

A Highly Scalable High Voltage MOSFET Model

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Outline

- Motivation – why new HV MOSFET Model
- Device Architecture and Modeling Strategy
 - Core – Low Voltage EKV MOSFET Model
 - Analytical bias dependent drift resistance
 - Strategy for charge evaluation based on V_K
- Validation and Results
 - Most of the results on VDMOS
 - Some results on LDMOS
- Conclusion

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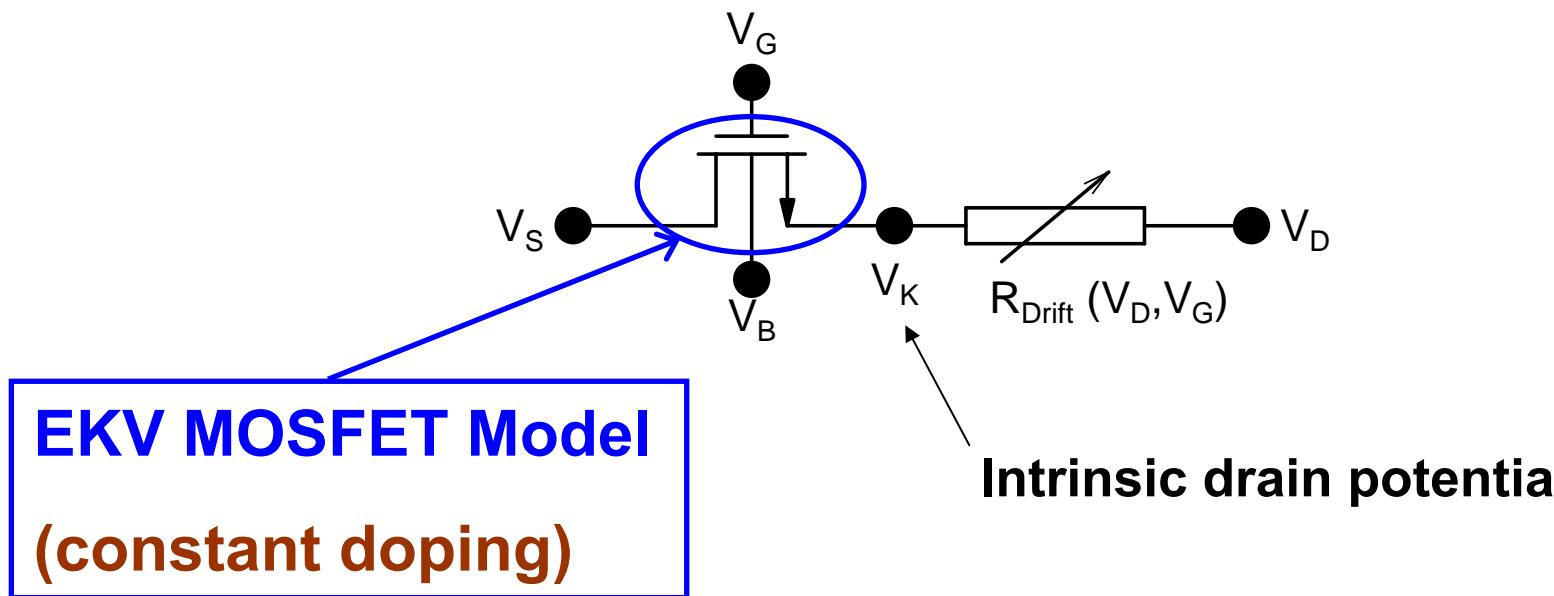
Motivation

- Robust HV Model for circuit simulators
- Analytical & Physical Compact Model
- Accuracy in DC & AC
- Small number of parameters: EKV!
- Scaling with physical & electrical parameters
- Convergence and Speed
- Open Source
- **General HV-MOS Model?**

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General HV MOSFET Modeling Strategy

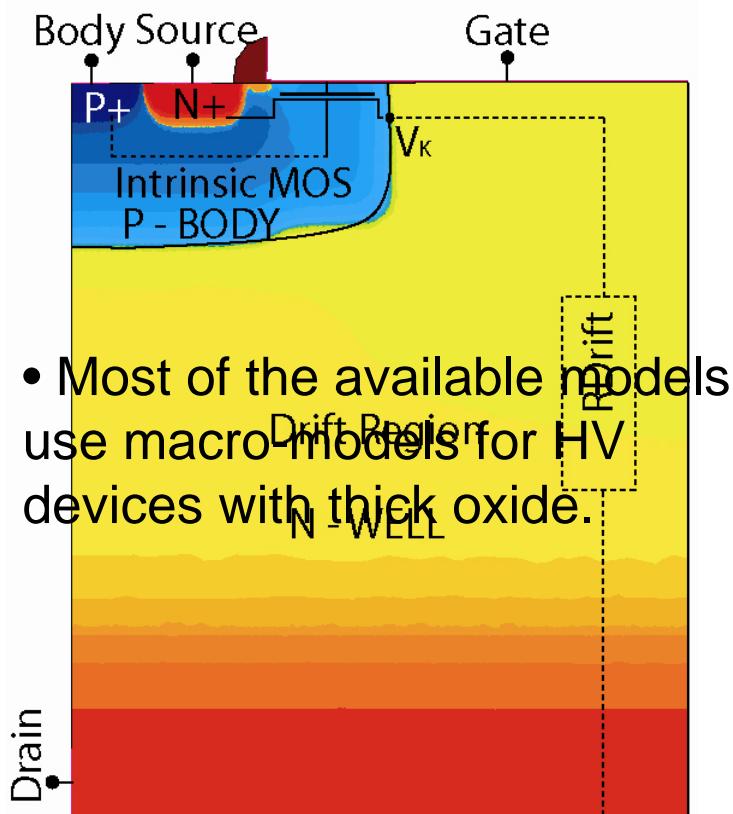


- EKV Model
 - Physically based parameters
 - Less parameters than BSIM

Device Architectures

- **VDMOS :**

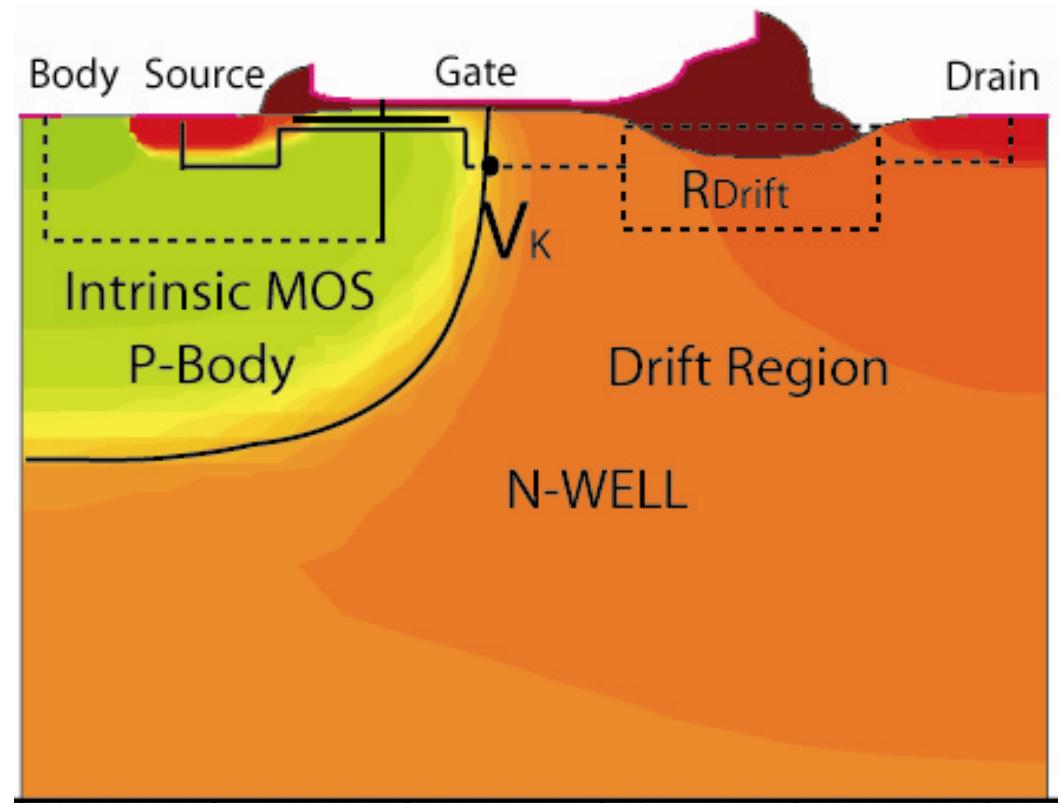
$$V_{Dmax} = 50V, V_{Gmax} = 3.3V$$



- Most of the available models use macro models for HV devices with thick oxide.

- **LDMOS :**

$$V_{Dmax} = 40-100V, V_{Gmax} = 13V$$



Main EKV Parameters

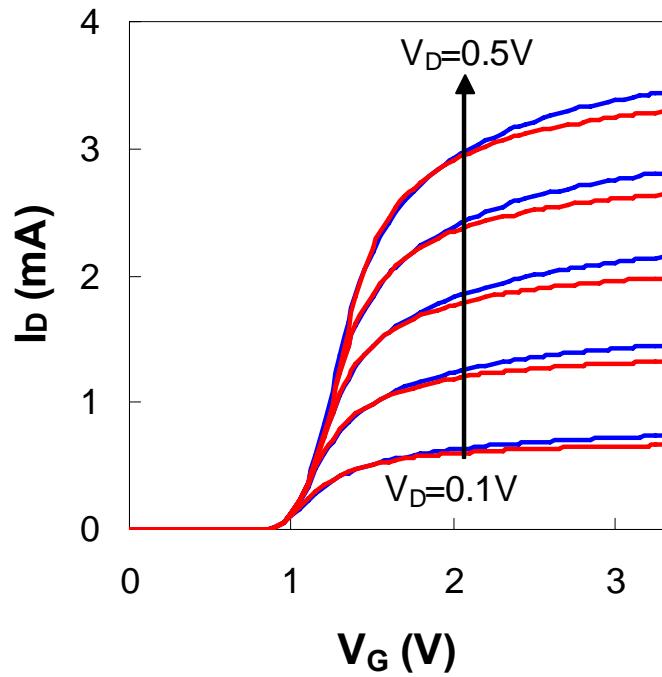
Name	Description	Units
W	Channel Width	m
L	Channel Length	m
COX	Oxide Cap. per unit area	F/m ²
VT0	Long-channel Threshold Voltage	V
U0	Low Field mobility	cm ² /Vs
GAMMA	Body Effect Parameter	V ^{1/2}
PHI	Bulk Fermi Potential	V
E0	Mobility Reduction Coefficient	V/m
UCRIT	Longitudinal Critical Field	V/m
LAMBDA	Channel Length Modulation	-

Modeling Strategy

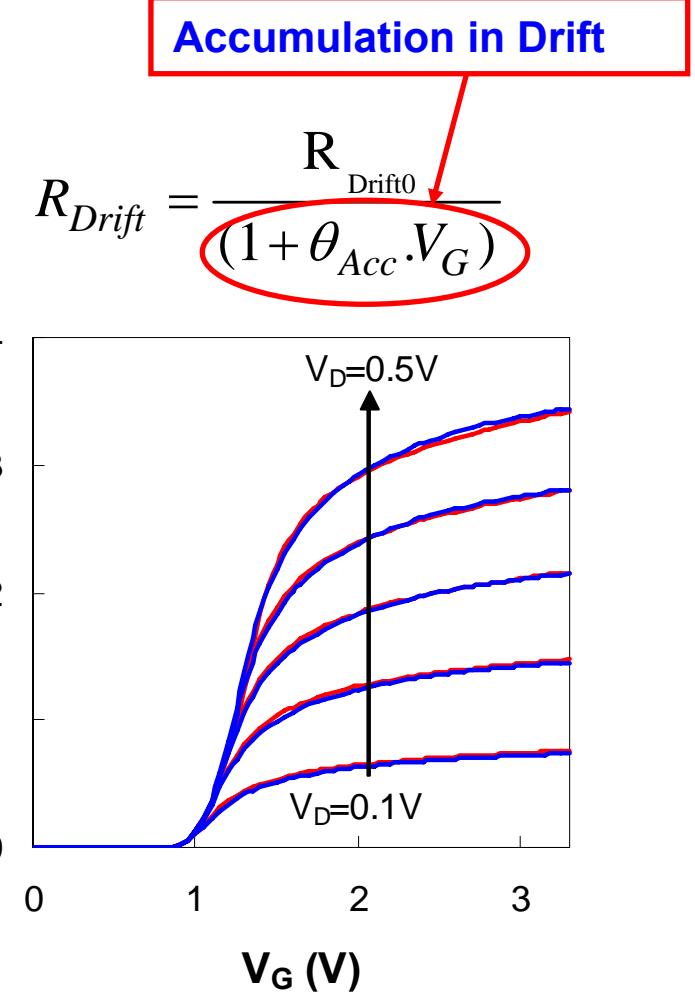
- Drift Resistance expression

Why not?

$$R_{Drift} = R = \text{constant}$$



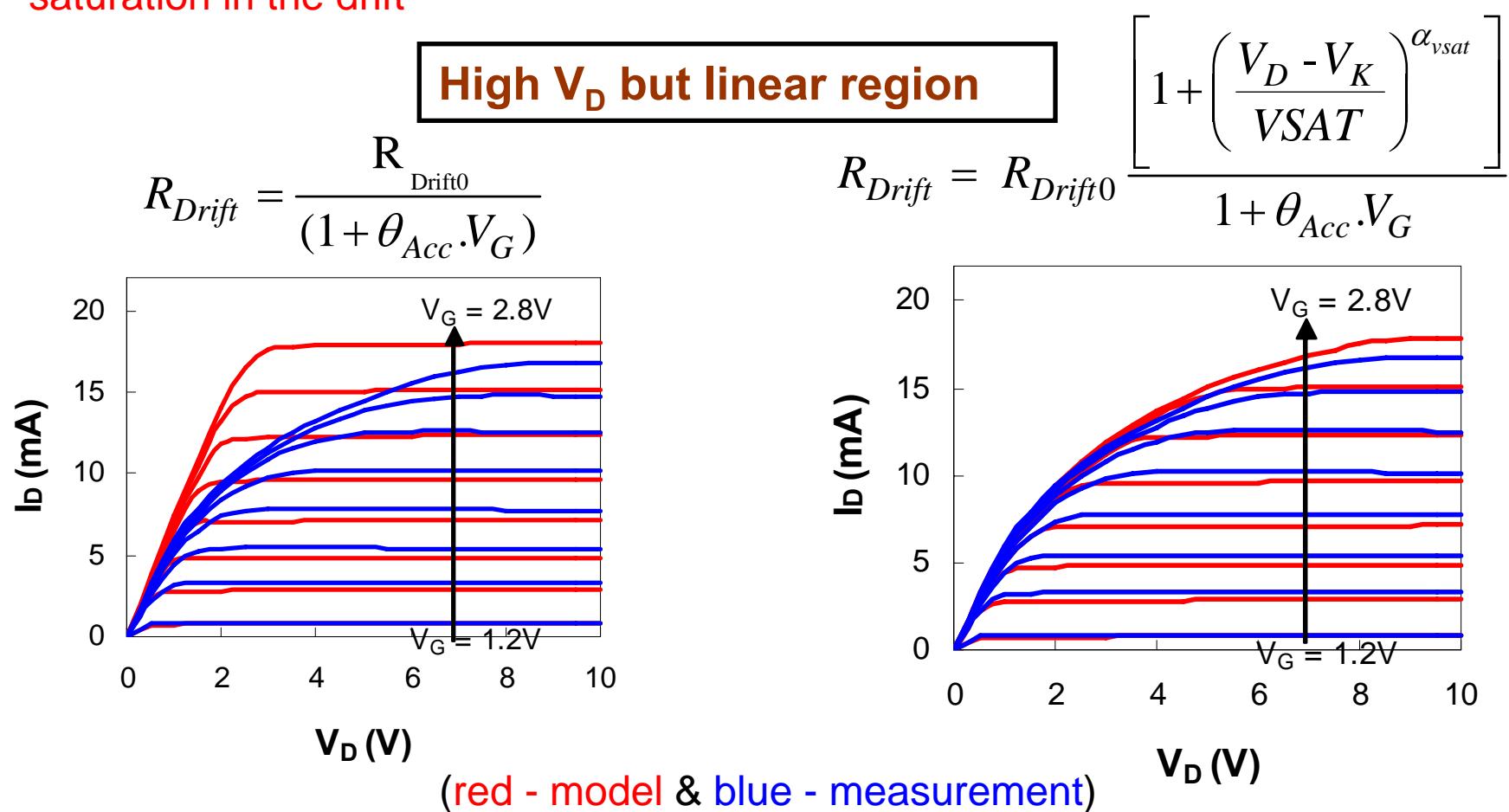
Low V_D



(red - model & blue - measurement)

Modeling Strategy

- Drift part mainly affects the linear region of the output characteristics.
- Delayed transition between linear and saturation regime at high V_G - **velocity saturation in the drift**



Scalable Drift Resistance

+ : Drain-on-sides
- : Drain all-around

$$R_{Drift} = R_{Drift0} \frac{\left[1 + \left(\frac{V_D - V_K}{VSAT} \right)^{\alpha_{vsat}} \right]}{(1 + \theta_{Acc} V_G)} \left(1 \pm (k_{rd} - 1) \frac{N_F - 1}{N_F + N_{CRIT}} \right) (1 + \alpha_T \cdot \Delta T)$$

Effect of Temperature

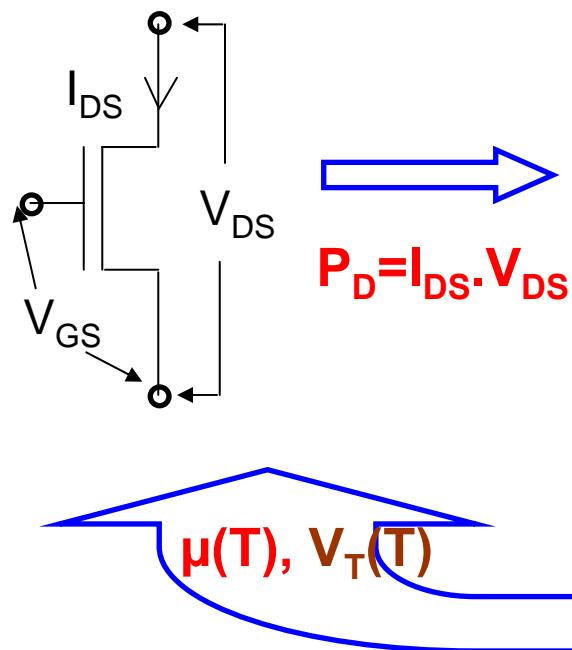
$$R_{Drift0} = \rho_{Drift0} \left(\frac{L_{DR}}{N_F (W + \Delta W)} \right)$$

Number of Fingers

Drift Length

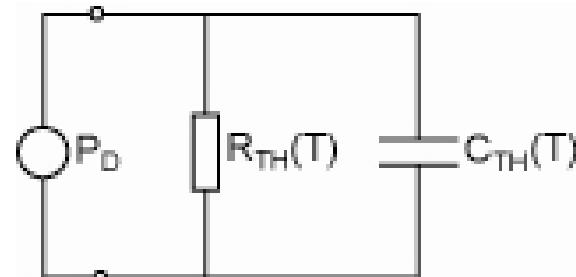
Width and Width Offset

Modeling of Self Heating Effect



R_{th} – Thermal Resistance

C_{th} – Thermal Capacitance



$$\Delta T$$

- External Temperature Node

Ref: C. Anghel et al., "Self-heating characterization and extraction method for thermal resistance and capacitance in HV MOSFETs", IEEE Electron Device Lett., 141 - 143, 2004

AC Modeling

- Charges in MOSFET and Drift region

$$Q_G = Q_{EKV} + Q_{Drift} = Q_S + Q_K + Q_B + Q_{Drift}$$

$$Q_{Drift} = (V_G - V_{FB} - \psi_s) \cdot W \cdot L_{DR} \cdot C_{ox}$$

Assumptions

- ψ_s varies linearly across accumulation charge sheet

AC Modeling

V_K behavior

- As mentioned earlier, Drift does not affect the transistor characteristics in saturation.
- V_K obtained from Spice is valid for linear region. Many models use interpolation function for smooth V_K from linear to saturation.

Normalized reverse Current

$$i_r = \left[\ln\left(1 + e^{\frac{v_p - v_k}{2}}\right) \right]^2$$

Normalized charge density at V_K (EKV)

$$q_k = \sqrt{i_r + 0.25} - 0.5$$

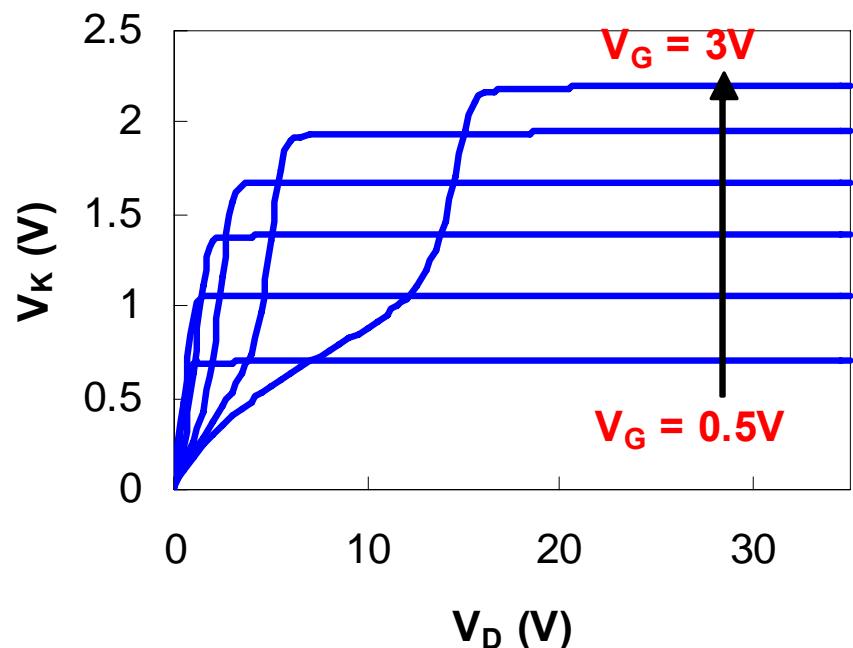
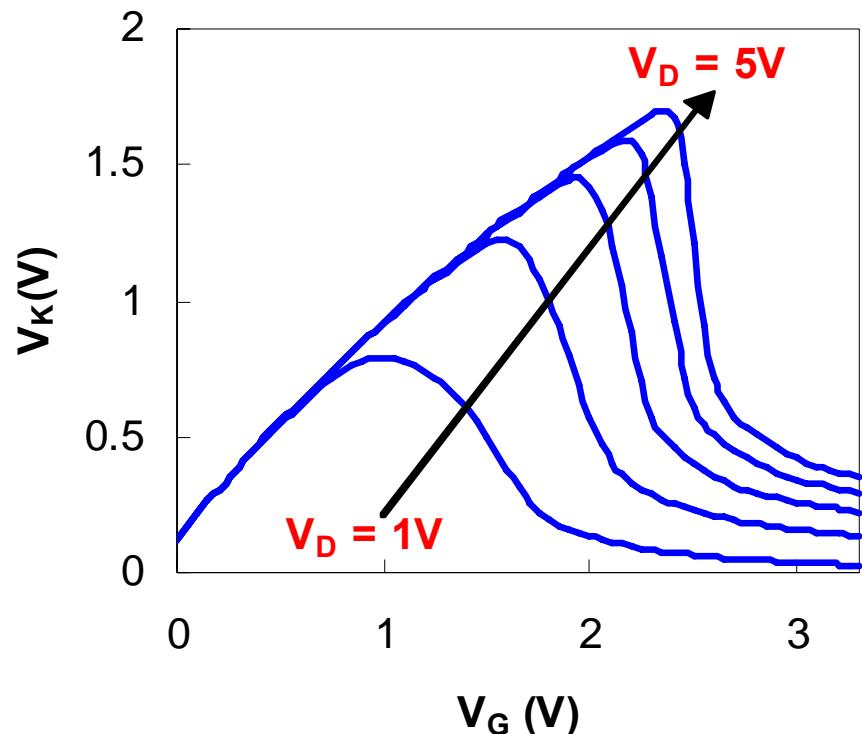
Normalized v_k (EKV)

$$v_k = \frac{V_K}{U_T} = v_p - (2 \cdot q_k + \ln(q_k))$$

Ref: J.-M. Sallese et al., "Inversion charge linearization in MOSFET modeling and rigorous derivation of the EKV compact model", Solid-State Electronics, pp. 677-683, 2003

V_K vs. V_G and V_D for VDMOS

- V_K – Important parameter for design of HV-MOS



- Trend matches with device simulation and also reported with literature

Ref: C.H. Kreuzer et al., "Physically based description of quasi-saturation region of vertical DMOS power transistors", IEDM, pp. 489 - 492, 1996

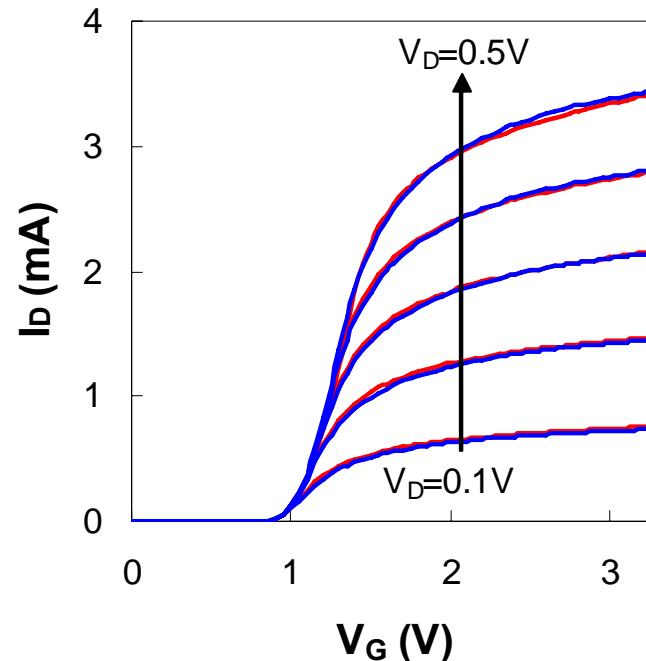
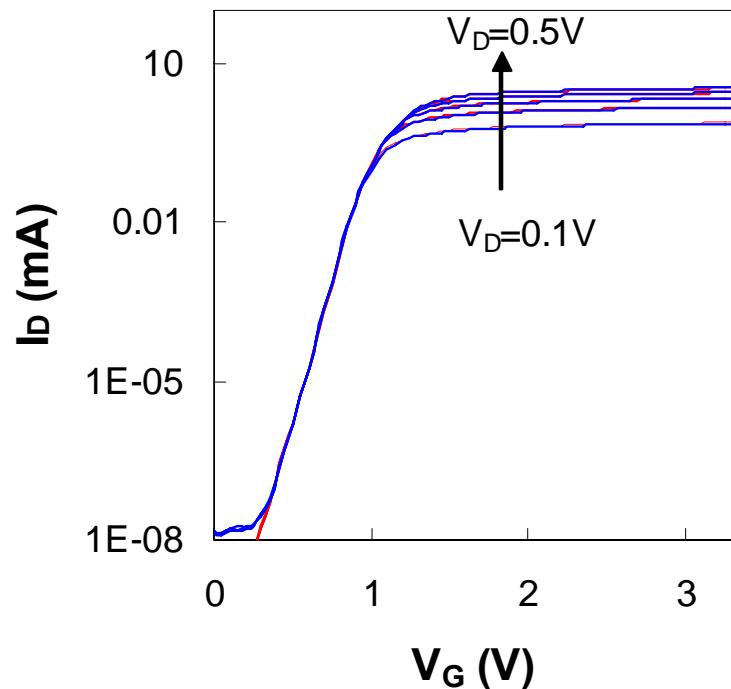
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Model Validation on 50V VDMOS

Transfer Characteristics (I_D - V_G)

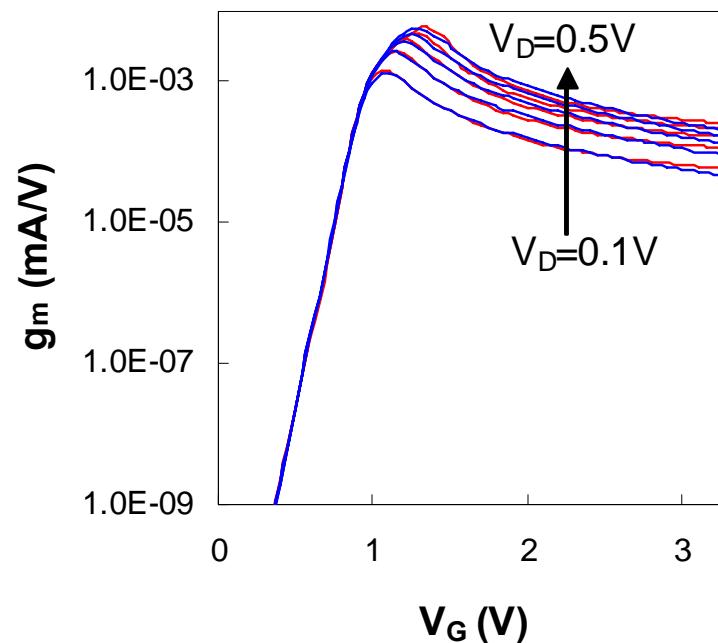
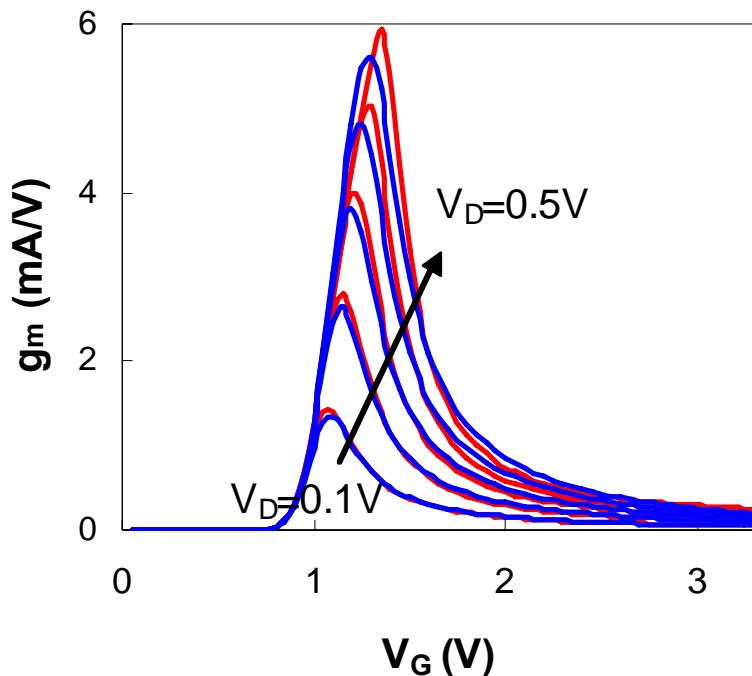
$V_D=0.1$ to 0.5 V



- Weak inversion to Strong inversion transition
- Subthreshold slope correctly matched
- Good accuracy

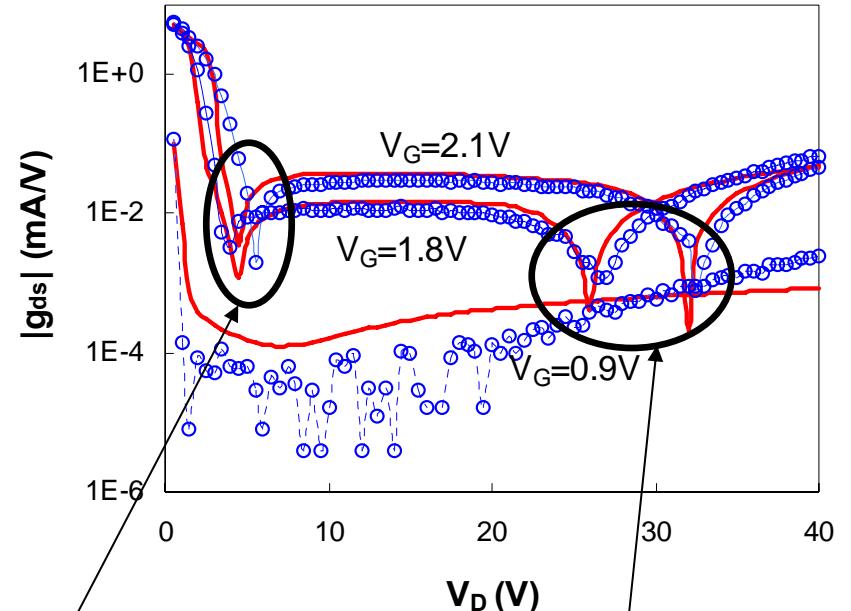
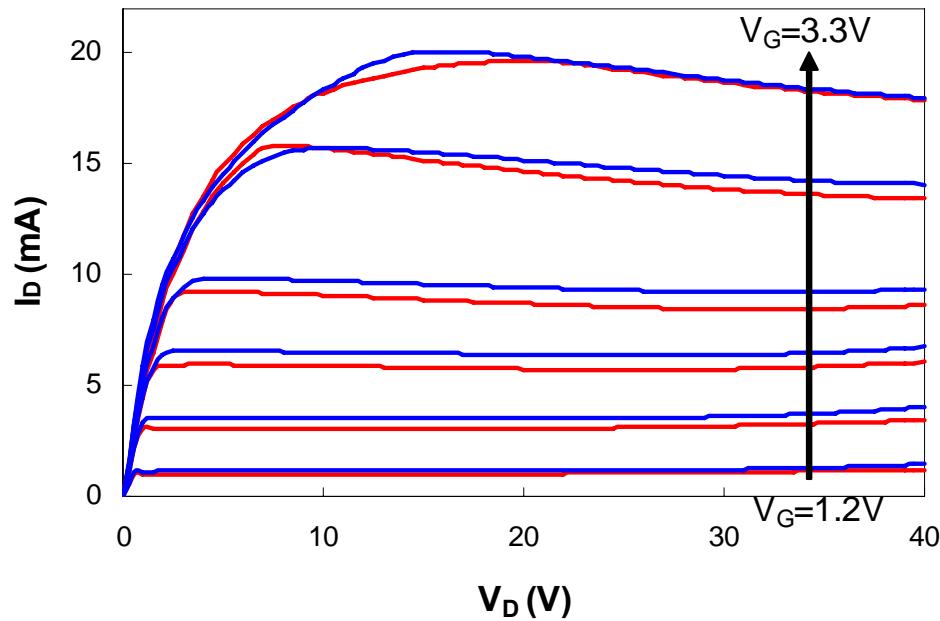
(red - model & blue - measurement)

Transconductance for $V_D=0.1-0.5V$



- Subthreshold slope correctly matched
- descending slope – drift resistance
(red - model & blue - measurement)

Output Characteristics



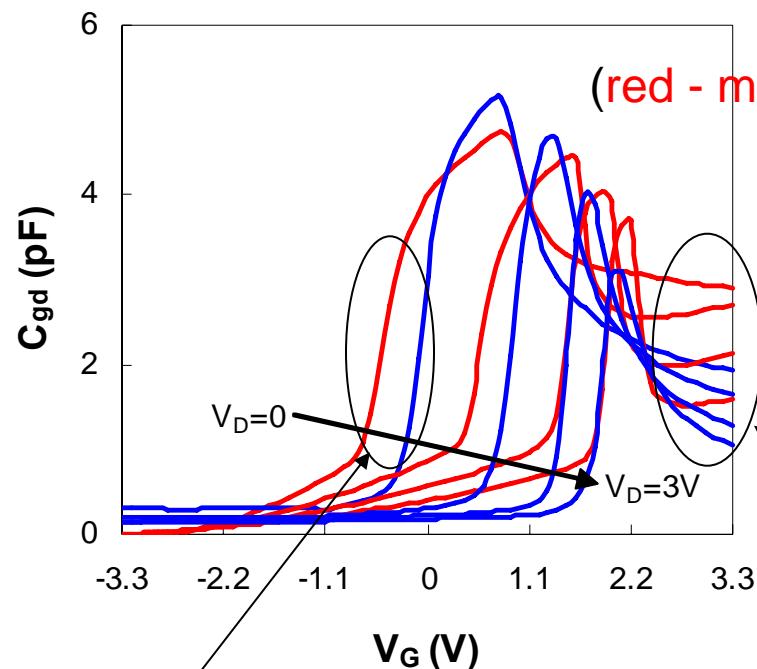
Self-Heating

Impact-Ionization

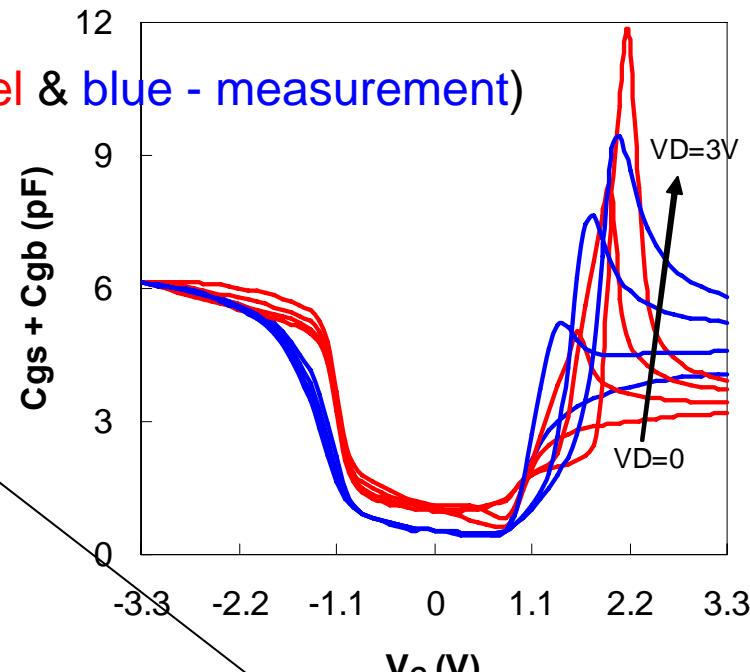
- Linear region correctly modeled by drift resistance.
 - Self Heating Effect
 - Peaks on g_{ds}
- (red - model & blue - measurement)

C_{GD} and $C_{GS}+C_{GB}$ vs V_G

$V_D=0-3V$



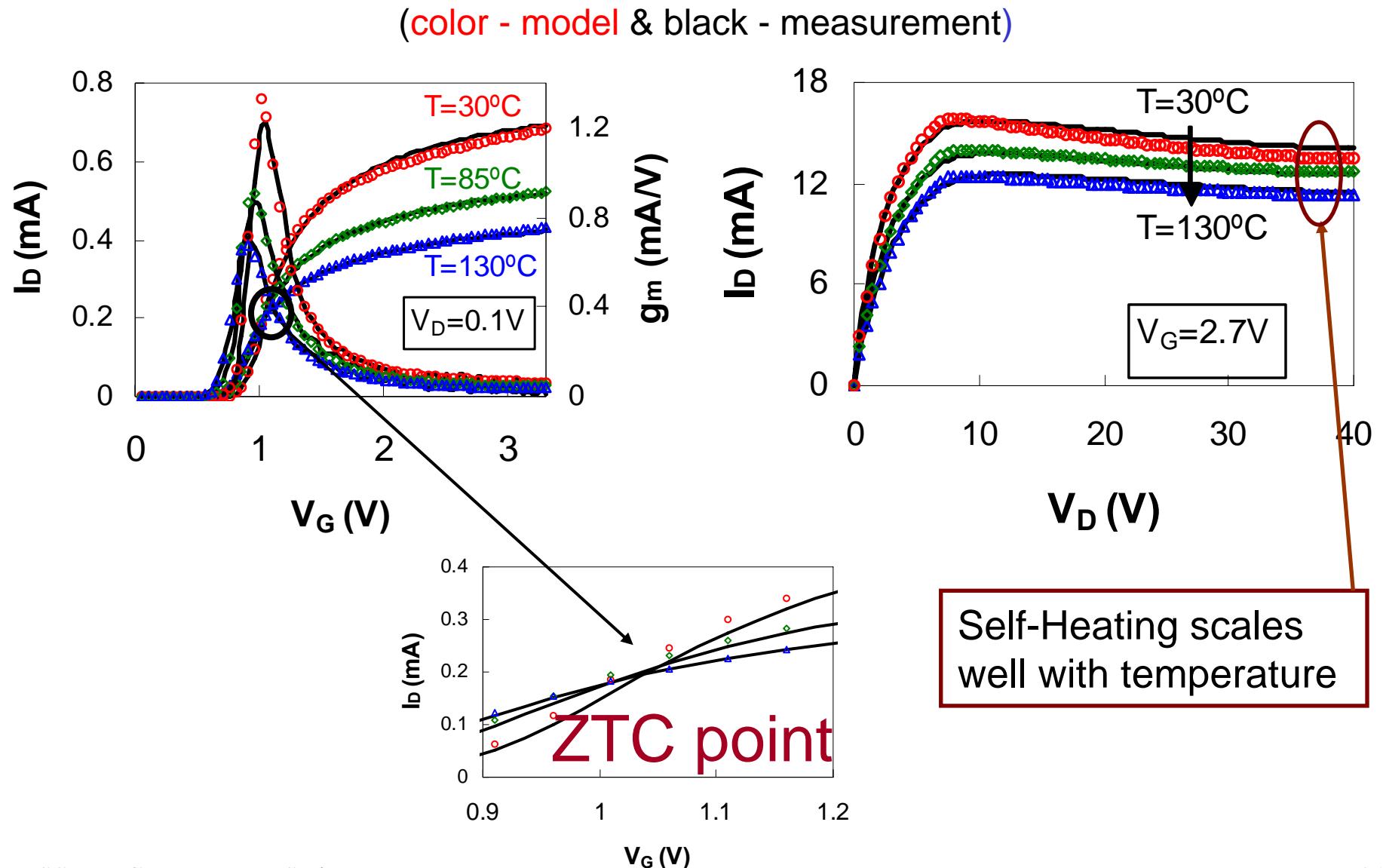
Lateral Doping in the channel



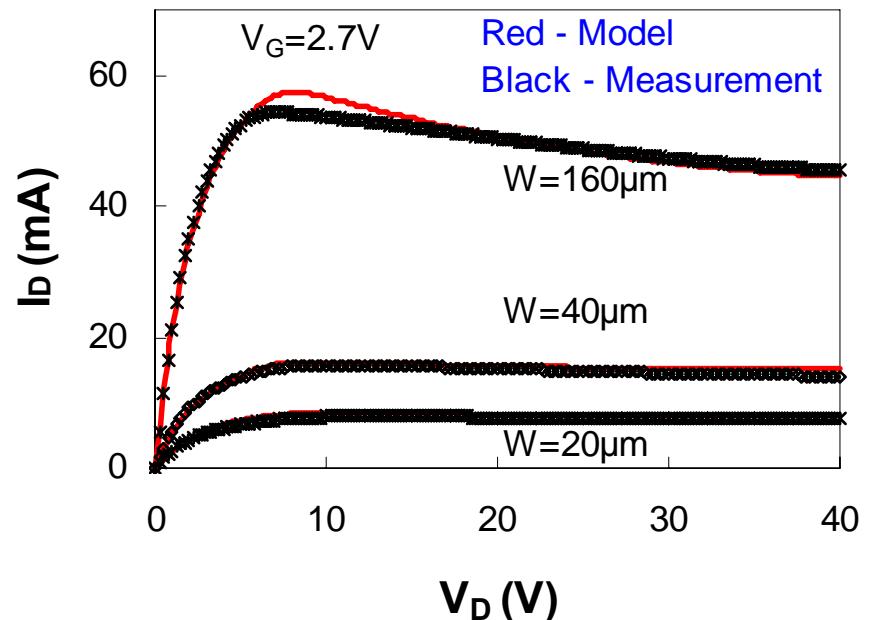
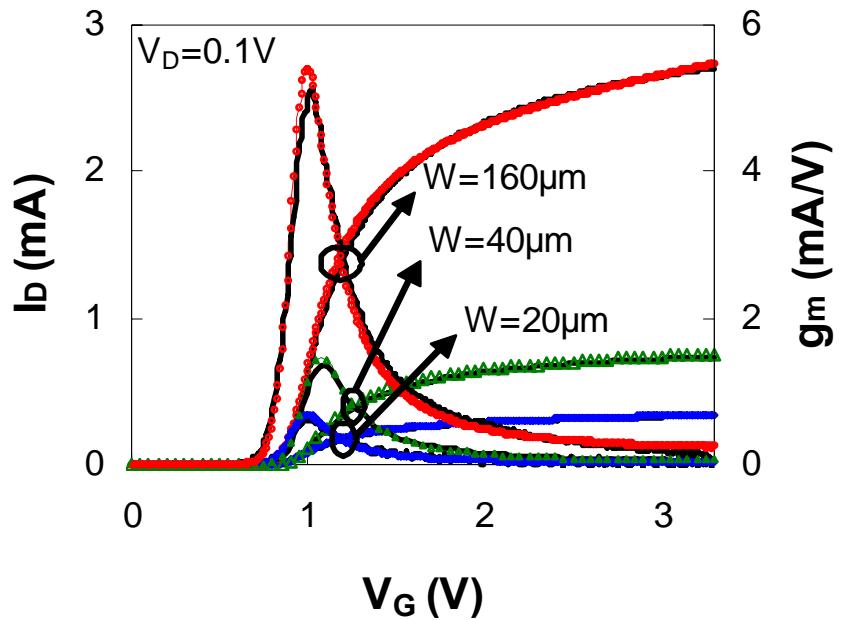
Interpolation function used in drift
(to be improved)

- Modeling of Non-uniform doping in intrinsic MOS (Chauhan et al. in *IEDM 2006*)

Temperature Scaling in VDMOS

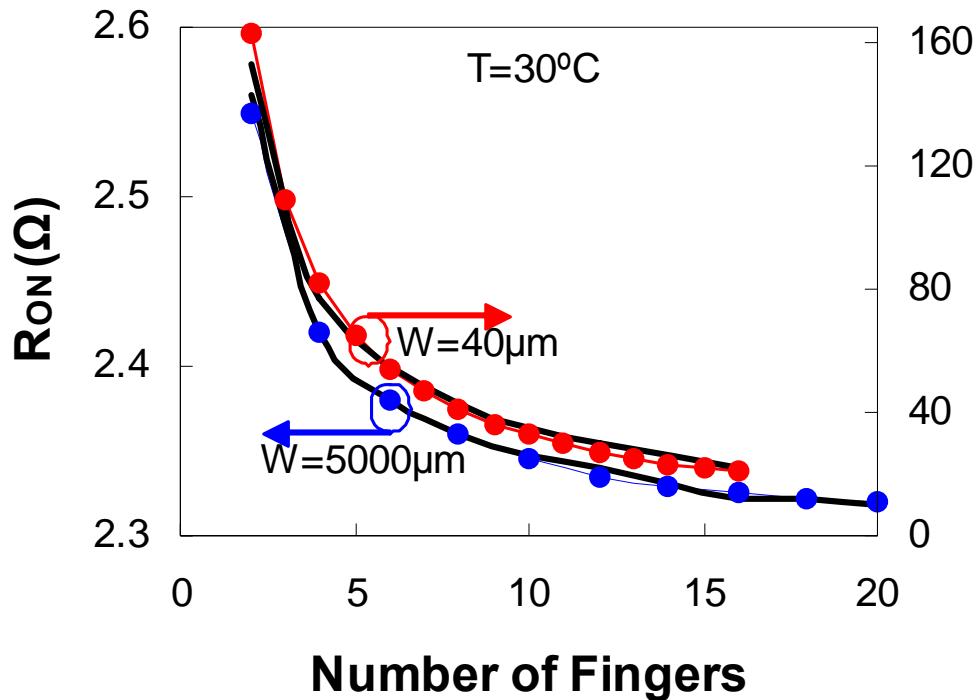


Width Scaling in VDMOS



- Increase in Current and transconductance with Width
 (red - model & black - measurement)

R_{ON} Scaling with number of fingers in VDMOS



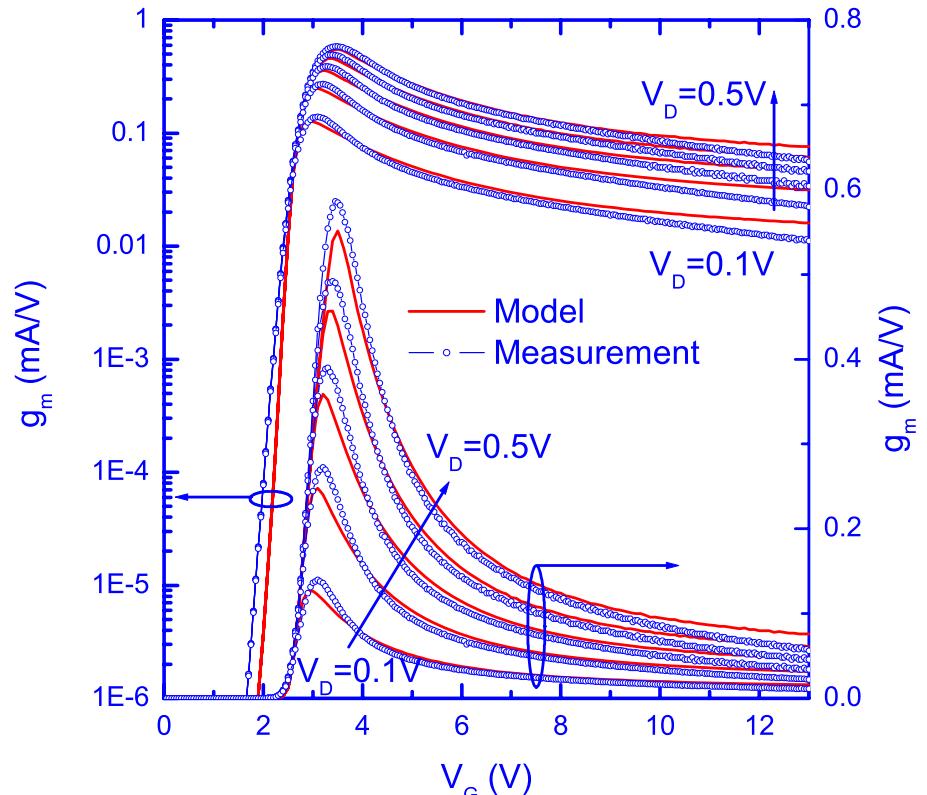
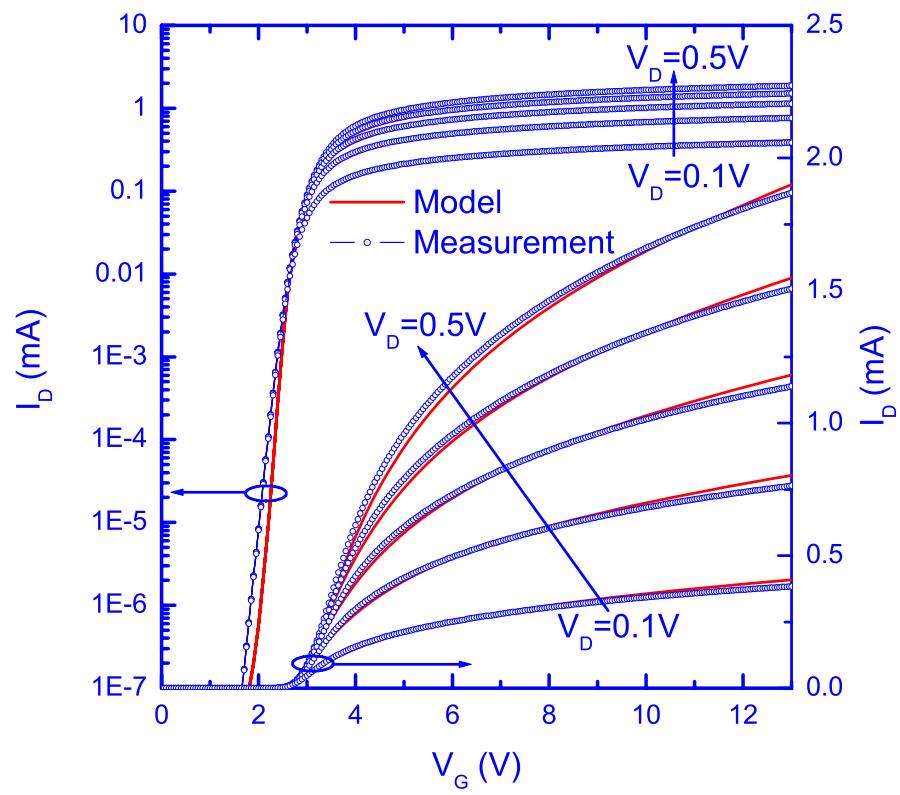
- $R_{ON} \downarrow$ - $N_F \uparrow$ for drain all-around-device due to current spreading at finger edges

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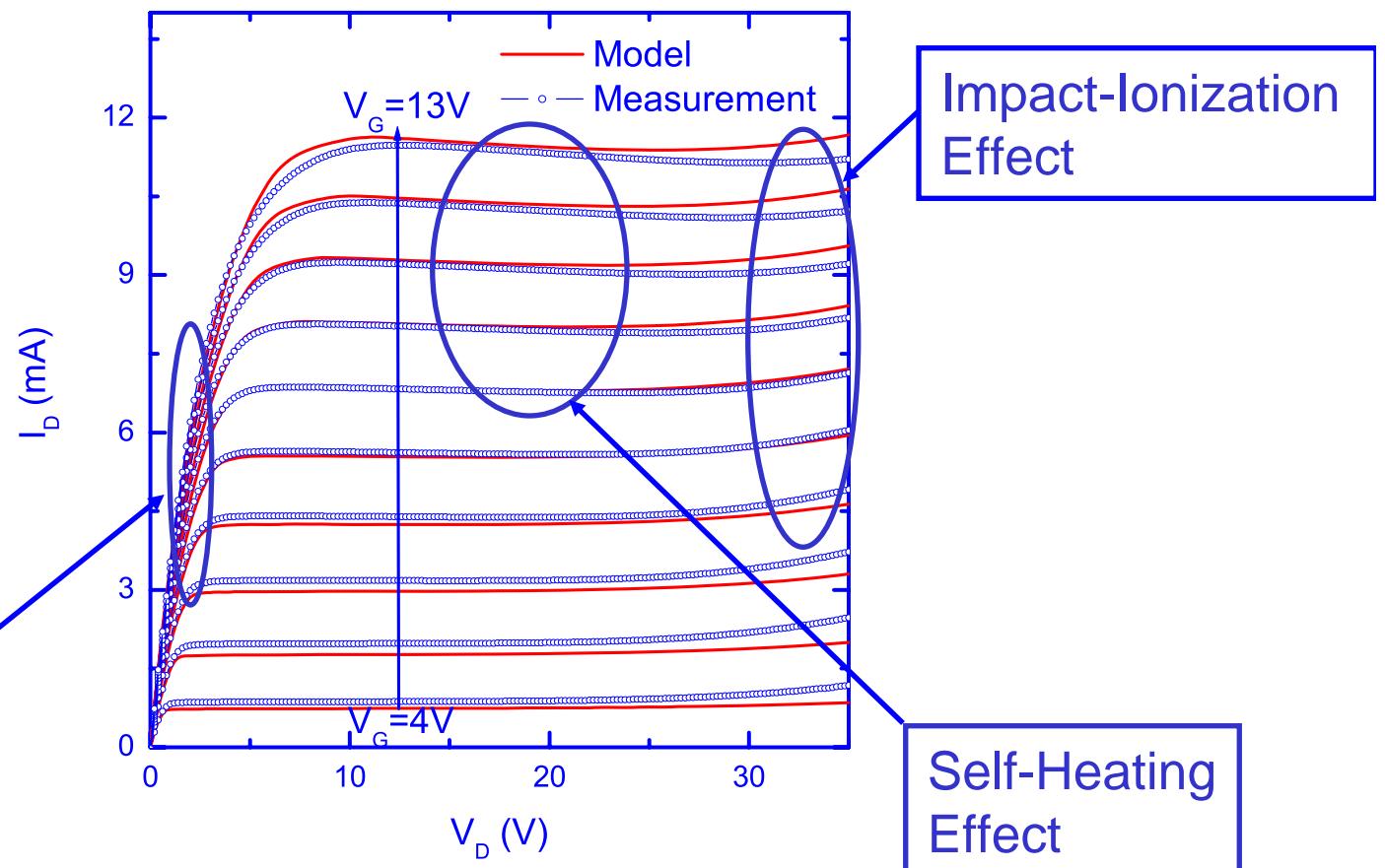
Model Validation on 40V LDMOS

Transfer Characteristics

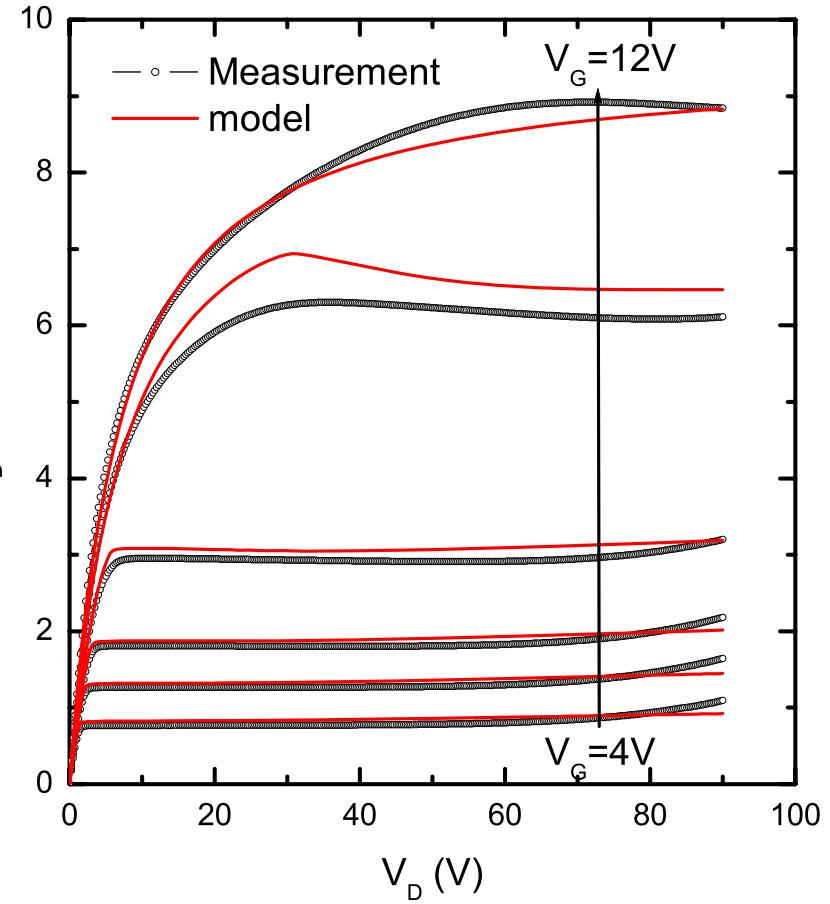
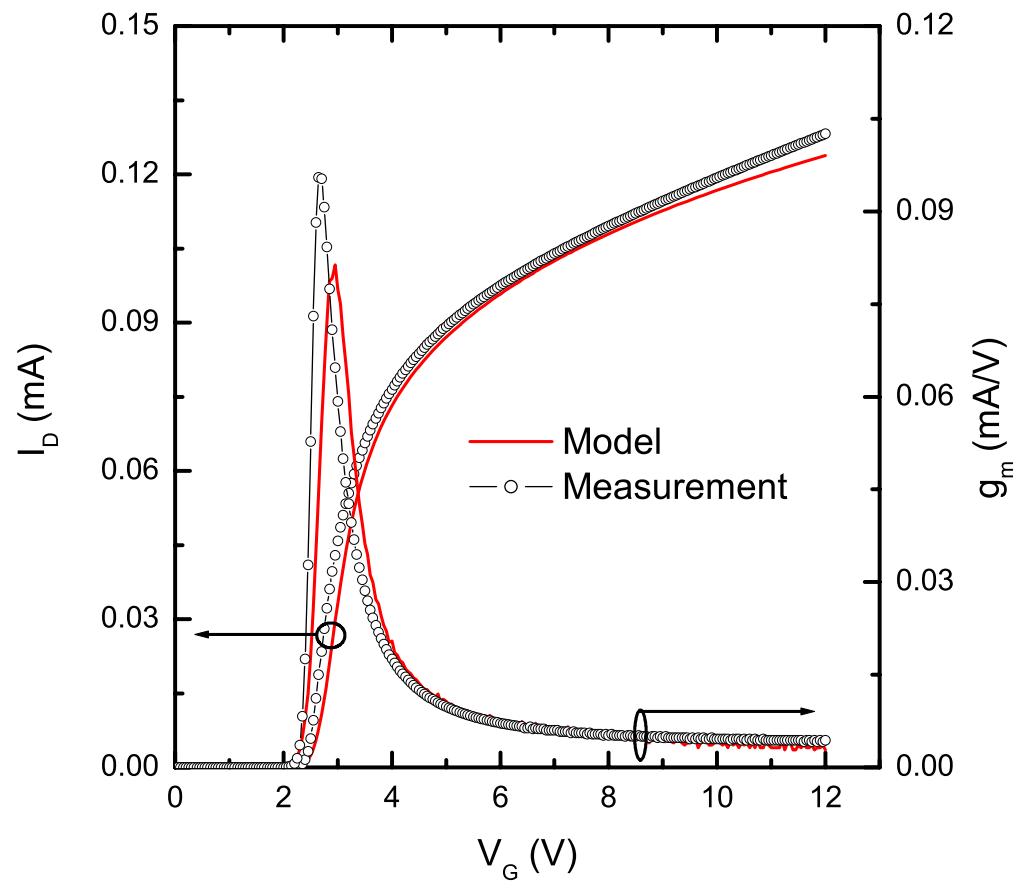


Model Validation on 40V LDMOS

Output Characteristics



Drift Length Scaling : 100V LDMOS



Conclusion

- An HV-EKV MOSFET model proposed
- Main number of parameters - 24
- Good performance in DC and AC operations
 - Error (I_{DS}) ~ 10%
 - Error (g_m) ~ 10%
 - Error (Capacitance) ~ 25%
- Tested for transient operations
- Model validated on industrial devices
- Excellent convergence and scalability
- Self-Heating effect included – No ill convergence
- Implemented in *Verilog-A* – Platform independent
- Tested on *ELDO*, *SABER*, Spectre, *UltraSim* simulators
- Model has been accepted for evaluation as a candidate for LDMOS standardization by *CMC*

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