

## Lecture IV

Linear equations, Bernoulli equations, Orthogonal trajectories, Oblique trajectories

## 1 Linear equations

A first order linear equations is of the form

$$y' + p(x)y = r(x) \quad (1)$$

This can be written as

$$(p(x)y - r(x))dx + dy = 0.$$

Here  $M = p(x)y - r(x)$  and  $N = 1$ . Now

$$\frac{1}{N} \left( \frac{\partial M}{\partial y} - \frac{\partial N}{\partial x} \right) = p(x)$$

Hence,

$$\mu(x) = e^{\int p(x) dx}$$

is an integrating factor. Multiplying (1) by  $\mu(x)$  we get

$$\frac{d}{dx} \left( e^{\int p(x) dx} y \right) = r(x) e^{\int p(x) dx}$$

Integrating we get

$$e^{\int p(x) dx} y = \int r(s) e^{\int p(s) ds} ds + C$$

which on simplification gives

$$y = e^{-\int p(x) dx} \left( C + \int r(s) e^{\int p(s) ds} ds \right)$$

**Example 1.** Solve  $y' + 2xy = 2x$

**Solution:** An integrating factor is  $e^{x^2}$ . Hence,

$$ye^{x^2} = \int 2te^{t^2} dt + C \Rightarrow y = 1 + Ce^{-x^2}$$

**Comment:** The usual notation  $dy/dx$  implies that  $x$  is the independent variable and  $y$  is the dependent variable. In trying to solve first order ODE, it is sometimes helpful to reverse the role of  $x$  and  $y$ , and work on the resulting equations. Hence, the resulting equation

$$\frac{dx}{dy} + p(y)x = r(y)$$

is also a linear equation.

**Example 2.** Solve  $(4y^3 - 2xy)y' = y^2$ ,  $y(2) = 1$

**Solution:** We write this as

$$\frac{dx}{dy} + \frac{2}{y}x = 4y$$

Clearly,  $y^2$  is an integrating factor. Hence,

$$xy^2 = \int 4y^3 dy + C \Rightarrow xy^2 = y^4 + C$$

Using initial condition, we find  $xy^2 = y^4 + 1$ .

## 2 Bernoulli's equation

This is of the form

$$y' + p(x)y = r(x)y^\lambda, \quad (2)$$

where  $\lambda$  is a real number. Equation (2) is linear for  $\lambda = 0$  or  $1$ . Otherwise, it is nonlinear and can be reduced to a linear form by substituting  $z = y^{1-\lambda}$

**Example 3.** Solve  $y' - y/x = y^3$

**Solution:** We write this as

$$y^{-3}y' - y^{-2}/x = 1$$

Substitute  $y^{-2} = z \Rightarrow -2y^{-3}y' = z'$ . This leads to

$$z' + 2z/x = -2$$

This is a linear equation whose solution is

$$zx^2 = -2x^3/3 + C$$

Replacing  $z$  we find

$$3\frac{x^2}{y^2} + 2x^3 = C$$

## 3 Reducible second order ODE

A general 2nd order ODE is of the form

$$F(x, y, y', y'') = 0$$

In some cases, by making substitution, we can reduce this 2nd order ODE to a 1st order ODE. Few cases are described below

**Case I:** If the *independent variable is missing*, then we have  $F(y, y', y'') = 0$ . If we substitute  $w = y'$ , then  $y'' = w \frac{dw}{dy}$ . Hence, the ODE becomes  $F(y, w, w \frac{dw}{dy}) = 0$ , which is a 1st order ODE.

**Example 4.** Solve  $2y'' - y'^2 - 4 = 0$

**Solution:** With  $w = y'$ , the above equation becomes

$$2w \frac{dw}{dy} - w^2 - 4 = 0 \Rightarrow \ln[(w^2 + 4)/C] = y \Rightarrow w = \pm \sqrt{Ce^y - 4}$$

Since  $w = y'$ , we find

$$\frac{dy}{\sqrt{Ce^y - 4}} = \pm x + D$$

The integral on the LHS can be evaluated by substitution.

**Case II:** If the *dependent variable is missing*, then we have  $F(x, y', y'') = 0$ . If we substitute  $w = y'$ , then  $y'' = w'$ . Hence, the ODE becomes  $F(x, w, w') = 0$ , which is a 1st order ODE.

**Example 5.** Solve  $xy'' + 2y' = 0$

**Solution:** Substitute  $w = y'$ , then we find

$$\frac{dw}{dx} + \frac{2}{x}w = 0 \Rightarrow w = Cx^{-2}$$

Since  $w = y'$ , we further get

$$y' = C/x^2 \Rightarrow y = -C/x + D$$

## 4 Orthogonal trajectories

**Definition 1.** Two families of curves are such that each curve in either family is orthogonal (whenever they intersect) to every curve in the other family. Each family of curves is orthogonal trajectories of the other. In case the two families are identical, they we say that the family is self-orthogonal.

**Comment:** Orthogonal trajectories has important applications in the field of physics. For example, the equipotential lines and the streamlines in an irrotational 2D flow are orthogonal.

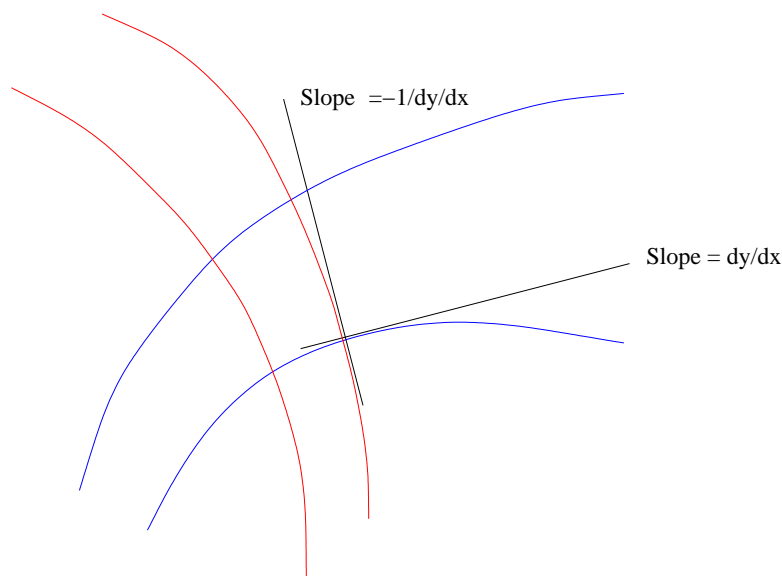


Figure 1: Orthogonal trajectories.

### 4.1 How to find orthonal trajectories

Suppose the first familiy

$$F(x, y, c) = 0. \quad (3)$$

To find the orthogonal trajectories of this family we proceed as follows. First, differentiate (3) w.r.t.  $x$  to find

$$G(x, y, y', c) = 0. \quad (4)$$

Now eliminate  $c$  between (3) and (4) to find the differential equation

$$H(x, y, y') = 0 \quad (5)$$

corresponding to the first family. As seen in Figure 1, the differential equation for the other family is obtained by replacing  $y'$  by  $-1/y'$ . Hence, the differential equation of the orthogonal trajectories is

$$H(x, y, -1/y') = 0 \quad (6)$$

General solution of (6) gives the required orthogonal trajectories.

**Example 6.** Find the orthogonal trajectories of family of straight lines through the origin.

**Solution:** The family of straight lines through the origin is given by

$$y = mx$$

The ODE for this family is

$$xy' - y = 0$$

The ODE for the orthogonal family is

$$x + yy' = 0$$

Integrating we find

$$x^2 + y^2 = C,$$

which are family of circles with centre at the origin.

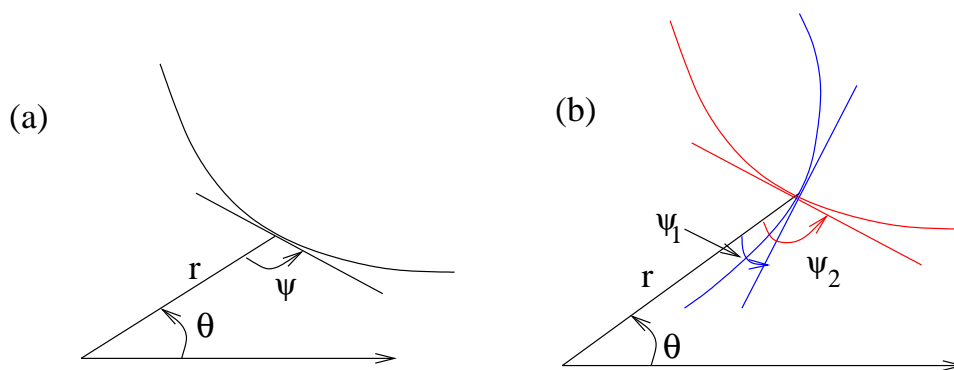


Figure 2: Orthogonal trajectories.

## 4.2 \*Orthogonal trajectories in polar coordinates

Consider a curve in polar coordinate. The angle  $\psi$  between the radial and tangent directions is given by

$$\tan \psi = \frac{r \, d\theta}{dr}$$

Consider the curve with angle  $\psi_1$ . The curve that intersects it orthogonally has angle  $\psi_2 = \psi_1 + \pi/2$ . Now

$$\tan \psi_2 = -\frac{1}{\tan \psi_1}$$

Thus, at the point of orthogonal intersection, the value of

$$\frac{r d\theta}{dr} \tag{7}$$

for the second family should be negative reciprocal of the value of (7) of the first family. To illustrate, consider the differential equation for the first family:

$$Pdr + Qd\theta = 0.$$

Thus we find  $r d\theta/dr = -Pr/Q$ . Hence, the differential equation of the orthogonal family is given by

$$\frac{r d\theta}{dr} = \frac{Q}{Pr}$$

or

$$Q dr - r^2 P d\theta = 0$$

General solution of the last equation gives the orthogonal trajectories.

**Example 7.** Find the orthogonal trajectories of family of straight lines through the origin.

**Solution:** The family of straight lines through the origin is given by

$$\theta = A$$

The ODE for this family is

$$d\theta = 0$$

The ODE for the orthogonal family is

$$dr = 0$$

Integrating we find

$$r = C,$$

which are family of circles with centre at the origin.

### 4.3 Oblique trajectories

Here the two families of curves intersect at an arbitrary angle  $\alpha \neq \pi/2$ . Suppose the first family

$$F(x, y, c) = 0. \tag{8}$$

To find the oblique trajectories of this family we proceed as follows. First, differentiate (8) w.r.t.  $x$  to find

$$G(x, y, y', c) = 0. \tag{9}$$

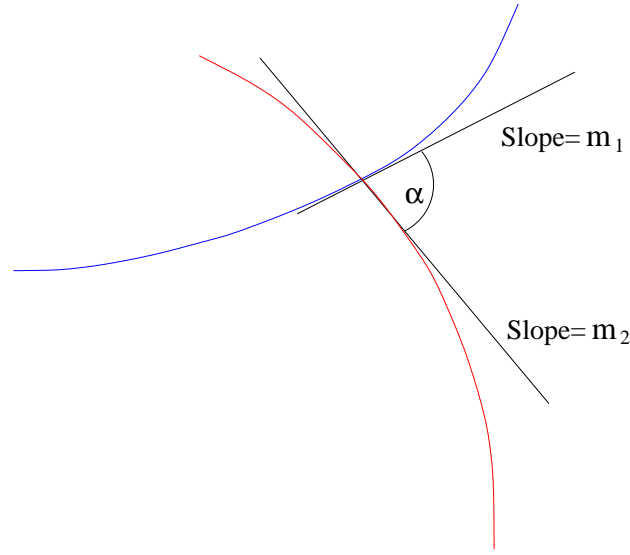


Figure 3: Oblique trajectories.

Now eliminate  $c$  between (8) and (9) to find the differential equation

$$H(x, y, y') = 0. \quad (10)$$

Now if  $m_1$  is the slope of this family, then we write (10) as

$$H(x, y, m_1) = 0, \quad (11)$$

Let  $m_2$  be the slope of the second family. Then

$$\pm \tan \alpha = \frac{m_1 - m_2}{1 + m_1 m_2}.$$

Thus, we find

$$m_1 = \frac{m_2 \pm \tan \alpha}{1 \mp m_2 \tan \alpha}$$

Hence, from (11), the ODE for the second family satisfies

$$H\left(x, y, \frac{m_2 \pm \tan \alpha}{1 \mp m_2 \tan \alpha}\right) = 0,$$

Replacing  $m_2$  by  $y'$ , the ODE for the second family is written as

$$H\left(x, y, \frac{y' \pm \tan \alpha}{1 \mp y' \tan \alpha}\right) = 0. \quad (12)$$

General solution of (12) gives the required oblique trajectories.

**Note:** If we let  $\alpha \rightarrow \pi/2$ , we obtained ODE for the orthogonal trajectories.

**Example 8.** Find the oblique trajectories that intersects the family  $y = x + A$  at an angle of  $60^\circ$

**Solution:** The ODE for the given family is

$$y' = 1$$

For the oblique trajectories, we replace

$$y' \text{ by } \frac{y' \pm \tan(\pi/3)}{1 \mp y' \tan(\pi/3)} = \frac{y' \pm \sqrt{3}}{1 \mp \sqrt{3}y'}$$

Thus, the ODE for the oblique trajectories is given by

$$\frac{y' \pm \sqrt{3}}{1 \mp \sqrt{3}y'} = 1$$

Simplifying we obtain

$$y' = \frac{1 - \sqrt{3}}{1 + \sqrt{3}} \quad \text{OR} \quad y' = \frac{1 + \sqrt{3}}{1 - \sqrt{3}}$$

Hence, the oblique trajectories are either

$$y = \frac{1 - \sqrt{3}}{1 + \sqrt{3}}x + C_1$$

Or

$$y = \frac{1 + \sqrt{3}}{1 - \sqrt{3}}x + C_2$$