

Useful Information

- $g = 9.8 \text{ m/s}^2$, density of water = 10^3 kg/m^3 , viscosity of water = 10^{-3} Pa s .
- Kinetic energy correction factor $\alpha = 2$ for laminar flow, $\alpha = 1$ for turbulent flow in pipes.
- $\frac{d}{dx} \sin^{-1}(x) = \frac{1}{\sqrt{1-x^2}}$, $\frac{d}{dx} \cos^{-1}(x) = -\frac{1}{\sqrt{1-x^2}}$, $\frac{d}{dx} \tan^{-1}(x) = \frac{1}{1+x^2}$
- Loss coefficient K for: entrance = 0.5, elbow (90°) = 0.9, gate valve (fully open) = 0.3, gate valve (half open) = 5.

Clearly state all the assumptions you make

1. An infinitely long cylindrical wire of radius R_1 is pulled (with constant velocity V) through a circular cylindrical tube of radius R_2 filled with a liquid of viscosity μ and density ρ , as shown in figure 1. The wire is placed coaxially in the tube, i.e. their axes of revolution coincide. The cylindrical tube connects two large reservoirs of the liquid maintained at a constant pressure P_0 . Determine:
 - (a) The steady velocity profile in the fully-developed region of the cylindrical tube, neglecting entrance and exit effects. Give brief reasons for why certain terms are neglected in the Navier-Stokes equations (see over-leaf for Navier-Stokes equations in cylindrical coordinates). [4 points]
 - (b) The force per unit length required to pull the wire through the cylindrical tube. (Neglect contributions to the force from the liquid in the reservoirs.) [3 points]

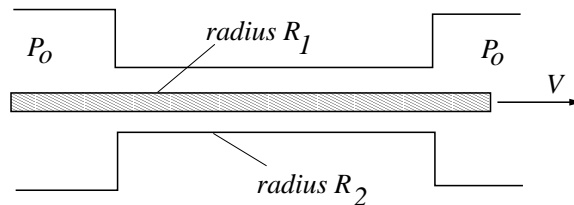


Figure 1: **Problem 1**

2. Consider a water tank which is connected to a pipe system as shown in figure 2. The pipe walls are *smooth*, and the pipe system has a sharp-edged entrance, one 90° elbow, and a fully-open gate valve. Water exits from the pipe to atmospheric pressure. The pipe diameter is 5 cm, and the total length of the pipe is 1 m. Calculate the minimum height H of the water in the tank above the pipe system discharge (H shown in the figure), such that the Reynolds number of flow in the pipe is 10^5 . [6 points]

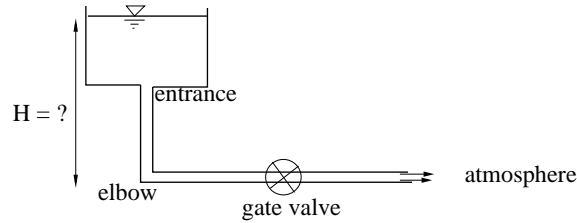


Figure 2: **Problem 2**

3. A swimming pool is approximated by a Rankine half-body shape as shown in figure 3. At point O, which is 0.5 m from the left edge of the swimming pool, there is a line source (into the paper) of water delivering $0.35 \text{ m}^3/\text{s}$ per meter of depth into the paper. Assuming potential flow, find the coordinates of point B along the axis where the water velocity is 25 cm/s. [7 points]

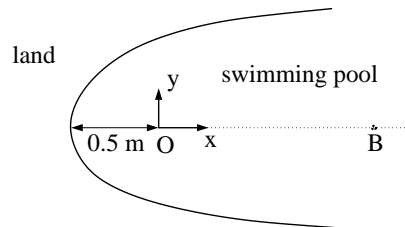


Figure 3: **Problem 3**

Navier-Stokes equations in cylindrical coordinates:

Continuity:

$$\frac{1}{r} \frac{\partial (rv_r)}{\partial r} + \frac{1}{r} \frac{\partial v_\theta}{\partial \theta} + \frac{\partial v_z}{\partial z} = 0$$

r-momentum:

$$\rho \left[\frac{\partial v_r}{\partial t} + v_r \frac{\partial v_r}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_r}{\partial \theta} + v_z \frac{\partial v_r}{\partial z} - \frac{v_\theta^2}{r} \right] = -\frac{\partial p}{\partial r} + \mu \left[\frac{\partial}{\partial r} \left(\frac{1}{r} \frac{\partial (rv_r)}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 v_r}{\partial \theta^2} + \frac{\partial^2 v_r}{\partial z^2} - \frac{2}{r^2} \frac{\partial v_\theta}{\partial \theta} \right] + \rho g_r$$

z-momentum:

$$\rho \left[\frac{\partial v_z}{\partial t} + v_r \frac{\partial v_z}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_z}{\partial \theta} + v_z \frac{\partial v_z}{\partial z} \right] = -\frac{\partial p}{\partial z} + \mu \left[\frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial v_z}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 v_z}{\partial \theta^2} + \frac{\partial^2 v_z}{\partial z^2} \right] + \rho g_z$$

θ -momentum:

$$\rho \left[\frac{\partial v_\theta}{\partial t} + v_r \frac{\partial v_\theta}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_\theta}{\partial \theta} + v_z \frac{\partial v_\theta}{\partial z} + \frac{v_\theta v_r}{r} \right] = -\frac{1}{r} \frac{\partial p}{\partial \theta} + \mu \left[\frac{\partial}{\partial r} \left(\frac{1}{r} \frac{\partial (rv_\theta)}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 v_\theta}{\partial \theta^2} + \frac{\partial^2 v_\theta}{\partial z^2} + \frac{2}{r^2} \frac{\partial v_\theta}{\partial \theta} \right] + \rho g_\theta$$