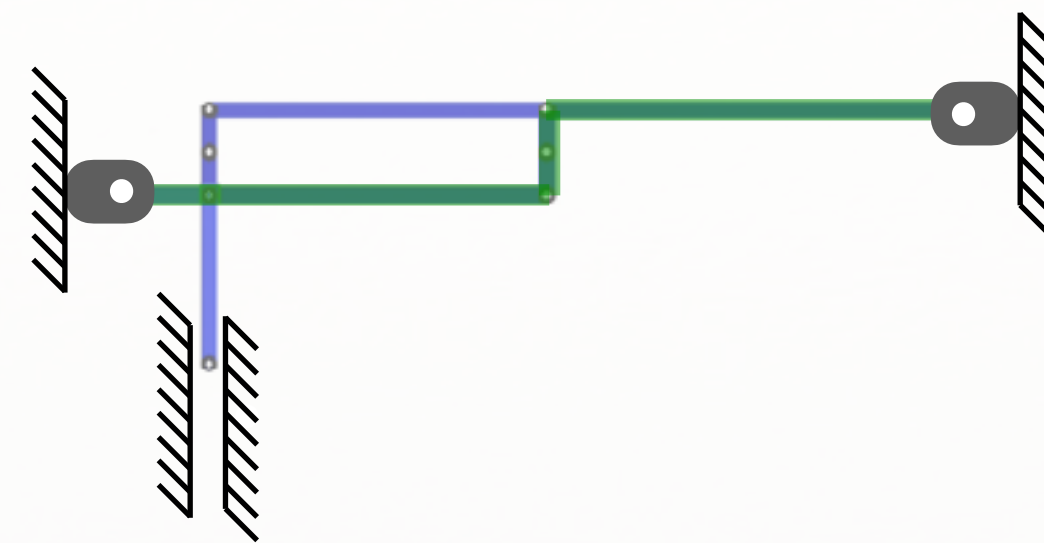
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Watt's (almost) Straight Liner



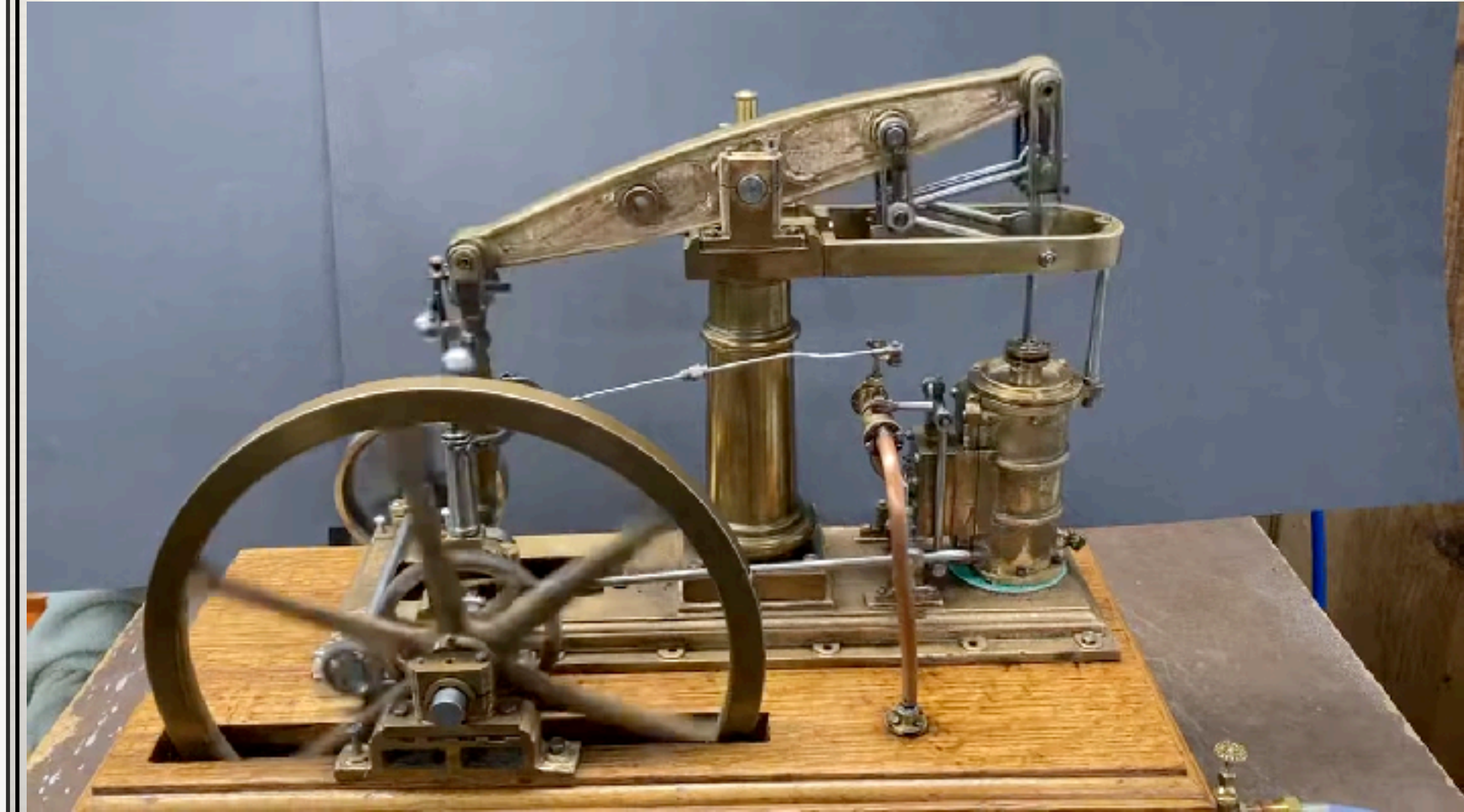
Peaucellier – Lipkin (exact) Straight Liner



Watt's Parallel motion Linkage

Function and Advantages

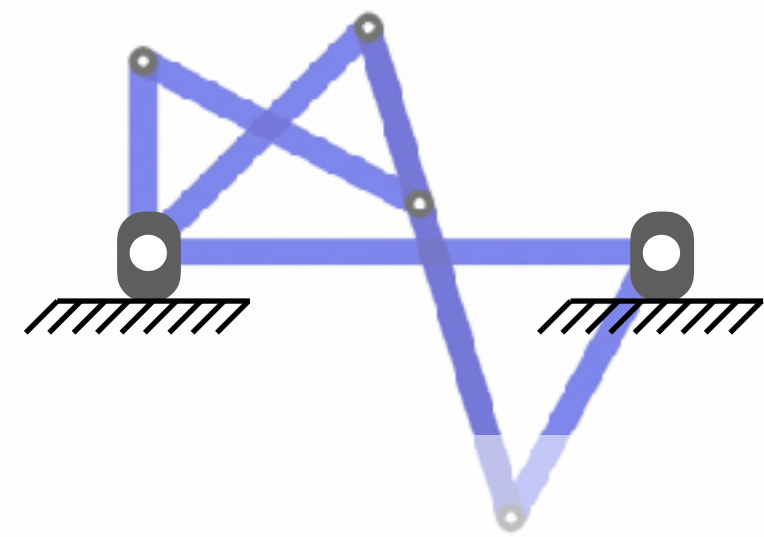
Force, Motion and/or Energy Transfer
 Function, Path and Motion Generation
 Repeatability



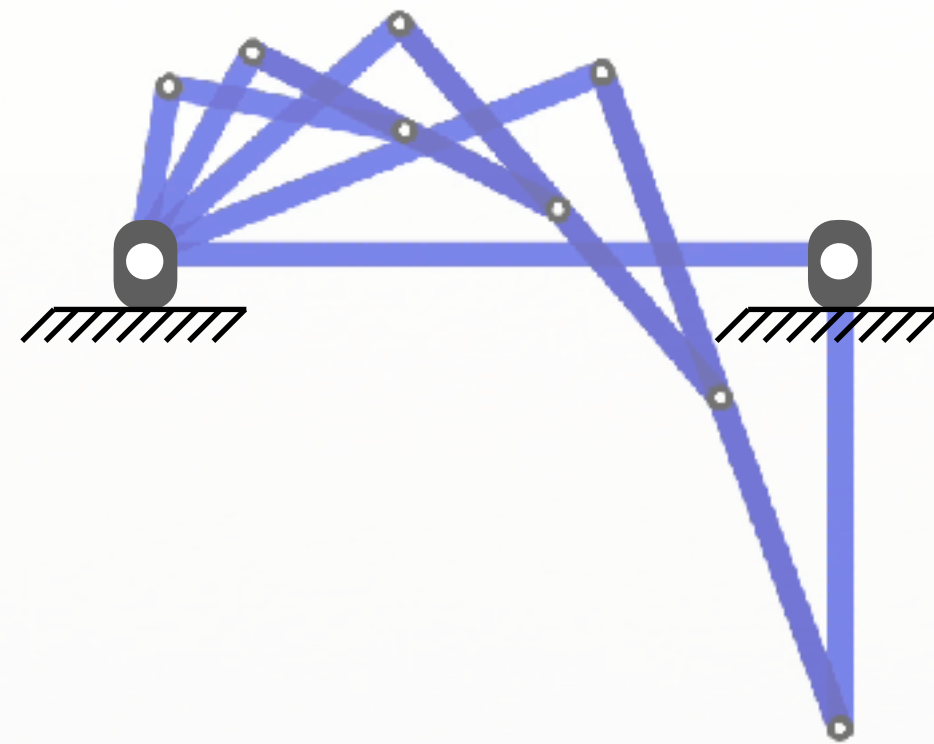
Brad E Smith: <https://www.youtube.com/watch?v=tFtsr1-l2vI>

Compliant Mechanisms (ME 851)

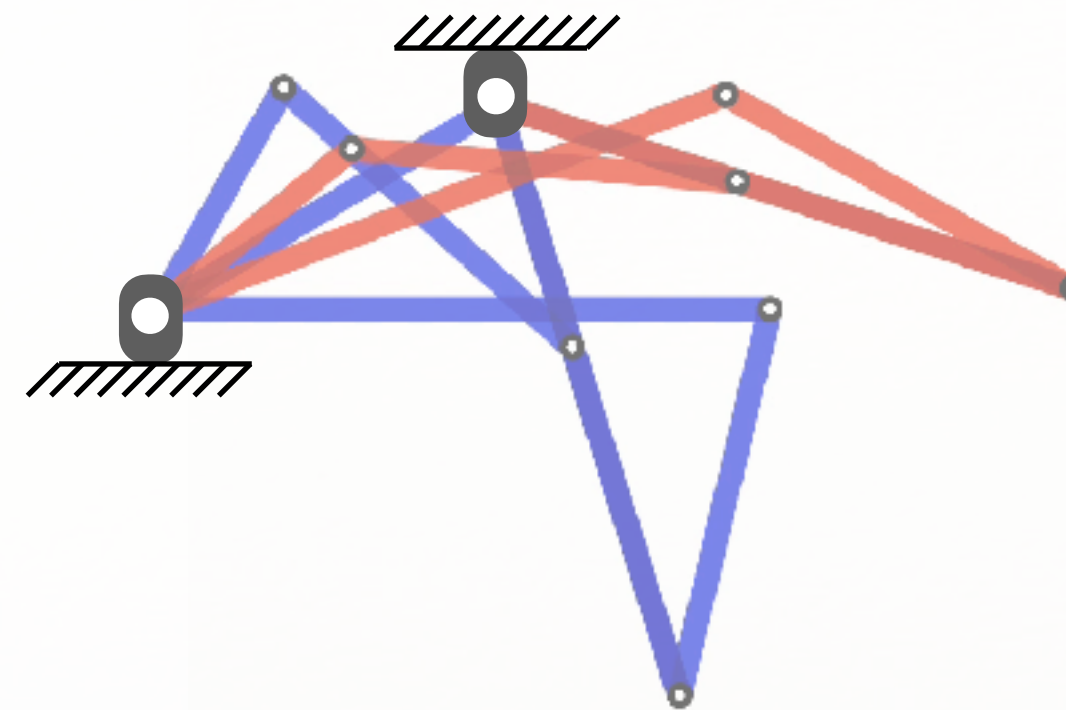
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Kempe's Angle Doubler



Kempe's Angle Quadrubler



Kempe's Angle Additor

Function and Advantages

Force, Motion and/or Energy Transfer
Function, Path and Motion Generation
Repeatability

Compliant Mechanisms (ME 851)

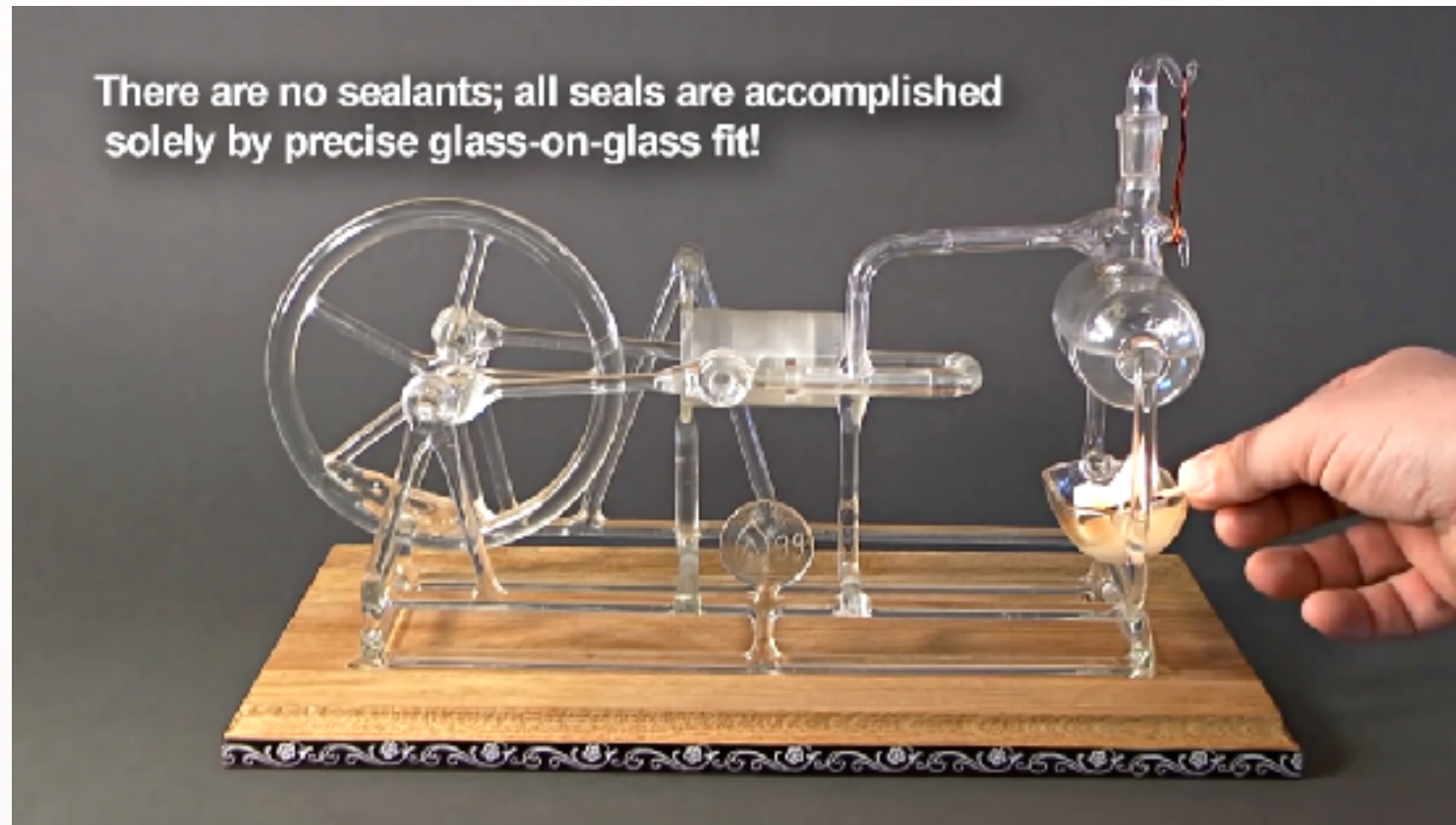
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Mechanisms: Designed, Existed and Developed over CENTURIES

Libraries and cool Animations available

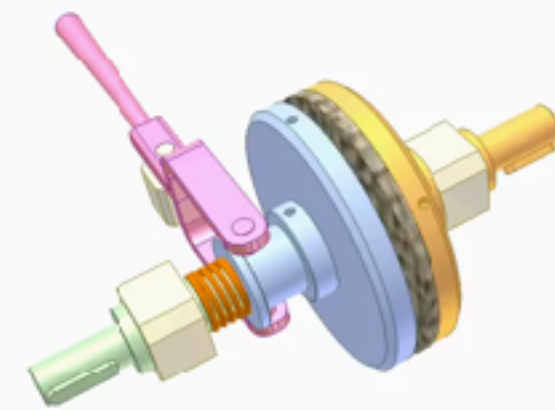
Stephenson's STEAM ENGINE

1700 ANIMATED MECHANICAL MECHANISMS

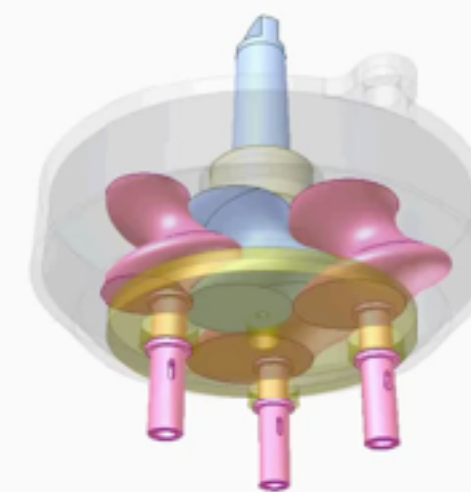


There are no sealants; all seals are accomplished solely by precise glass-on-glass fit!

Pokáčovo Kanál : <https://www.youtube.com/watch?v=73txXT21aZU>



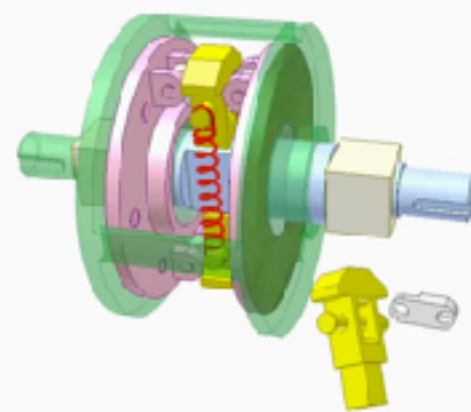
Friction clutch I



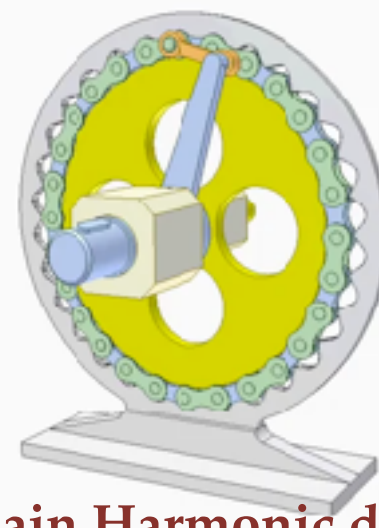
Multi-shaft driller



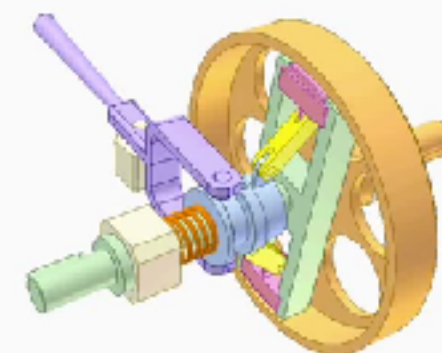
Belt & Gear drive



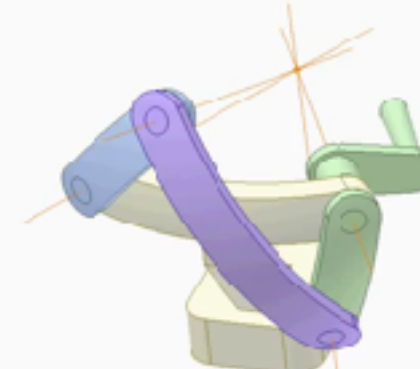
Centrifugal Clutch



Chain Harmonic drive



Friction clutch II



Spherical 4 bar

Function and Advantages

Force, Motion and/or Energy Transfer

Function, Path and Motion Generation

Repeatability



Dr. Nguyen Duc Thang

Hanoi, Vietnam

1946-2002 (RETIRED)

Compliant Mechanisms (ME 851)

Anupam Saxena

Professor

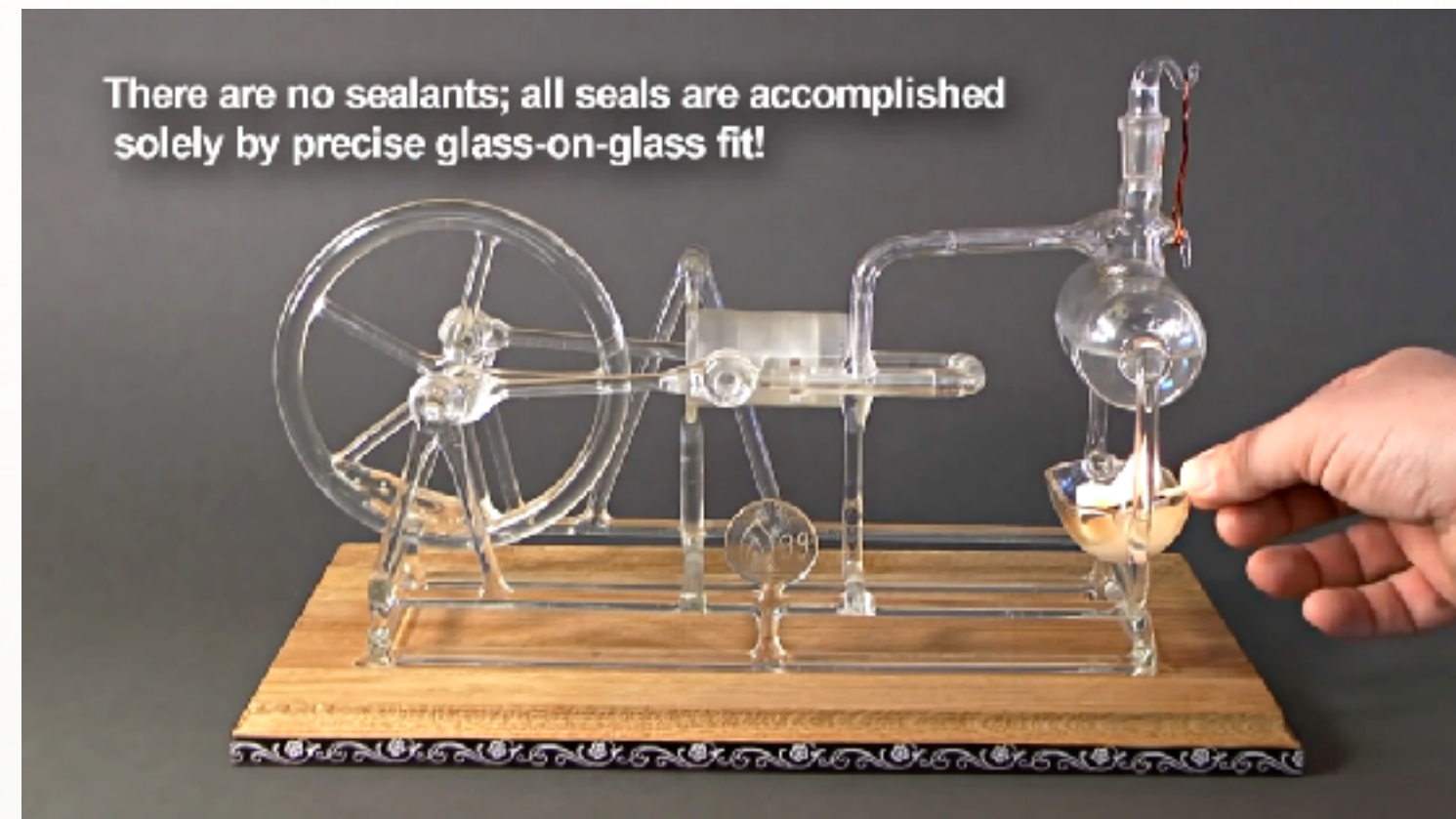
Indian Institute of Technology Kanpur

Mechanisms: Designed, Existed and Developed over CENTURIES

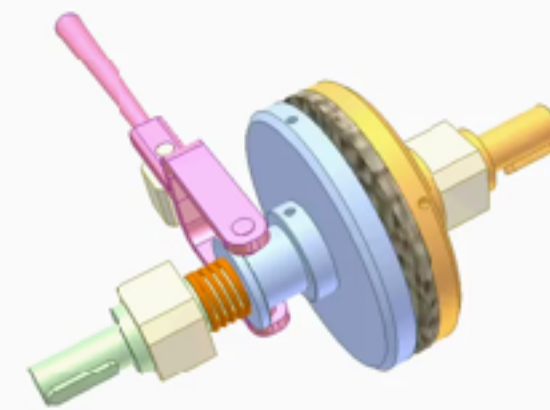
Libraries and cool Animations available

Stephenson's STEAM ENGINE

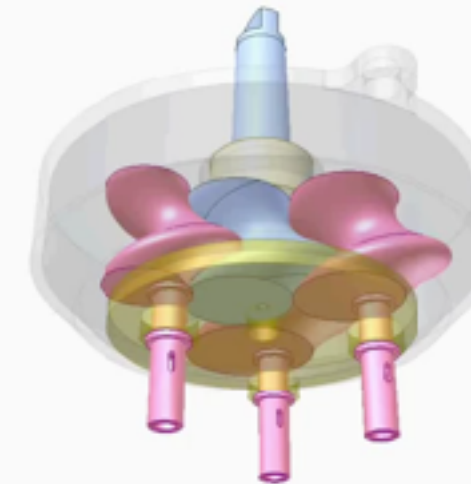
1700 ANIMATED MECHANICAL MECHANISMS



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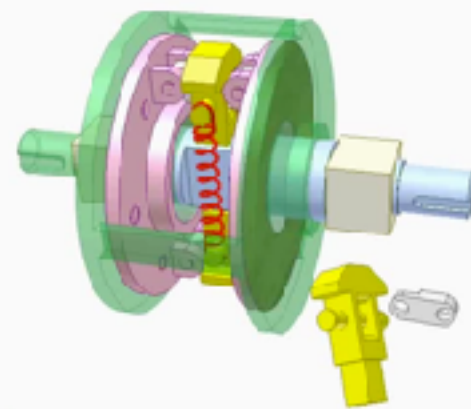
Friction clutch I



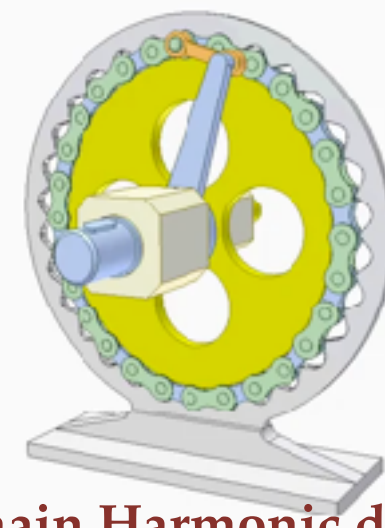
Multi-shaft driller



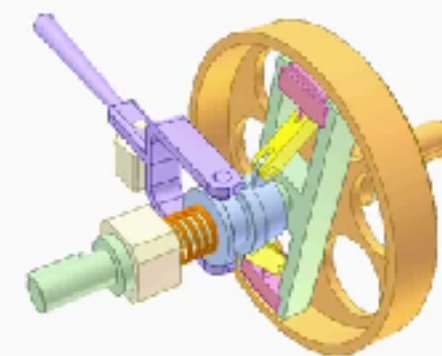
Belt & Gear drive



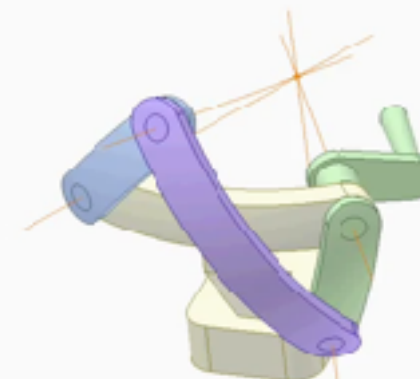
Centrifugal Clutch



Chain Harmonic drive



Friction clutch II



Spherical 4 bar

Function and Advantages

- Force, Motion and/or Energy Transfer
- Function, Path and Motion Generation
- Repeatability

Disadvantages

- Friction
- Wear and Tear
- Lubrication
- Vibrations
- Noise
- Need for Assembly
- Backlash (play)

Compliant Mechanisms (ME 851)

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Professor

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<https://engineering.purdue.edu/ME/Seminars/2021/compliant-mechanisms-memory-lane-and-some-novel-and-exciting-applications/amidha.PNG>

Prof. Ashok Midha

A (my) Little Story

Masters student at UT 1995-97



<https://www.utoledo.edu/engineering/mechanical-industrial-manufacturing-engineering/people/kramer.html>

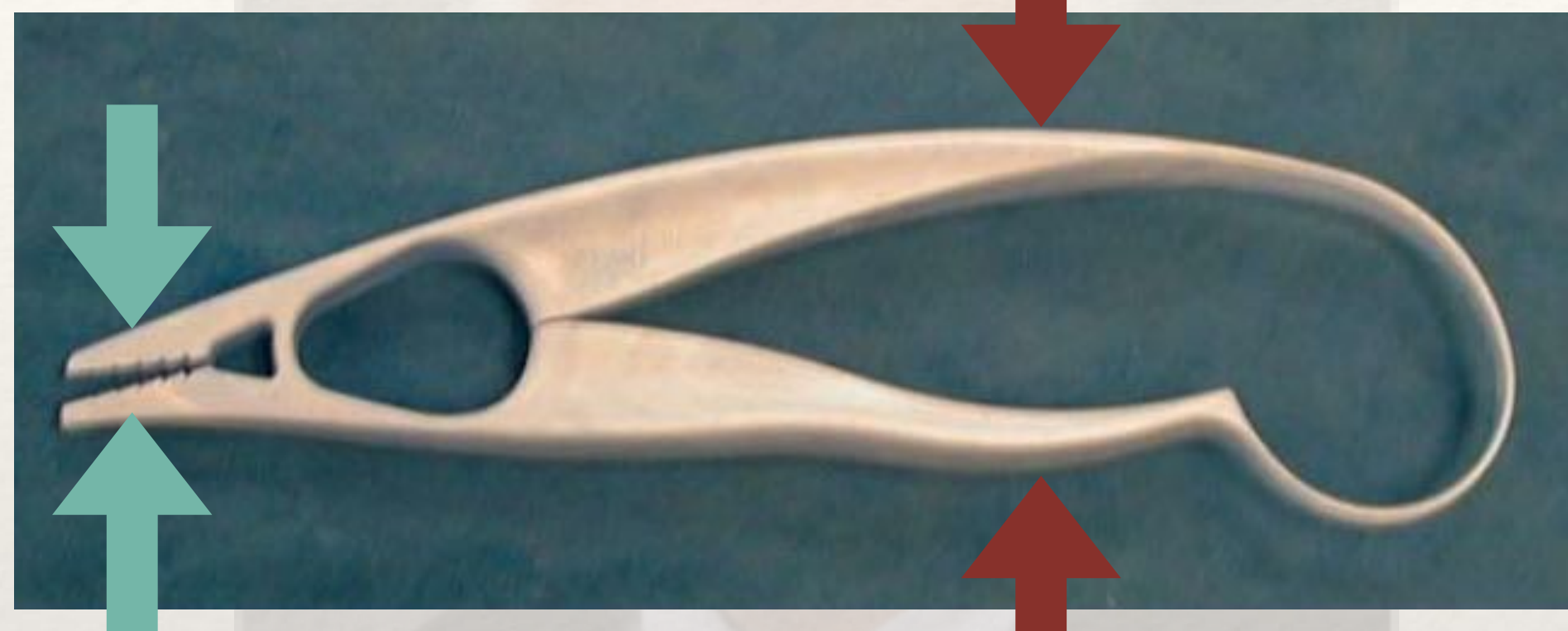
Fall of 1996

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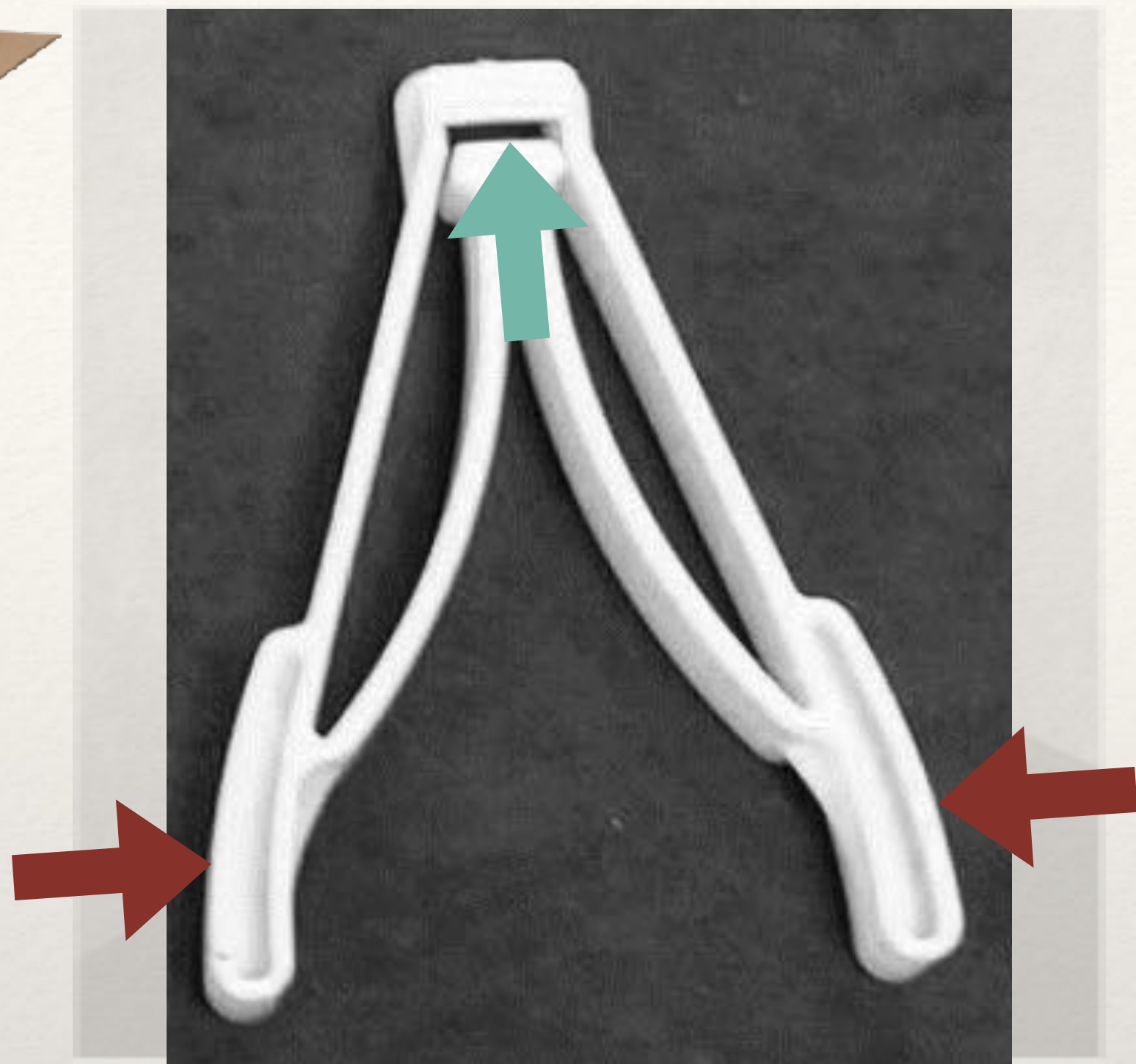
Fall of 1996

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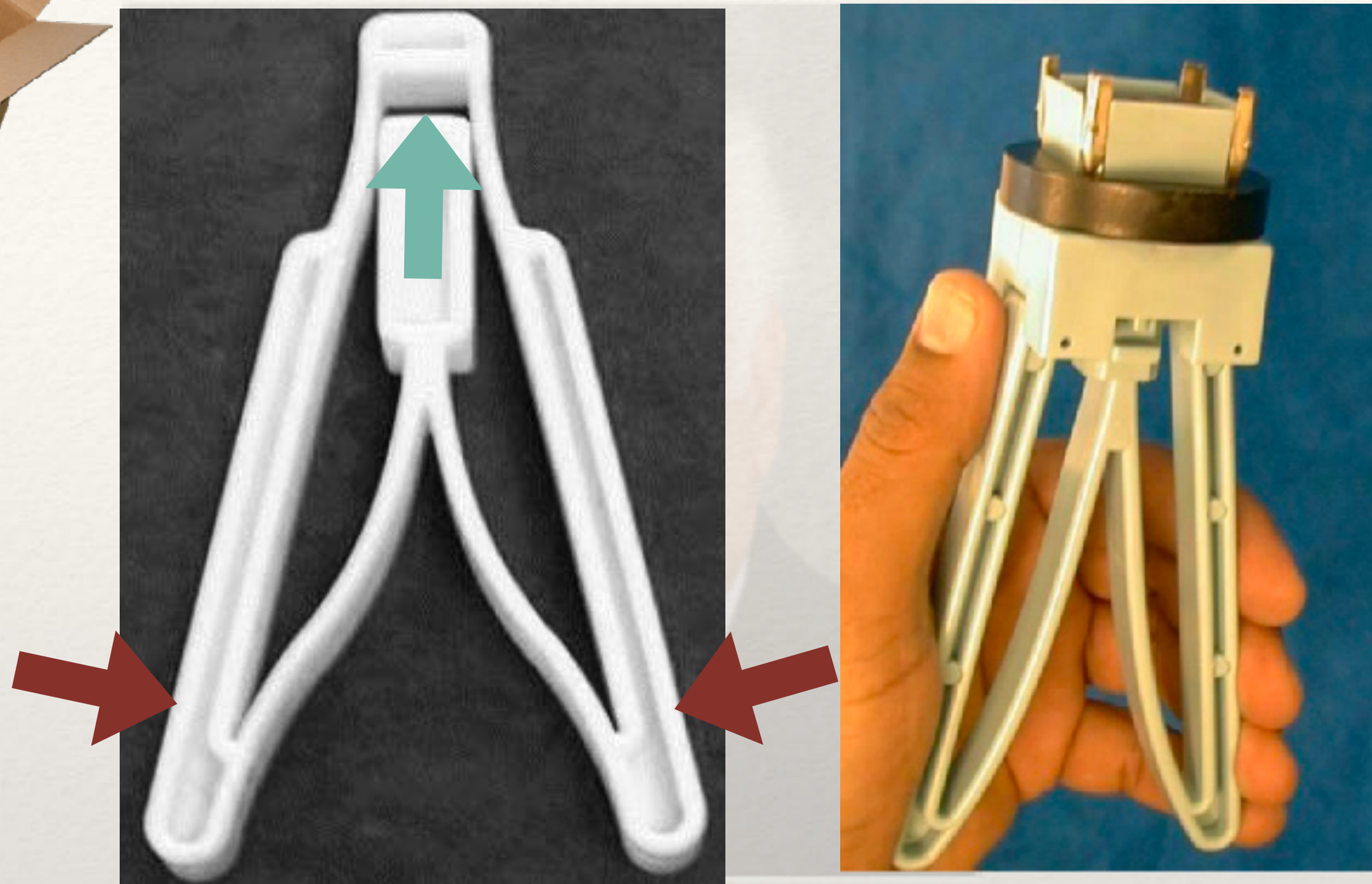
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AMP Chip Carrier Extractor



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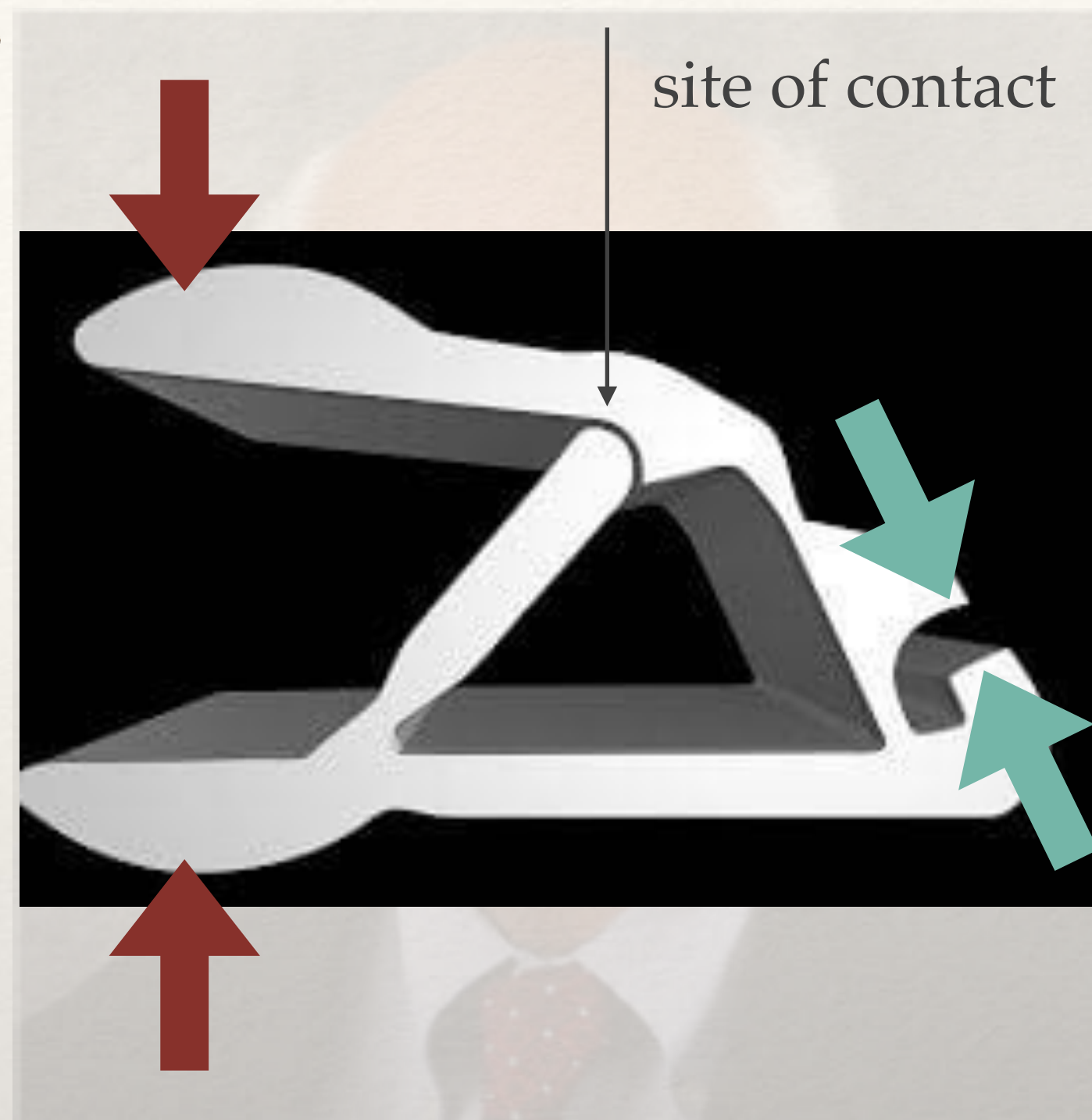
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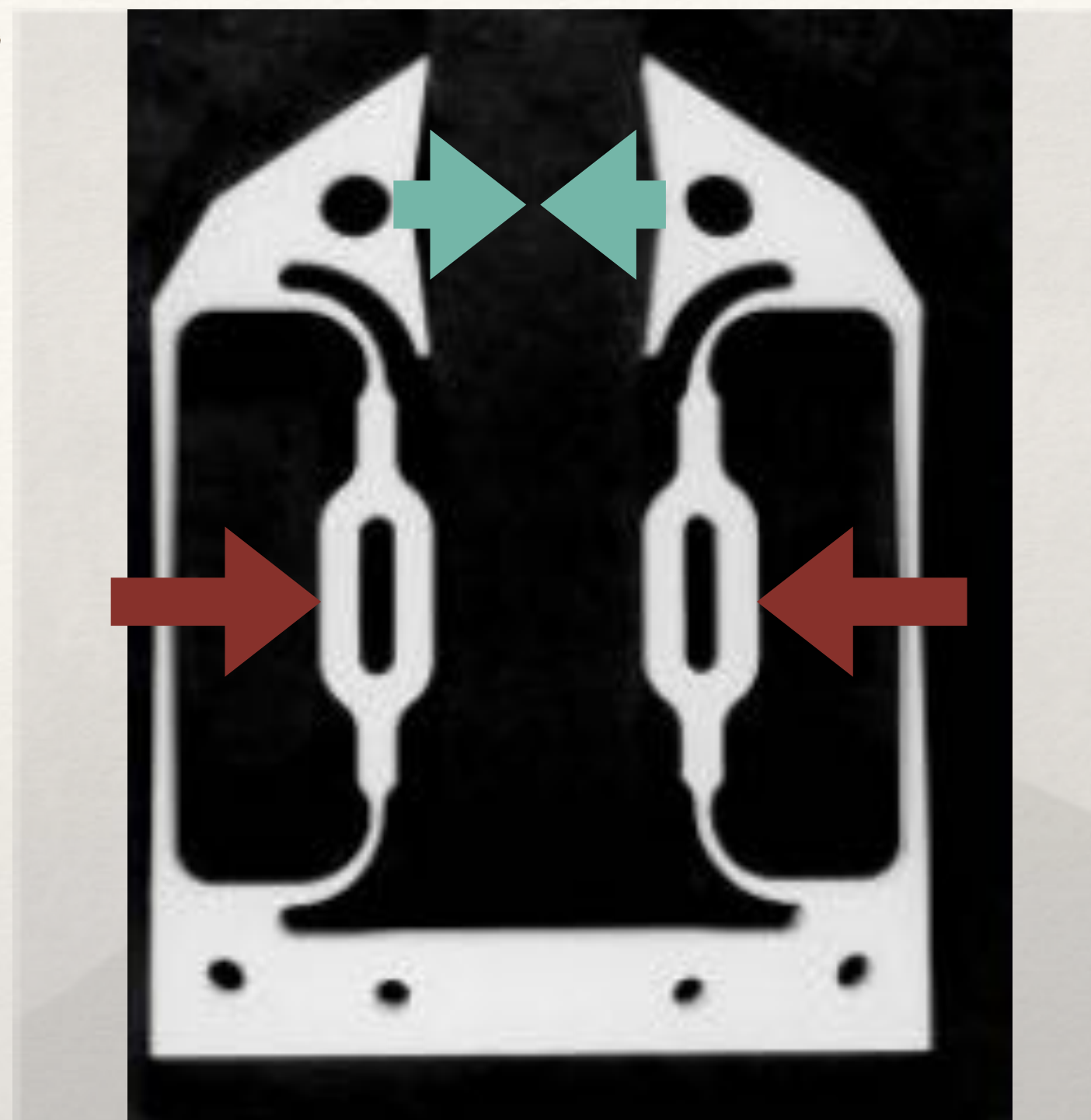
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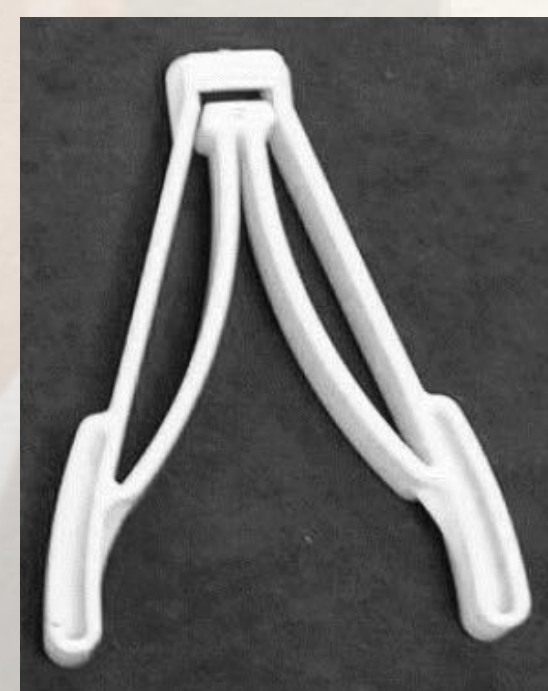
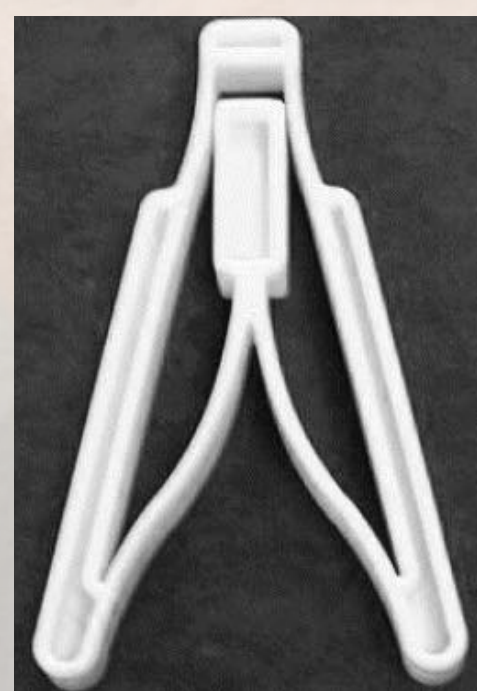
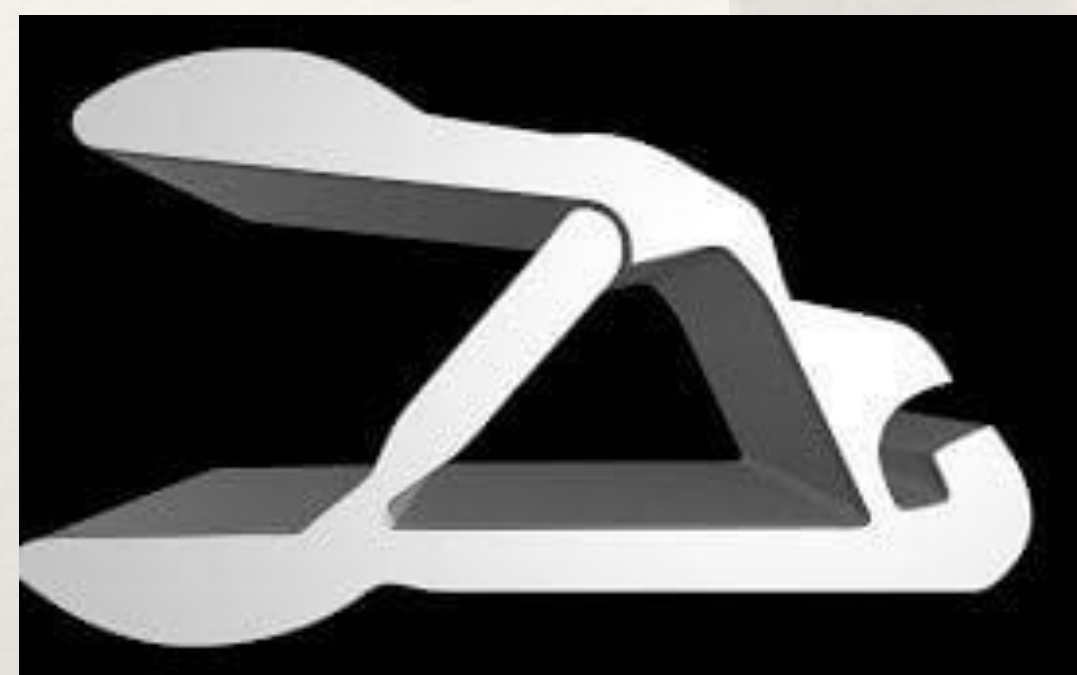
Fall of 1996

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Mechanical Elements

~~Hinges?~~ ~~Sliders?~~

~~Belt-pulley?~~ ~~Chain-sprocket?~~

~~Gears?~~

What are these then?

Monolithic (Single-piece) Devices

Force, Motion, Energy Transfer

While performing desired

function, path, motion generation

Through purely

(Large) *elastic deformation*

Compliant Mechanisms (ME 851)

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Professor

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Compliant Mechanisms



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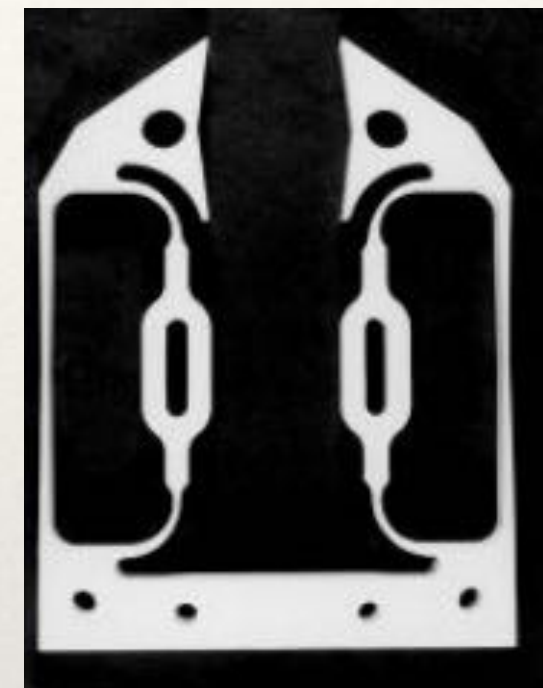
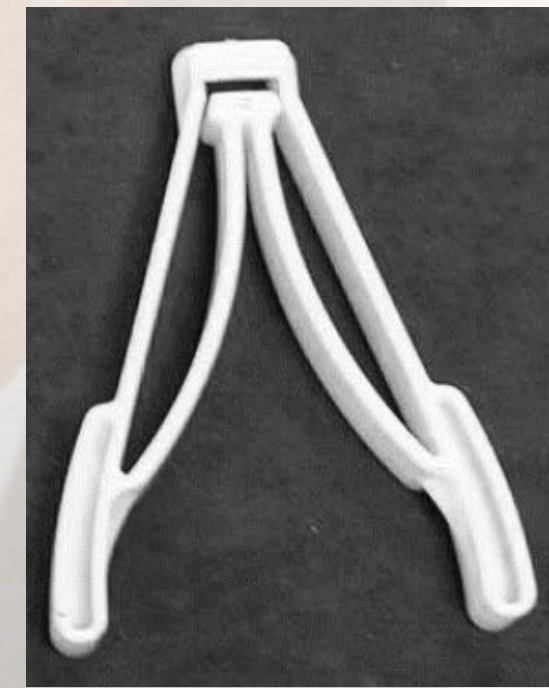
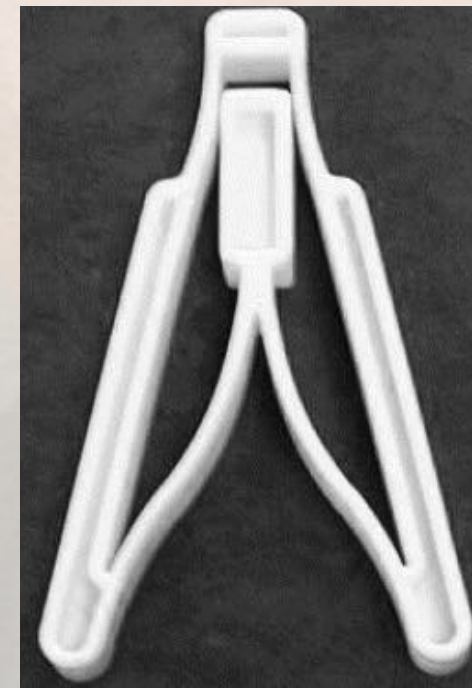
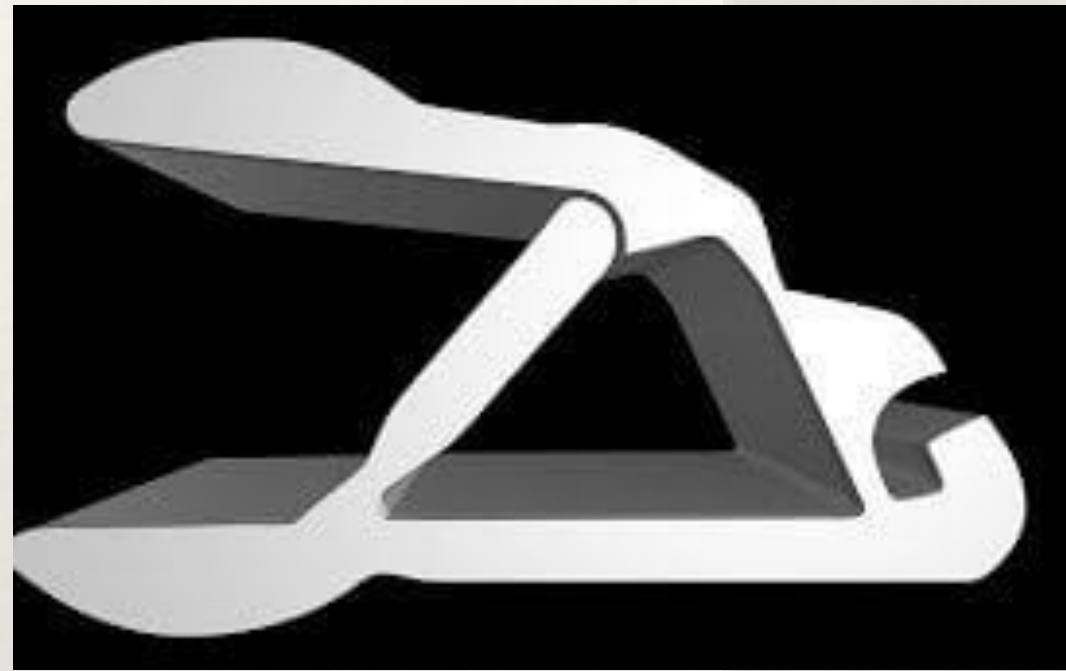
(Large) *elastic deformation*

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Function and Advantages

Force, Motion and/or Energy Transfer
Function, Path and Motion Generation
Repeatability

Disadvantages (Would we now witness)

~~Friction~~

~~Wear and Tear~~

~~Lubrication~~

~~Vibrations~~

~~Noise~~

~~Need for Assembly~~

~~Backlash (play)~~

Compliant Mechanisms (ME 851)

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Professor

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A (my) Little Story

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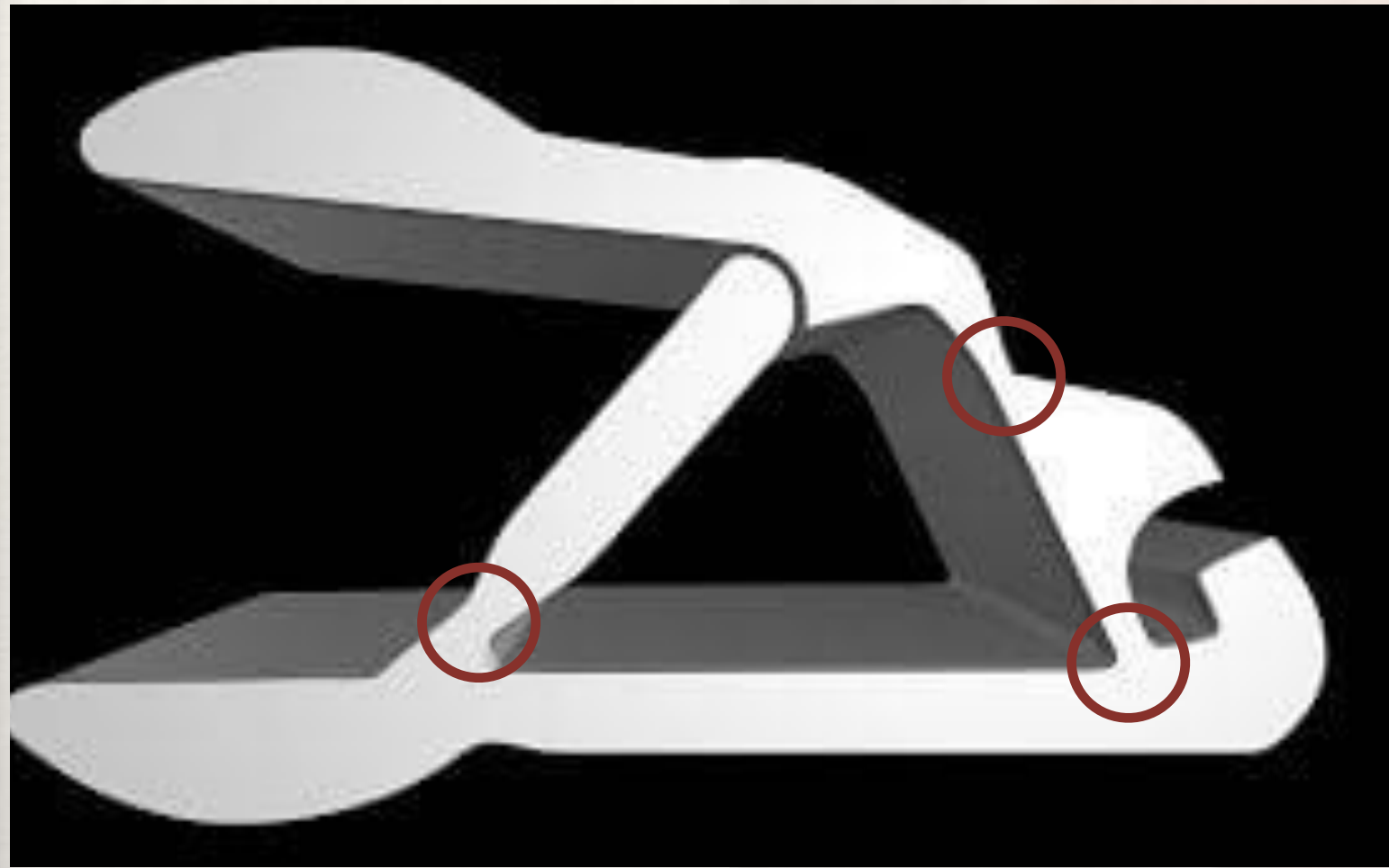
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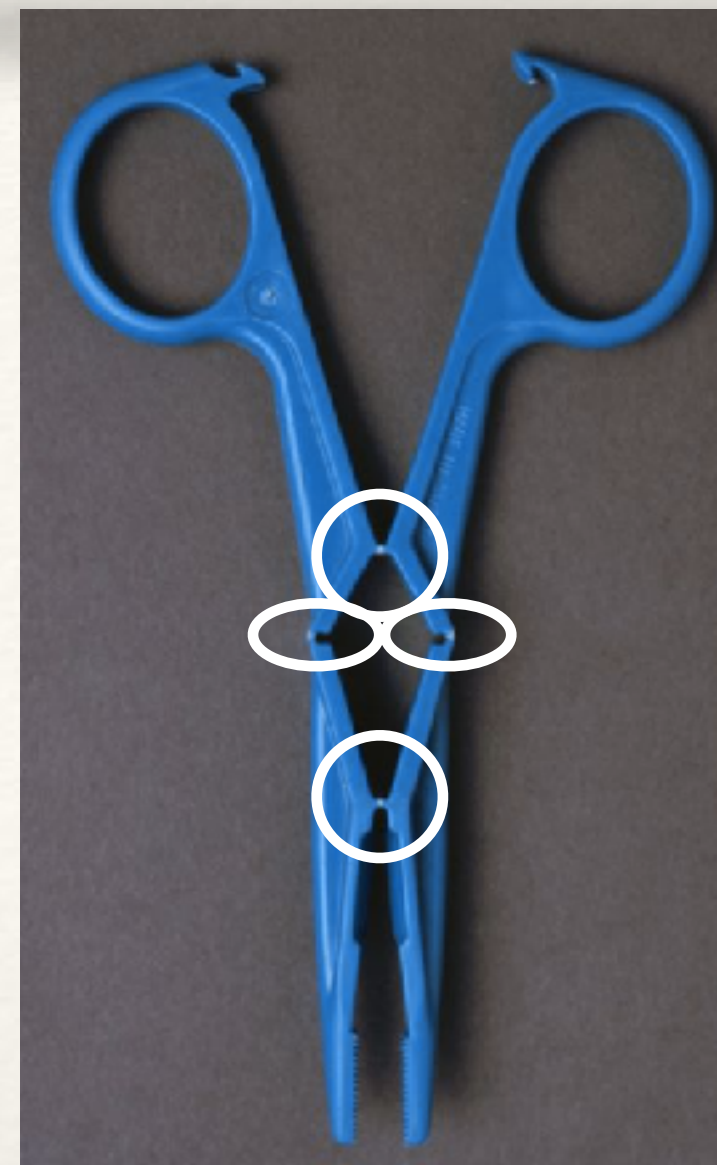
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<https://engineering.purdue.edu/ME/Seminars/2021/compliant-mechanisms-memory-lane-and-some-novel-and-exciting-applications/amidha.PNG>

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Flexibility is concentrated

FLEXURES

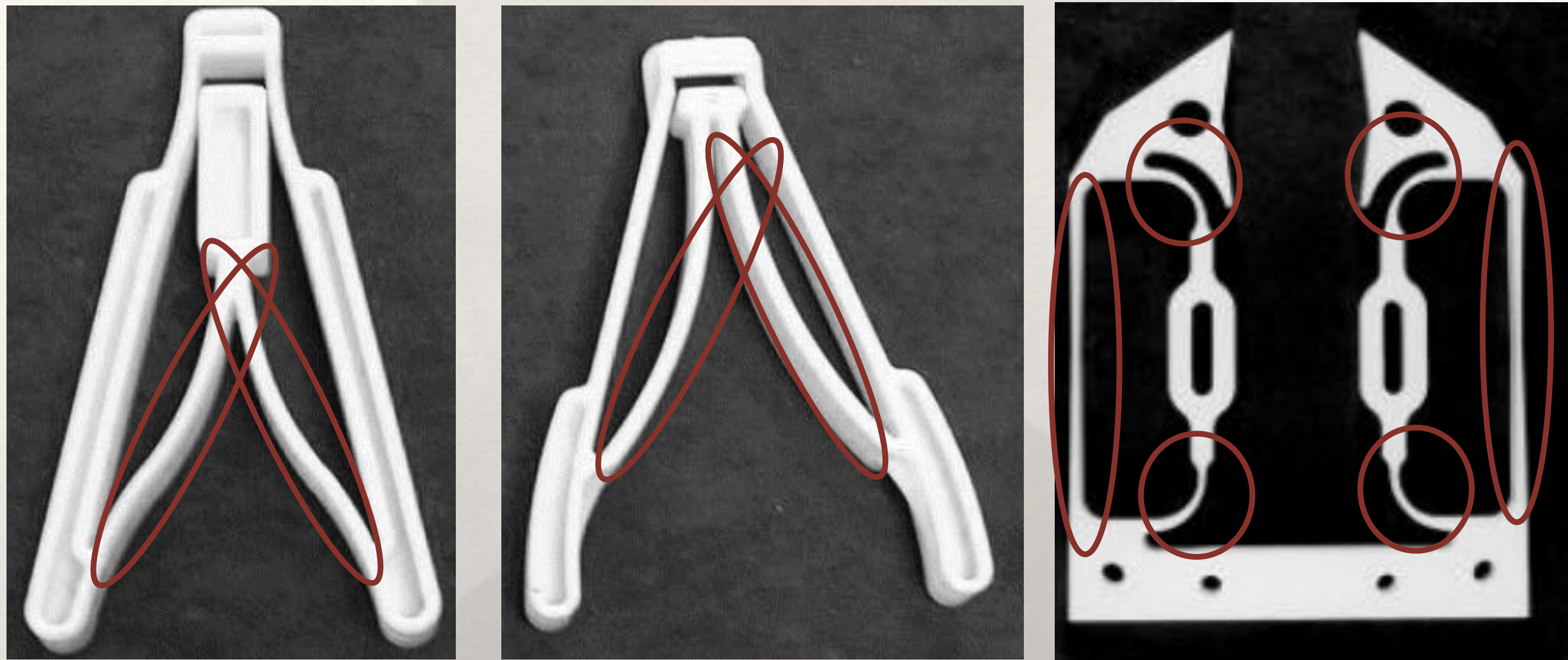
LUMPED

COMPLIANT MECHANISMS

Compliant Mechanisms (ME 851)

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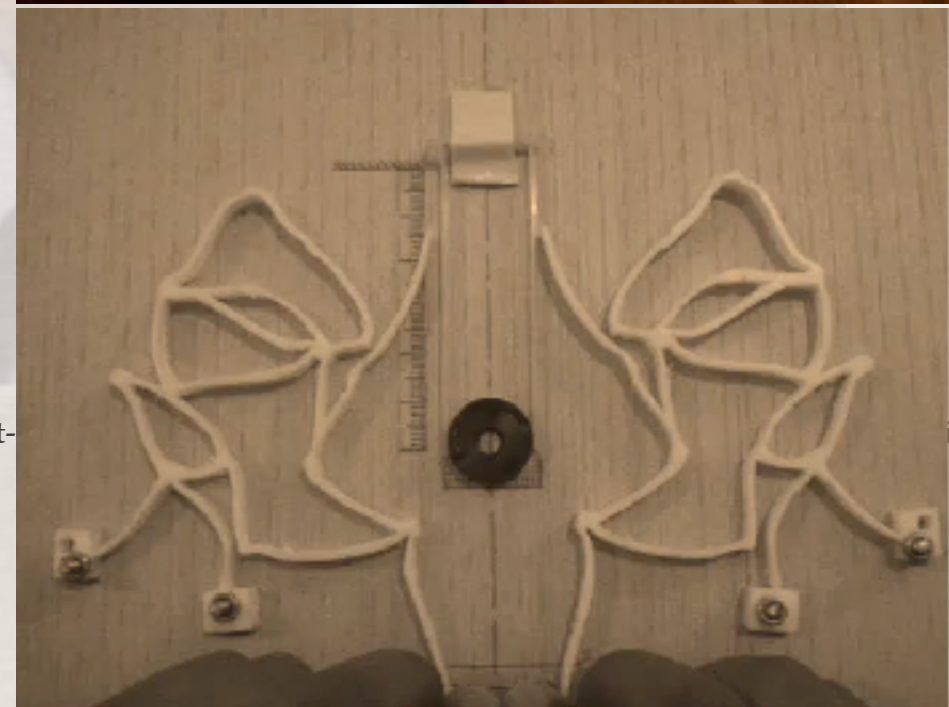
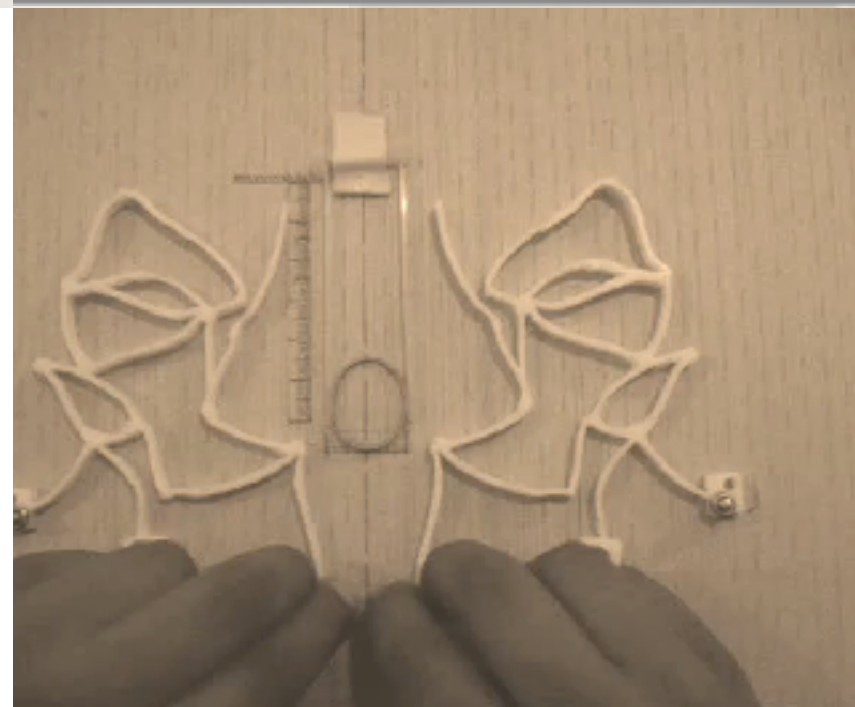
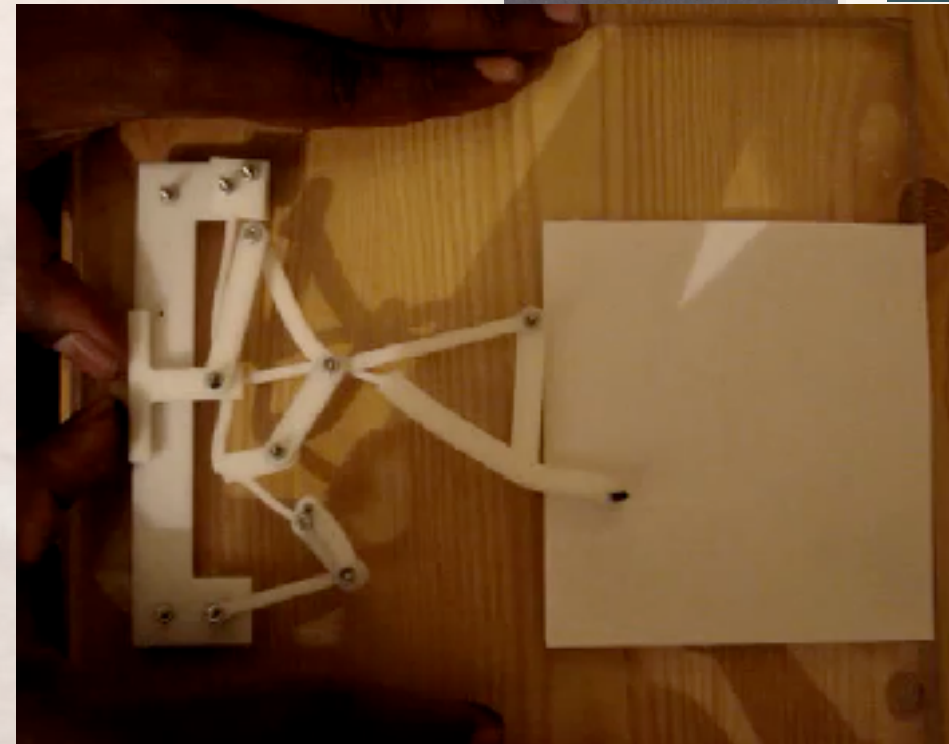
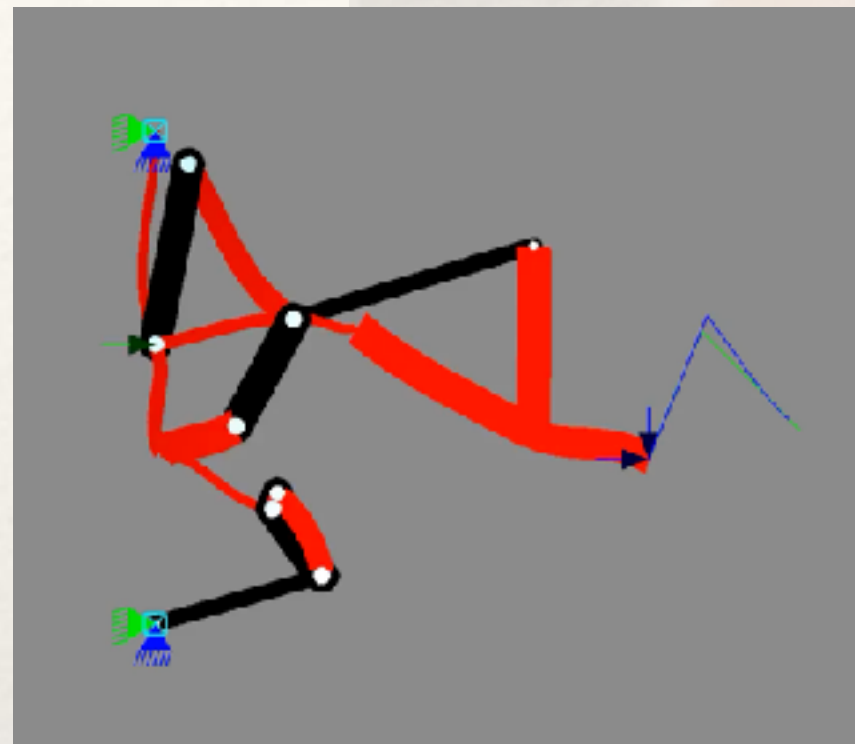
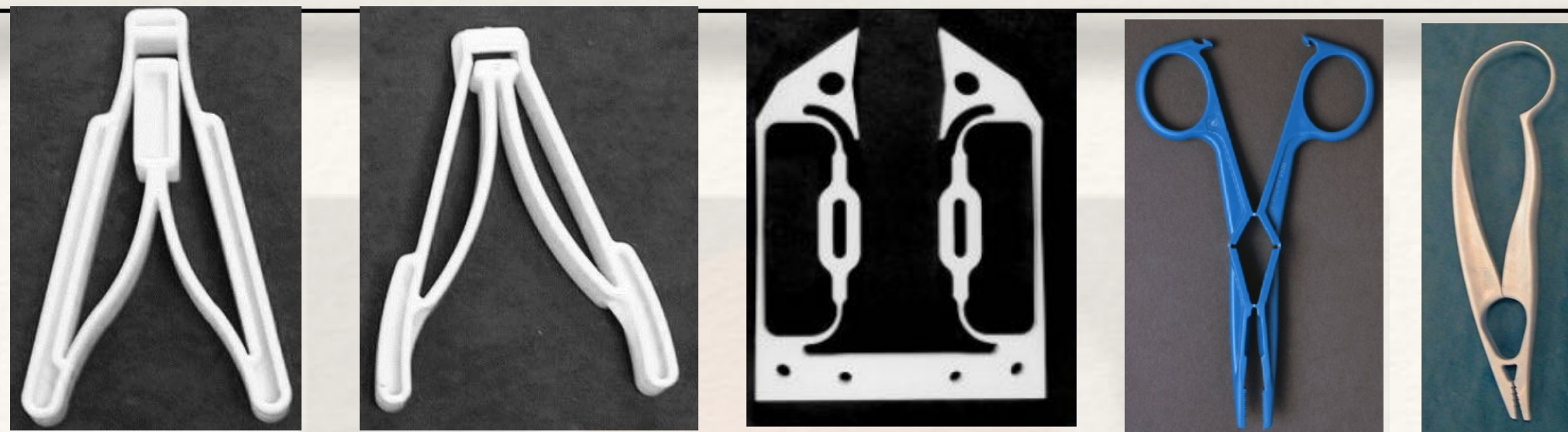
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Flexibility is Distributed

**DISTRIBUTED
COMPLIANT MECHANISMS**

Compliant Mechanisms (ME 851)

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ons/amidha.PNG

Midha

FULLY COMPLIANT MECHANISMS

No rigid-body joints

ALL Members undergo elastic deformation

PARTIALLY COMPLIANT MECHANISMS

SOME rigid-body joints

SOME Members undergo elastic deformation

CONTACT-AIDED COMPLIANT MECHANISMS

No rigid-body joints

ALL Members undergo elastic deformation

Pseudo joints at contact sites

Compliant Mechanisms (ME 851)

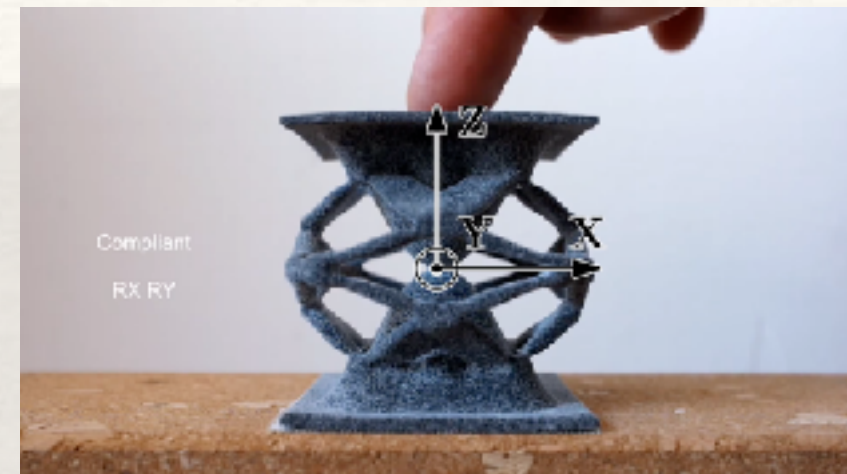
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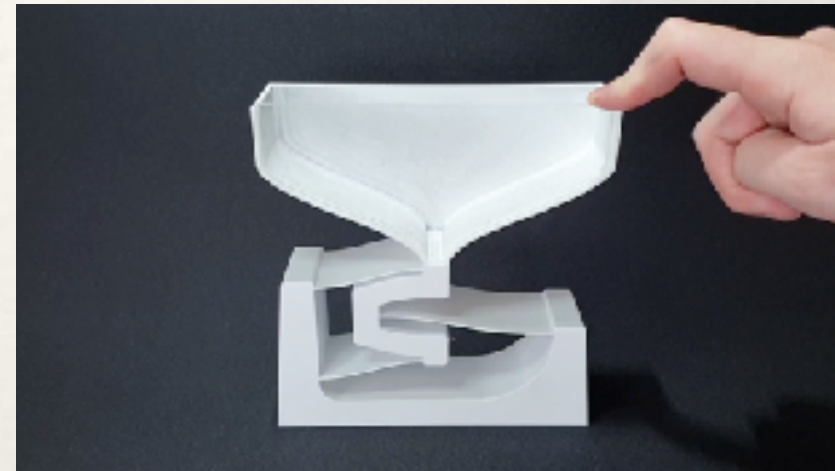
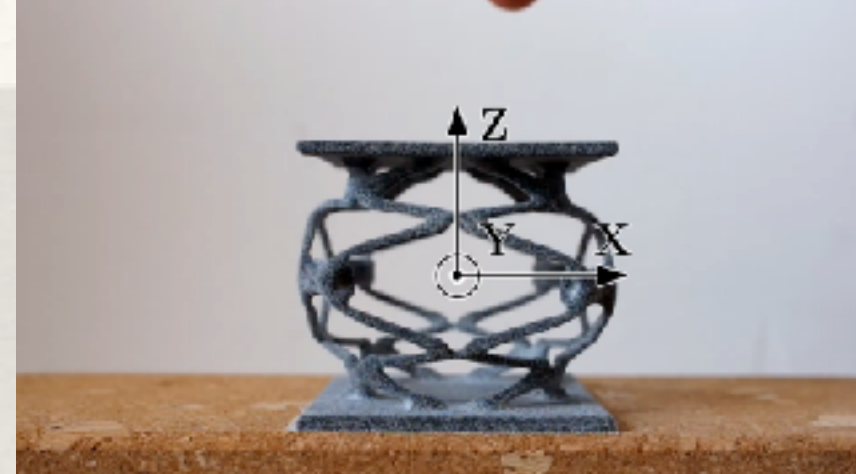
(MANY) Youtube videos



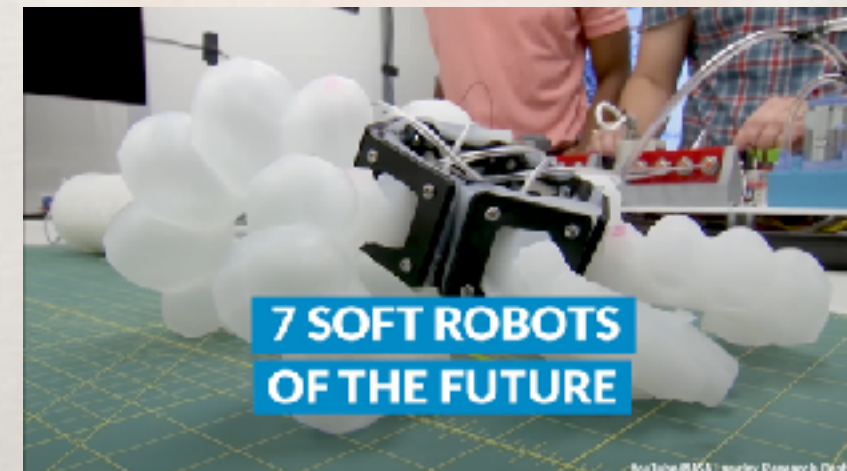
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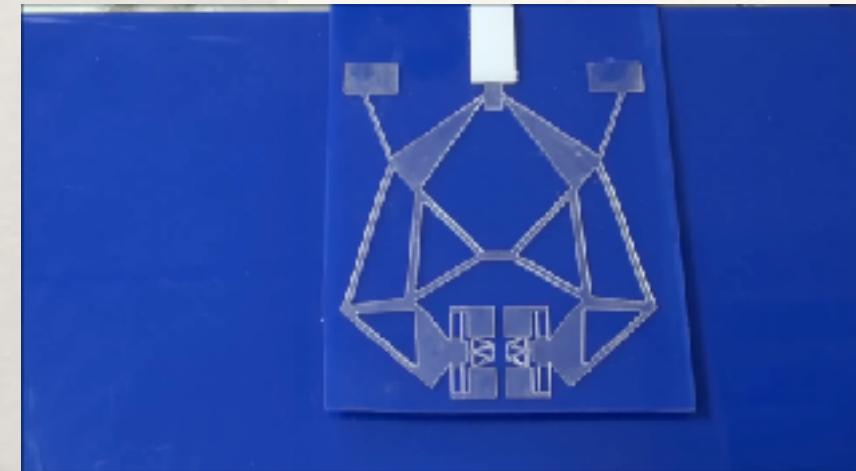
<https://www.youtube.com/watch?v=jHqkL6dLo2M>



<https://www.youtube.com/watch?v=r6kGVtMbHg>



<https://www.youtube.com/watch?v=ifLvpXMuos8>



<https://www.youtube.com/watch?v=K-vw1-a3UUM>



<https://www.youtube.com/watch?v=C-SbMsYNTxM>



https://www.youtube.com/watch?v=T5wnomW_CJE

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(MANY) MORE out there!

APPLICATIONS ...

Aerospace/Automotive

Sensing, Actuation, Grasp, Manipulation

Biomedical/Healthcare

Orthotic/Prosthetic devices

Robotics

Soft/Medical

Miniature Scales

Micro/Nano Electro Mechanical Systems

Space

Foldable/Deployable mechanisms

Product Design

Special Purpose Mechanisms

Statically balanced mechanisms

Bistability

Constant I/O force mechanisms

Compliant Mechanisms (ME 851)

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Professor

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HOW DO WE CONCEIVE (DESIGN) COMPLIANT MECHANISMS

Intuition / Experience
based

FACT
(Freedom And
Constraint Topologies)

Rigid-body replacement
(PRBM)

Building Block
Approach

Specific Synthesis
Approaches

(Large Deformation)
Structural Optimization

References: Personal Notes

WEB Course: Prof. G. K. Ananthasuresh: **Compliant Mechanisms:
Principles and Design**

<https://archive.nptel.ac.in/noc/courses/noc18/SEM1/noc18-me22/>



Great Deal of Web material

Compliant Mechanisms (ME 851)

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TENTATIVE OUTLINE

L2: Generic Design Philosophy: Is concurrent design process sustainable?

L3-L4: Understanding kinematics, kinetics, kinetostatics, dynamics... R-B and C

L5: Flexures — Lumped Compliance

L6-L7: Nonlinear FEM — introduction: trusses with torsional springs — K & K

L8-L14: Pseudo-Rigid-Body-Models (lumped and distributed compliance)

L8-L10: Incentive, 4 bar, function, path, motion generation

L9-L14: Models for various beams, loading and boundary conditions

L5-L22: Structural Optimization: beams, four-nodes, hexes, small deformation, large deformation

APPLICATIONS ...

Aerospace/Automotive

Sensing, Actuation, Grasp, Manipulation

Biomedical/Healthcare

Orthotic/Prosthetic devices

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Miniature Scales

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