

# AN ADAPTIVE PROBABILISTIC ROUTING ALGORITHM

*by*

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# AN ADAPTIVE PROBABILISTIC ROUTING ALGORITHM

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**CERTIFICATE**

It is certified that the work contained in the thesis entitled “*An Adaptive Probabilistic Routing Algorithm*” by *Swapnil Shukla* has been carried out under my supervision and that this work has not been submitted elsewhere for a degree.

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Swapnil Shukla

## Abstract

The internet has grown and changed ever since the first connections were made in 1969. The problem of routing assignments has been one of the most intensively studied areas in the fields of data networks since then. Network routing essentially consists of two entities the Routing Protocol and the Routing Algorithm. The routing protocol provides each node in a network, a consistent view of the topology and the routing algorithm provides the intelligence to compute paths between nodes. The focus of this thesis is on Routing Algorithm.

Routing algorithms can broadly be classified into Selfish and Non-Selfish Routing Algorithms. This thesis starts with discussion of the problems faced with Selfish routing algorithms and presents a Non-Selfish Routing Algorithm with the aim to solve the problems. This algorithm falls into category of multipath routing. Performance of the network is improved because the resources of multiple paths are utilized.

Finally extensive simulations have been carried out for evaluation of the performance of the algorithm in different scenarios. The factors that decide the performance of a network are how frequently updates are sent and how frequently routes are computed. The effect of variation of these factors on convergence time, load on routers and the queue size have been studied.

# Contents

<b>1</b>	<b>Introduction</b>	<b>1</b>
1.1	Routing in the Internet . . . . .	2
1.1.1	Subnetting . . . . .	4
1.1.2	Hierarchical Routing . . . . .	5
1.2	Goals of Routing Protocols . . . . .	6
1.3	Existing Routing Algorithms . . . . .	8
1.3.1	The Distance Vector Routing Algorithm . . . . .	8
1.3.2	The Link State Routing Algorithm . . . . .	9
1.4	Problems with Selfish Routing . . . . .	10
1.5	Work Done . . . . .	11
1.6	Organization of the thesis . . . . .	11
<b>2</b>	<b>The Probabilistic Routing Algorithm</b>	<b>13</b>
2.1	Structure of the Routing Table . . . . .	13
2.2	Advantages of the Structure . . . . .	14
2.2.1	Using Multiple Paths . . . . .	14

2.2.2	Network Oscillations . . . . .	14
2.2.3	Routing Loops . . . . .	15
2.3	The Algorithm . . . . .	17
2.3.1	Computation of the Routing Table . . . . .	17
2.4	Example Network . . . . .	22
<b>3</b>	<b>Simulation and Results</b>	<b>30</b>
3.1	Implementation Details . . . . .	30
3.2	Factors affecting the performance . . . . .	33
3.3	Results . . . . .	35
3.3.1	Convergence Time . . . . .	35
3.3.2	Load on the Routers . . . . .	39
3.3.3	Size of the Queue . . . . .	40
<b>4</b>	<b>Conclusion</b>	<b>42</b>
4.1	Future Aspects . . . . .	43

# List of Figures

2.1	Scenario depicting Network Oscillations . . . . .	15
2.2	Scenario demonstrating Network Loop . . . . .	16
2.3	Demonstration of update rejection . . . . .	21
2.4	Example Network . . . . .	22
3.1	Network A . . . . .	32
3.2	Network B . . . . .	33
3.3	Convergence Time vs Route Computation Delay for Network A . . . . .	36
3.4	Convergence Time vs Route Computation Delay for Network B . . . . .	37
3.5	Convergence Time vs Number of Events for Network A . . . . .	37
3.6	Convergence Time vs Number of Events for Network B . . . . .	38
3.7	Router Load in percentage vs Route Computation Delay for Network A . . . . .	39
3.8	Router load in percentage vs Route Computation Delay for Network B . . . . .	40
3.9	Size of Queue on a router vs Time . . . . .	41



# Chapter 1

## Introduction

Computer networks have been growing at an enormous rate ever since the concept was first proposed, for example, networks were first designed with two different purposes which later on merged to form the internet. The military network (MILNET) was designed to keep military communications working under a war. The American University Networks (National Science Foundation Network, NSFNET / Advanced Research Projects Agency Network, ARPANET) were designed to make the exchange of research results easier.

Large-scale, wide area data networks are a part of today's global communication infrastructure. Networks such as the Internet have become an integral medium of information transfer, ranging from personal communication to electronic commerce and entertainment. The importance of such networks will keep on increasing as the electronic world becomes more and more prevalent.

The basic function of a data network is very simple: delivering data from one

network node to another. Data networks can be viewed as huge graph with routers as vertices and transmission lines as edges. On such a huge graph the data packets must find their way from the source to the destination. Routing can be described as the process of creating a logical connection between nodes in a network so that packets sent by a node can reach their destination [13].

The challenge in developing network routing algorithms is in dealing with the scale and distribution of the physical network. As wide area networks have nodes on the order of tens of thousands, routing algorithms must be scalable. Moreover, routing algorithms must be able to calculate paths in a distributed manner due to the global and distributive nature of physical networks. Also, routing algorithms need to cope with events such as node and link failures and recalculate paths whenever such events occur. Finally, routing algorithms need to calculate paths to allow nodes to achieve high network performance.

## 1.1 Routing in the Internet

The Internet is a global data network having millions of hosts. The Internet is a best effort datagram network: units of data transmission are packetized, and each packet is individually and independently delivered (hop-by-hop) to its destination without any guarantee of success, packets can be dropped in transit [9]. In order for a node to send packets to another node, the sending node must specify the destination node. In the Internet today, every node is uniquely identified by an 32 bit IP address [12].

Thus for node  $\mathcal{A}$  to send a packet to node  $\mathcal{B}$ ,  $\mathcal{A}$  must designate the IP address of  $\mathcal{B}$  as the packet's destination. This universal naming allows every node in the Internet to uniquely identify every other node.

Physically, the Internet is a collection of smaller inter-networks called routing domains (or autonomous systems). Each routing domain is responsible for routing packets within itself. That is, packets destined to hosts in a routing domain are routed by the domain's routing algorithm. An intra-domain routing algorithm refers to a routing algorithm that routes packets within a domain, and an inter-domain routing algorithm is responsible for routing packets between domains. Using this organization, packets sent from one domain to another are first routed out of the sending domain, then to the destination domain, and finally to the destination host by the destination domain's routing algorithm. Thus, logical Internet connectivity is ensured by the cooperation of inter- and intra-domain routing algorithms.

It is practically impossible to maintain an entry for every destination (host) in the internet, because of two reasons. Firstly the size of routing table will be enormous this will require a large amount of space on the routers. Secondly the time taken to look up a destination in such an enormous table will be very high. Because of the size of the Internet, two methods are used to make the network scalable: subnetting and hierarchical routing domains. Subnetting uses the IP addressing structure so that routers can route packets based on a set of hosts instead of individual hosts, and hierarchical routing domains reduce the size of routing domains. Both of these methods

are described below.

### **1.1.1 Subnetting**

Internet addresses are divided into subnets. A subnet is identified by its IP address prefix. Whenever an organization wants to connect to the Internet, it needs to obtain a unique subnet address or a set of unique subnet addresses. Furthermore, every host owned by the organization that connects to the Internet needs to have an IP address such that the IP prefix of the host address is the same as one of the subnet addresses obtained by the organization. The number of bits in the IP prefix is variable length.

With subnet addressing, routers outside a subnet need to know and maintain only a single route (i.e. state) for all the hosts in the subnet. That is, routers outside a particular subnet do not need to maintain a route for every hosts in that subnet, but rather, these routers only need to maintain one route to the subnet; this route is used to forward packets to every host in that subnet. Because several thousand hosts can have the same subnet address, subnetting allows substantial space savings in routers, making routing over the Internet more scalable.

However, subnetting alone is not enough to provide scalability because there are hundreds of thousands of subnet addresses in the Internet. To further reduce the amount of information that routers have to process and store, hierarchical routing domains are used.

### 1.1.2 Hierarchical Routing

Hierarchical routing allows a routing domain to contain subnet addresses as well as other routing domains (represented by a set of subnet addresses). Conceptually, routing is hierarchically structured such that at the lowest level, a routing algorithm routes packets to hosts with the same subnet address. At the second level, a routing algorithm routes packets among second-level routing domains using the subnet addresses the routing domains encompass. Similarly, at level  $i$ , a routing algorithm routes packets to the appropriate level  $i$  routing domain that contains the packets destination subnet address.

Because of the inclusive property of routing domains, a packet is routed to level  $i + 1$  if the packet is destined for a subnet address that is not in level  $i$ . Eventually, routers in the highest level of the hierarchy, say level  $L$ , know about every subnet address and the level  $L$  routing domain that contains the address.

Thus a packet destined for a different subnet first travels up the domain hierarchy, until it reaches the routing domain that is the first common ancestor of both the source and destination routing domains. From this ancestor domain, the packet then travels down the hierarchy until it reaches the destination domain. The destination domain's routing algorithm then ensures the packet reaches its destination.

This hierarchical organization achieves scalability because a routing algorithm operating in a level  $i$  routing domain only needs to compute paths to nodes at that level. A node at level  $i$  could be a host (if  $i = 1$ ) or a level  $i - 1$  routing domain. If a node is

a routing domain, then the node advertises the subnet addresses that it encompasses. With this hierarchical structure, a routing algorithm at a particular level only has to compute paths to nodes at that level, thereby reducing the size of path recomputations that routers need to perform.

Conceptually, the Internet routing hierarchy can have many levels. However, in practice, the Internet routing is divided into only two levels, intra-domain (lower level) and inter-domain (higher level) routing levels. Although the size of host addresses is different from domain addresses, a routers basic mechanisms for computing paths and forwarding packets are the same. Thus, the routing algorithm described in this thesis are applicable for all the levels of the routing hierarchy.

## 1.2 Goals of Routing Protocols

A lot of Routing protocols [3, 5, 8] have been developed for this purpose they all vary in the way they accomplish the task, but they all have more or less common goals.

The main goals are [4, 6]:

- Low latency for end to end communication. Latency is the time taken by the packet to reach its destination from its source.
- Low latency jitter for end to end communication. Latency jitter is the variation in latency, for real time applications such as streaming video, the requirement for low latency jitter is more important than the requirement of low latency.

- High throughput for end to end communication. Throughput can be defined as the number of data packets delivered per second. Throughput is affected by packets being dropped, and protocol data units that are used by protocols to set up communication with peers.
- Low packet loss or High Reliability. Packet loss causes decrease in throughput and increases latency.
- Low convergence time in case of changes in network topology. It is necessary for routing algorithm to adapt to changes in network as quickly as possible, so that utilization of network resources is maximized.
- Low routing overhead. Routing overhead is caused by the update packets that are exchanged by routing protocols to convey network information to its peers. Routing overhead decreases throughput.

It is not possible for a routing protocol to achieve all the goals. As some of the above stated goals are conflicting in nature, for example to achieve Low convergence time in case of change in topology certainly requires high routing overhead which in turn reduces the throughput for end to end communication.

Normally routing is split into two groups: Source Routing and Destination Routing.

**Source Routing** is where the source specifies the path a packet should traverse to reach its destination. This requires each node in the network to have a precise

knowledge of the network, which seems almost impossible to accomplish on the networks which are dynamic in nature and hence hampers the adaptiveness.

**Destination Routing** is where each node knows in which direction to forward a packet for a given destination. Here the source node has no control over the path a packet traverses. The internet works on this kind of routing.

In dynamically changing networks Source Routing is not deployed and Destination Routing is the obvious choice.

## 1.3 Existing Routing Algorithms

The chapter begins by describing the two predominant routing algorithms, the Distance Vector and Link State routing algorithms [14, 26], which are the basis of many Internet routing protocols. This section briefly summarizes the two algorithms.

### 1.3.1 The Distance Vector Routing Algorithm

The distance vector [7] routing algorithm is a distributed, adaptive routing algorithm that computes shortest paths between all node pairs. The distance vector routing algorithm is the basis of many practical routing algorithms currently in use.

Here a router computes a routing table which is used to forward packets on the best known path to its destination. Each entry in a routing table contains three elements: the destination address, the next-hop neighbor on the known shortest path to that destination, and the cost of the known path. Each routers forwarding table is



continually updated by the distributed Distance Vector algorithm to indicate, via the next-hop entry, the shortest path between nodes. Routers update their routing tables by exchanging path information with their neighbors via distance vector packets. A distance vector packet carries the identity of the originating router and a list of distance vectors of the form (dst addr, cost), which are taken from the routers forwarding table.

Routers exchange distance vector packets with their neighbors periodically or in response to link/node failures or recoveries. After distance vector routing tables converge, routers will then forward packets to their destinations on the calculated shortest paths. Because distance vector routing computes all pairs single shortest paths, tagging a packet with its destination address uniquely identifies the packets path through the network. To send a packet to the destination the router looks up the entry in its routing table for the destination and forwards the packet to the next-hop listed in table entry.

### **1.3.2 The Link State Routing Algorithm**

The Link State algorithm is another routing algorithm on which many protocols are based. In the LS routing algorithm, every router periodically broadcasts (via flooding) its local connectivity. This information is flooded in a Link State packet (LSP) which consists of the routers ID, a list of its neighbors IDs, and the cost of each connecting link. After all routers broadcast their LSP, every router knows the entire network topology. A router then computes a shortest-path spanning tree keeping itself as the

root of that tree. This information is then encoded in the routing table. A Link State routing table comprises of a list of tuples of the form (dst addr, next-hop), where dst addr is the address of the destination, and next-hop is the neighboring router on the shortest path to that destination.

The method of sending a packet in Link State routing is exactly the same as that for distance vector routing

## 1.4 Problems with Selfish Routing

The biggest problem with selfish routing [17, 18] is that the routing decision is based node's perspective rather than on a system-wide perspective this leads to suboptimal system behavior. Some research has been done to find out the effect of selfish routing on network's efficiency [15, 16, 19] and how much selfish routing hampers the performance of network [20, 21, 22].

Selfish routing has three major drawbacks [23].

1. Only one path per source-destination pair is used, while other paths are left unused, this potentially limits the throughput of the network.
2. It is susceptible to oscillation, these oscillations are caused due to abrupt shift in traffic from one link to another when some of the shortest paths change because of change in link lengths.
3. If a routing loop exists the data packet will keep on traversing in the loop till

routing table is again updated.

## 1.5 Work Done

This thesis presents probabilistic adaptive routing algorithm. This algorithm is proposed as a solution to the problems faced by selfish routing. As opposed to selfish routing which decides in favor of single path, it assigns probabilities multiple paths between a source destination. This improves the utilization of available network resources mainly the bandwidth. Simulations of the algorithm were carried out to measure the performance of the algorithm in dynamic networks.

## 1.6 Organization of the thesis

Chapter 1 gives the basic background of routing in today's internet. Then it discusses the basic goals of routing in communication networks. After that a brief introduction of the link state and distance vector routing is presented. These two algorithms form the base of most of the routing protocols currently employed in the internet. Then the problems faced with Selfish Routing are described.

Chapter 2 describes the probabilistic routing algorithm and the structure of the routing table. Then it gives a description of how the problems are solved. Finally this chapter concludes with an example of working of this algorithm on a simple network.

Chapter 3 describes the implementation and simulations carried out to study the performance of the probabilistic routing algorithm, and presents the results obtained

from the simulations.

Chapter 4 gives the conclusion and scope for future work.

# Chapter 2

## The Probabilistic Routing Algorithm

This chapter presents a *Probabilistic Routing Algorithm* as a solution to the problems stated in the previous chapter.

### 2.1 Structure of the Routing Table

The Routing Table for the algorithm consists of the pairs of next-hop and the probability of data packet taking that path. Consider a node  $i$  in the network having  $N$  neighbors. The routing table of node  $i$ , for every destination  $k$  will have probabilities  $p_{ik}(j)$  for every neighbor  $j \in 1, \dots, N$ . The routing table of node  $i$  is shown in Table 2.1

where the entity  $p_{ik}(j)$  stands for probability of path from node  $i$  to destination node  $k$  via neighbor  $j$ . All probabilities satisfy:

$$p_{ik}(j) \geq 0$$

and,

$$\sum_j p_{ik}(j) = 1$$

Destination	(Next-Hop, Probability) pairs
1	$(1, p_{i1}(1)), \dots, (j, p_{i1}(j)), \dots (N, p_{i1}(N))$
$\vdots$	$\vdots$
$k$	$(1, p_{ik}(1)), \dots, (j, p_{ik}(j)), \dots (N, p_{ik}(N))$
$\vdots$	$\vdots$

Table 2.1: Routing Table of node  $i$ .

## 2.2 Advantages of the Structure

This section consists of the description of how the structure solves the problems faced in Selfish Routing.

### 2.2.1 Using Multiple Paths

In Selfish Routing the routing table consists of a next-hop for every destination, to route a packet to the destination, the router looks up the next hop for the destination and forwards it to the next hop. This is the source of the first problem, because, of all the paths available only one (the shortest) path will always be used. As seen from the routing table all available paths are present and have a finite probability so all the paths will be used, hence the throughput of the network will be improved

### 2.2.2 Network Oscillations

Network Oscillations occur because of single path selection. For example if two paths exist for a destination, selfish routing selects the better among the two and starts routing the traffic on that path. After some time the path becomes congested so selfish routing starts to send all the traffic on the second path till it becomes congested. This repetitive pattern gives rise to oscillations in the network. The figure 2.1 depicts a simple scenario in which oscillations will occur.

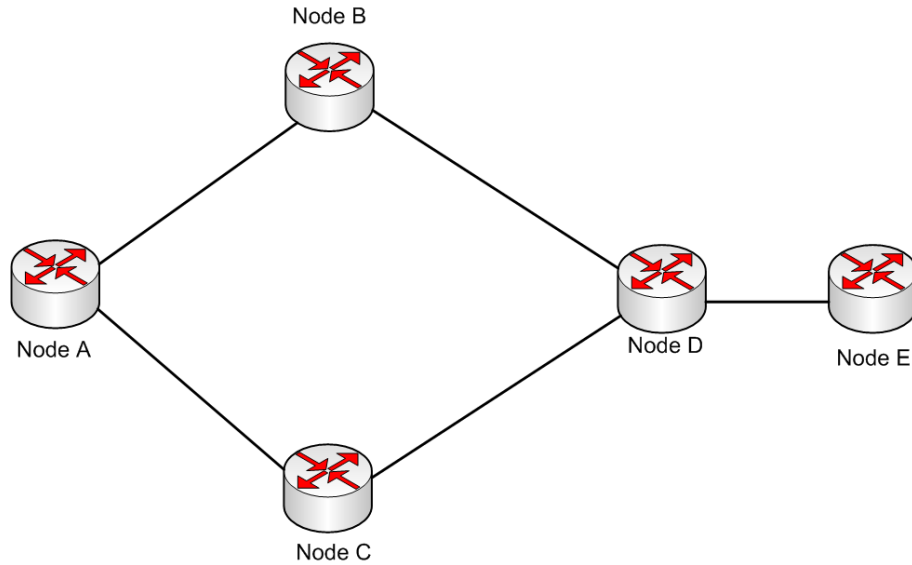


Figure 2.1: Scenario depicting Network Oscillations

To route the traffic from node *A* to node *E* selfish routing will choose one route *ABDE* (say). Once the path becomes congested it will start to route packets on the path *ACDE* till it becomes congested, and the pattern repeats itself.

For the same scenario probabilistic routing will route packets on both routes hence none of the routes will be congested.

### 2.2.3 Routing Loops

Figure 2.2 depicts a scenario in which routing loop can occur. In case of Selfish Routing if for sending a packet from node *A* to node *G*. The routing tables of the nodes *B*, *C* and *D* in the network are as shown in the table below. Node *A* will send packets to either node *B* or node *C*. If packets are sent to *B* then the path traversed will be *ABDCBD* and if the packets are sent to *C* then the path traversed will be *ACBDCB* and a routing loop will occur in both cases.

While in case of Probabilistic Routing there will be finite probabilities of packets taking any given path. The probability that a packet will be stuck in a loop is low.

Furthermore, even if a packet traverses a loop, it will not stay in the loop till the routing table is updates.

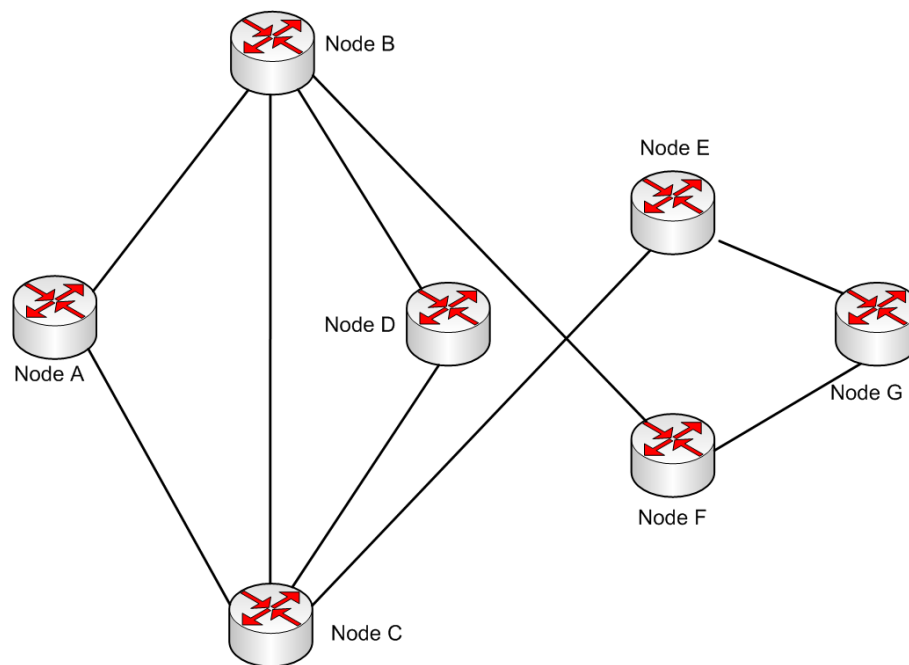


Figure 2.2: Scenario demonstrating Network Loop

Dest.	NextHop	Dest.	NextHop	Dest.	NextHop
A	A	A	A	A	C
B	B	B	B	B	B
C	C	C	C	C	C
D	D	D	D	D	D
E	C	E	E	E	C
F	F	F	D	F	F
G	D	G	B	G	C



## 2.3 The Algorithm

This section presents the routing algorithm developed to create the routing table shown in Section 2.1. The goal is to assign probabilities to paths via each neighbor according to the cost to the destination.

Consider a node  $i$  with  $N$  neighbors. For computing the routing table at node  $i$  for destination  $k$ . The node  $i$  has to store the following:

- $q_{ik}(j)$  It is the probabilistic weight for a path from node  $i$  to node  $k$  via neighbor  $j$ . This weight is proportional to the cost of the path from node  $i$  to node  $k$  via neighbor  $j$ .
- $q_{ik}^{prev}(j)$  It is the previous value of  $q_{ik}(j)$ .
- $p_{ik}(j)$  It is the probability of choosing the path from node  $i$  to node  $k$  via neighbor  $j$ . All probabilities satisfy  $p_{ik}(j) \geq 0$  and  $\sum_j p_{ik}(j) = 1$ .
- $p_{ik}^{prev}(j)$  It is the previous value of  $p_{ik}(j)$ .
- $l_j$  It is the cost from the node  $i$  to its neighbor  $j$ .
- $L_{jk}$  It is the estimated cost to the destination  $k$  as reported by neighbor  $j$ .

### 2.3.1 Computation of the Routing Table

This section describes how the routing table at node  $i$  for the destination  $k$  is computed.

After receiving an update  $L_{jk}$  from neighbor  $j$ , node  $i$  updates its cost estimate  $L_{ik}(j)$  i.e. estimated cost to destination  $k$  via neighbor  $j$  using equation 2.1. This procedure is repeated for every neighbor.

$$L_{ik}(j) = l_j + L_{jk} \quad (2.1)$$

Node  $i$  then computes overall cost estimate to destination  $k$  using equation 2.2. This overall cost estimate is used for assigning probabilistic weights to each path and

is sent as an update to every neighbor of node  $i$ .

$$E[L_{ik}] = \sum_j p_{ik}^{prev}(j) L_{ik}(j) \quad (2.2)$$

Initially when routing table does not exist the algorithm uses equal probabilities for computing the estimated cost. The equal probabilities are only for paths through those neighbors from which update for the destination is received. All the following computations use previous values of probabilities.

Using the estimated costs node  $i$  then computes the probabilistic weights for each path using equation 2.3.

$$q_{ik}(j) = q_{ik}^{prev}(j) + \frac{q_{ik}^{prev}(j)(E[L_{ik}] - L_{ik}(j))}{\omega} \quad (2.3)$$

Initially when the routing table does not exist all  $q_{ik}^{prev}(j)$  are assigned equal weights 1. For all further computations previous values of  $q_{ik}(j)$  are used.  $\omega$  is a weighing factor used to deal with negative values of  $E[L_{ik}] - L_{ik}(j)$ .

If the cost of path to destination  $k$  via neighbor  $j$  satisfies

$$L_{ik}(j) < E[L_{ik}]$$

i.e. the path through neighbor  $j$  has less cost than the estimated cost then

$$q_{ik}(j) > q_{ik}^{prev}(j)$$

the probabilistic weight of the path through neighbor  $j$  increases. If the cost of path to destination  $k$  via neighbor  $j$  satisfies

$$L_{ik}(j) > E[L_{ik}]$$

i.e. the path through neighbor  $j$  has more cost than the estimated cost then

$$q_{ik}(j) < q_{ik}^{prev}(j)$$

the probabilistic weight of the path through neighbor  $j$  decreases. This ensures that paths with low cost have high probabilistic weights and paths with high cost will have low probabilistic weights.

As the desired relationship between cost of the paths and probabilistic weights has been established node  $i$  uses equation 2.4 to compute the probabilities.

$$p_{ik}(j) = \frac{q_{ik}(j)}{\sum_j q_{ik}(j)} \quad (2.4)$$

Node  $i$  uses the values of  $p_{ik}(j)$  to update the routing table. The algorithm is explained below:

```

Do forever
[
  If an event occurs
  [
    For every neighbor  $j \in 1 \dots N$ 
    [
      assign all  $q_{ik}(j)$  to  $q_{ik}^{prev}(j)$ 
      assign all  $p_{ik}(j)$  to  $p_{ik}^{prev}(j)$ 
      compute  $L_{ik}(j)$  using equation 2.1
      compute  $E[L_{ik}]$  using equation 2.2
      compute  $q_{ik}(j)$  using equation 2.3
      compute  $p_{ik}(j)$  using equation 2.4
      update the routing table
    ]
    For every destination in the routing table
    [
      Send an update to every neighbor
    ]
  ]
]

```

An event is either an arrival of update or a link going up or down, or a link's cost changes.

A node will not send the update for a destination to the neighbors through which it has the path to that destination. Consider a node  $\mathcal{S}$  having 5 neighboring nodes  $\mathcal{A}$ ,  $\mathcal{B}$ ,  $\mathcal{C}$ ,  $\mathcal{D}$  and  $\mathcal{E}$ . If for target node  $\mathcal{T}$ , node  $\mathcal{S}$  has paths through neighbors  $\mathcal{A}$ ,  $\mathcal{B}$  and  $\mathcal{E}$ , then  $\mathcal{S}$  will send the update  $L_{\mathcal{S}\mathcal{T}}$  only to nodes  $\mathcal{C}$  and  $\mathcal{D}$ . The update  $L_{\mathcal{S}\mathcal{T}}$  will not be sent to  $\mathcal{A}$ ,  $\mathcal{B}$  and  $\mathcal{E}$ .

Also, when an update  $L_{jk}$  is received at node  $i$ , if the destination  $k$  is also neighbor

of node  $i$ , then it is checked whether neighbor  $j$  is reporting a path with less cost than the direct path to neighbor  $k$ . If neighbor  $j$  reports a path with lesser cost then the update  $L_{jk}$  is used for computing the routing table otherwise the update is rejected. This scenario is depicted in figure 2.3.

When node  $E$  receives an update  $L_{CD}$  (of cost 5) it calculates  $L_{ED}(C) = l_C + L_{CD}$  and compares it with  $l_D$ . In this case  $L_{ED}(C) < l_D$  so the update is not used in computation.

When node  $C$  receives an update  $L_{ED}$  (of cost 2) it calculates  $L_{CD}(E) = l_E + L_{ED}$  and compares it with  $l_D$ . In this case  $L_{CD}(E) > l_D$  so node  $C$  uses this node in computation of routing table.

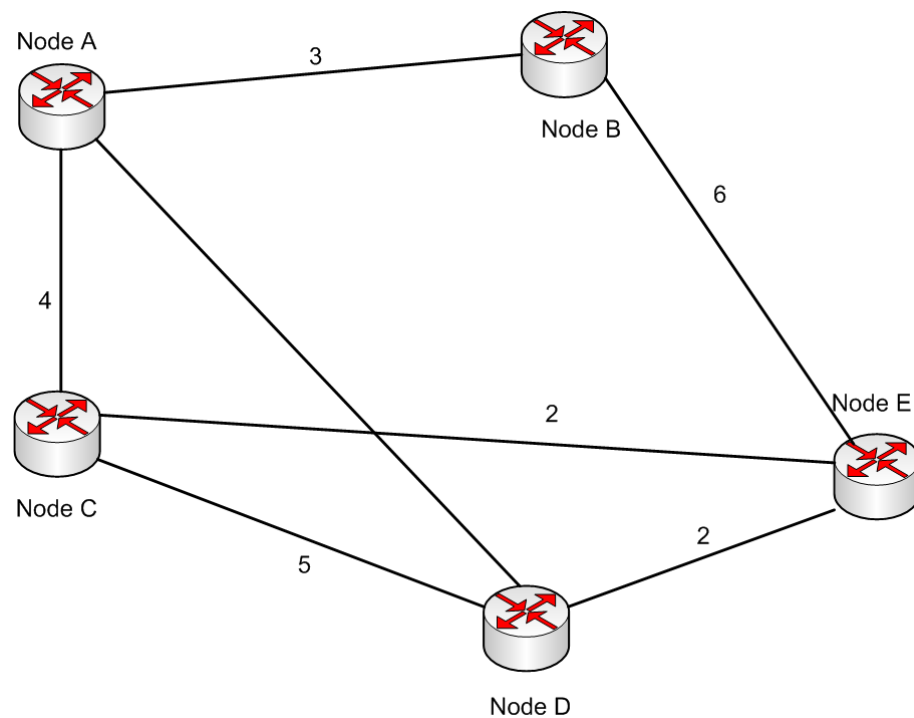


Figure 2.3: Demonstration of update rejection

## 2.4 Example Network

Figure 2.4 shows a simple network which will be used to show how the routing algorithm works.

Initially node 1 has information only about its neighbors (2, 3 and 4) so it creates an entry for each of its neighbors. The routing table of node 1 looks like:

Dest.	(NextHop, Probability)
2	(2, 1)
3	(3, 1)
4	(4, 1)

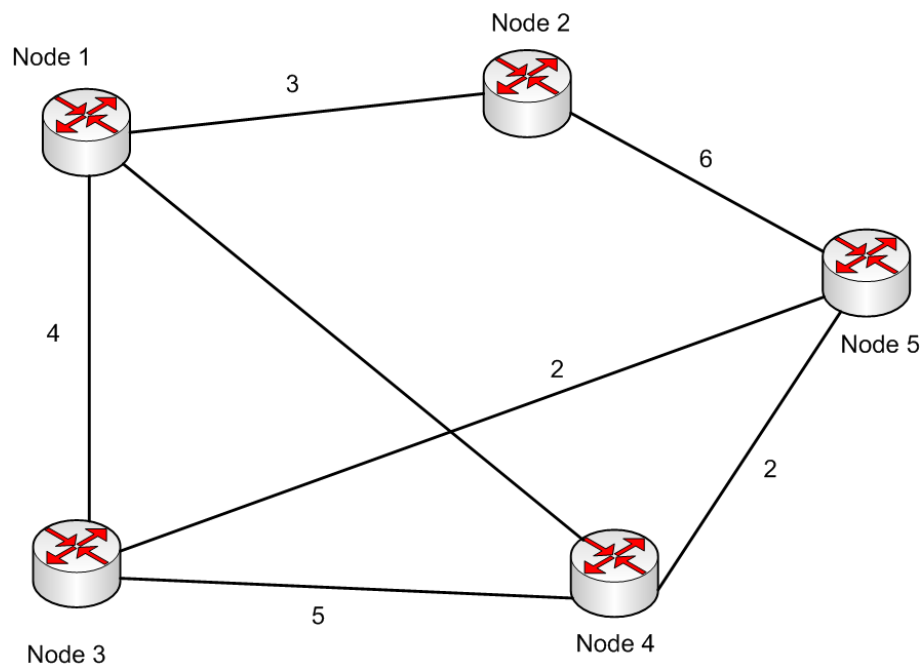


Figure 2.4: Example Network

Similarly the initial routing tables of nodes 2, ..., 5 contain only information about their respective neighbors. Their routing tables have similar form as node 1.

Node 2 sends an update  $L_{25}$ , similarly node 3 sends two updates  $L_{34}$  and  $L_{35}$ , and node 4 sends two updates  $L_{43}$  and  $L_{45}$  to node 1. Consider update  $L_{34}$ , node 1 has the

direct path to node 4,  $l_4 = 7$ , using equation 2.1 node 1 computes:

$$L_{14}(3) = l_3 + L_{34} = 4 + 5 = 9$$

which is more than  $l_4$  hence this update is rejected. Similarly using equation 2.1 node 1 computes:

$$L_{13}(4) = l_4 + L_{43} = 7 + 5 = 12$$

hence the update  $L_{43}$  is also rejected because  $l_3 < L_{13}(4)$ .

There are three updates for node 5,  $L_{25} = 6$ ,  $L_{35} = 2$  and  $L_{45} = 2$ . Now  $l_2 = 3$ ,  $l_3 = 4$  and  $l_4 = 7$ . Substituting these values in equation 2.1 node 1 computes:

$$L_{15}(2) = l_2 + L_{25} = 3 + 6 = 9$$

$$L_{15}(3) = l_3 + L_{35} = 4 + 2 = 6$$

and

$$L_{15}(4) = l_4 + L_{45} = 7 + 2 = 9$$

As there is no entry for node 5 the previous values of probabilistic weights are  $q_{15}^{prev}(2) = q_{15}^{prev}(3) = q_{15}^{prev}(4) = 1$ , similarly the previous values of routing probabilities are  $p_{15}^{prev}(2) = p_{15}^{prev}(3) = p_{15}^{prev}(4) = 1/3$ .

These values are substituted in equation 2.2 and estimated cost to node 5 comes out to be

$$E[L_{15}] = \frac{1}{3}[9 + 6 + 9] = 8$$

Using equation 2.3 the probabilistic weights become  $q_{15}(2) = 0.9$ ,  $q_{15}(3) = 1.2$  and  $q_{15}(4) = 0.9$ . Using equation 2.4 the probabilities are computed and we get  $p_{15}(2) = 0.3$ ,  $p_{15}(3) = 0.4$  and  $p_{15}(4) = 0.3$ . The routing table of node 1 becomes:

Dest	(NextHop, Probability)
2	(2, 1)
3	(3, 1)
4	(4, 1)
5	(2, 0.3), (3, 0.4), (4, 0.3)

Node 2 receives updates  $L_{13} = 4$  and  $L_{14} = 7$  from node 1 and updates  $L_{53} = 2$  and  $L_{54} = 2$ . Consider updates  $L_{13} = 4$  and  $L_{53} = 2$  first, node 2 already has  $l_1 = 3$  and  $l_5 = 6$ . Substituting these values in equation 2.1 node 2 computes

$$L_{23}(1) = l_1 + L_{13} = 3 + 4 = 7$$

$$L_{23}(5) = l_5 + L_{53} = 6 + 2 = 8$$

As there is no entry for node 3 the previous values of probabilistic weights are  $q_{23}^{prev}(1) = q_{23}^{prev}(5) = 1$ , similarly the previous values of routing probabilities are  $p_{23}^{prev}(1) = p_{23}^{prev}(5) = 1/2$ .

These values are substituted in equation 2.2 and estimated cost to node 3 comes out to be

$$E[L_{23}] = \frac{1}{2}[7 + 8] = 7.5$$

Using equation 2.3 the probabilistic weights become  $q_{23}(1) = 1.05$  and  $q_{23}(5) = 0.95$ .

Using equation 2.4 the probabilities are computed and we get  $p_{23}(1) = 0.525$  and  $p_{23}(5) = 0.475$ .

Consider updates  $L_{14} = 7$  and  $L_{54} = 2$  first, node 2 already has  $l_1 = 3$  and  $l_5 = 6$ . Substituting these values in equation 2.1 node 2 computes

$$L_{24}(1) = l_1 + L_{14} = 3 + 7 = 10$$

$$L_{24}(5) = l_5 + L_{54} = 6 + 2 = 8$$

As there is no entry for node 4 the previous values of probabilistic weights are  $q_{24}^{prev}(1) = q_{24}^{prev}(5) = 1$ , similarly the previous values of routing probabilities are  $p_{24}^{prev}(1) = p_{24}^{prev}(5) = 1/2$ .

These values are substituted in equation 2.2 and estimated cost to node 4 comes out to be

$$E[L_{24}] = \frac{1}{2}[10 + 8] = 9$$

Using equation 2.3 the probabilistic weights become  $q_{24}(1) = 0.9$  and  $q_{24}(5) = 1.1$ .

Using equation 2.4 the probabilities are computed and we get  $p_{24}(1) = 0.45$  and  $p_{24}(5) = 0.55$ . The routing table of node 2 becomes:



Dest	(NextHop, Probability)
1	(1, 1)
3	(1, 0.525), (5, 0.475)
4	(1, 0.45), (5, 0.55)
5	(5, 1)

Node 3 receives updates  $L_{12} = 3$  and  $L_{14} = 7$  from node 1, updates  $L_{41} = 7$  and  $L_{45} = 2$  from node 5 and updates  $L_{52} = 6$  and  $L_{54} = 2$  from node 5. Consider update  $L_{41}$ , node 3 has the direct path to node 1,  $l_1 = 4$ , using equation 2.1 node 3 computes  $L_{31}(4) = 12$  which is more than  $l_1$  hence this update is rejected.

Consider updates  $L_{12} = 3$  and  $L_{52} = 6$  first, node 3 already has  $l_1 = 4$  and  $l_5 = 2$ . Substituting these values in equation 2.1 node 3 computes  $L_{32}(1) = l_1 + L_{12} = 4 + 3 = 7$   $L_{32}(5) = l_5 + L_{52} = 2 + 6 = 8$  As there is no entry for node 3 the previous values of probabilistic weights are  $q_{32}^{prev}(1) = q_{32}^{prev}(5) = 1$ , similarly the previous values of routing probabilities are  $p_{32}^{prev}(1) = p_{32}^{prev}(5) = 1/2$ .

These values are substituted in equation 2.2 and estimated cost to node 2 comes out to be

$$E[L_{32}] = \frac{1}{2}[7 + 8] = 7.5$$

Using equation 2.3 the probabilistic weights become  $q_{32}(1) = 1.05$  and  $q_{32}(5) = 0.95$ . Using equation 2.4 the probabilities are computed and we get  $p_{32}(1) = 0.525$  and  $p_{32}(5) = 0.475$ .

Consider update  $L_{14}$ , node 3 has the direct path to node 4,  $l_4 = 5$ , using equation 2.1 node 3 computes

$$L_{34}(1) = l_1 + L_{14} = 4 + 7 = 11$$

which is more than  $l_4$  hence this update is rejected. Consider update  $L_{54}$ , node 3 has the direct path to node 4,  $l_4 = 5$ , using equation 2.1 node 3 computes

$$L_{34}(5) = l_5 + L_{54} = 2 + 2 = 4$$

which is less than  $l_4$  hence this update is accepted. Node 3 already has  $L_{34}(4) = 5$ . The previous values of probabilistic weights used are  $q_{34}^{prev}(4) = q_{34}^{prev}(5) = 1$ , similarly the previous values of routing probabilities are  $p_{34}^{prev}(4) = p_{34}^{prev}(5) = 1/2$ .

These values are substituted in equation 2.2 and estimated cost to node 4 comes out to be

$$E[L_{34}] = \frac{1}{2}[4 + 5] = 4.5$$

Using equation 2.3 the probabilistic weights become  $q_{34}(4) = 0.95$  and  $q_{34}(5) = 1.05$ . Using equation 2.4 the probabilities are computed and we get  $p_{34}(4) = 0.475$  and  $p_{34}(5) = 0.525$ .

Consider update  $L_{45}$ , node 3 has the direct path to node 5,  $l_5 = 2$ , using equation 2.1 node 3 computes  $L_{35}(4) = l_4 + L_{45} = 5 + 2 = 7$  which is more than  $l_7$  hence this update is rejected. The routing table of node 3 becomes:

Dest	(NextHop, Probability)
1	(1, 1)
2	(1, 0.525), (5, 0.475)
4	(4, 0.475), (5, 0.525)
5	(5, 1)

Node 4 receives updates  $L_{12} = 3$  and  $L_{13} = 4$  from node 1, updates  $L_{31} = 4$  and  $L_{35} = 2$  from node 2 and updates  $L_{52} = 6$  and  $L_{53} = 2$  from node 5. Consider update  $L_{31}$ , node 4 has the direct path to node 1,  $l_1 = 7$ , using equation 2.1 node 4 computes

$$L_{41}(3) = l_3 + L_{31} = 5 + 4 = 9$$

which is more than  $l_1$  hence this update is rejected.

Consider updates  $L_{12} = 3$  and  $L_{52} = 6$  first, node 4 already has  $l_1 = 7$  and  $l_5 = 2$ . Substituting these values in equation 2.1 node 4 computes

$$L_{42}(1) = l_1 + L_{12} = 7 + 3 = 10$$

$$L_{42}(5) = l_5 + L_{52} = 2 + 6 = 8$$

As there is no entry for node 2 the previous values of probabilistic weights are  $q_{42}^{prev}(1) = q_{52}^{prev}(5) = 1$ , similarly the previous values of routing probabilities are  $p_{42}^{prev}(1) = p_{42}^{prev}(5) = 1/2$ .

These values are substituted in equation 2.2 and estimated cost to node 2 comes out to be

$$E[L_{42}] = \frac{1}{2}[10 + 8] = 9$$

Using equation 2.3 the probabilistic weights become  $q_{42}(1) = 0.9$  and  $q_{42}(5) = 1.1$ . Using equation 2.4 the probabilities are computed and we get  $p_{42}(1) = 0.45$  and  $p_{42}(5) = 0.55$ .

Consider update  $L_{13}$ , node 4 has the direct path to node 3,  $l_3 = 5$ , using equation 2.1 node 4 computes

$$L_{43}(1) = l_1 + L_{13} = 7 + 4 = 11$$

which is more than  $l_3$  hence this update is rejected.

Consider update  $L_{53}$ , node 4 has the direct path to node 3,  $l_3 = 5$ , using equation 2.1 node 4 computes

$$L_{43}(5) = l_5 + L_{53} = 2 + 2 = 4$$

which is less than  $l_3$  hence this update is accepted. Node 4 already has  $L_{43}(3) = 5$ . The previous values of probabilistic weights used are  $q_{43}^{prev}(3) = q_{43}^{prev}(5) = 1$ , similarly the previous values of routing probabilities are  $p_{43}^{prev}(3) = p_{43}^{prev}(5) = 1/2$ .

These values are substituted in equation 2.2 and estimated cost to node 3 comes out to be

$$E[L_{43}] = \frac{1}{2}[4 + 3] = 4.5$$

Using equation 2.3 the probabilistic weights become  $q_{43}(3) = 0.95$  and  $q_{43}(5) = 1.05$ . Using equation 2.4 the probabilities are computed and we get  $p_{43}(3) = 0.475$  and  $p_{43}(5) = 0.525$ .

Consider update  $L_{35}$ , node 4 has the direct path to node 5,  $l_5 = 2$ , using equation 2.1 node 4 computes  $L_{45}(3) = 7$  which is more than  $l_5$  hence this update is rejected. The

routing table of node 4 becomes:

Dest	(NextHop, Probability)
1	(1, 1)
2	(1, 0.45), (5, 0.55)
3	(3, 0.475), (5, 0.525)
5	(5, 1)

Node 5 receives update  $L_{21} = 3$  from node 2, updates  $L_{31} = 4$  and  $L_{34} = 5$  from node 3 and updates  $L_{41} = 7$  and  $L_{43} = 5$  from node 4.

There are three updates for node 1,  $L_{21} = 3$ ,  $L_{31} = 4$  and  $L_{41} = 7$ . Now  $l_2 = 6$ ,  $l_3 = 2$  and  $l_4 = 2$ . Substituting these values in equation 2.1 node 5 computes

$$L_{51}(2) = l_2 + L_{21} = 6 + 3 = 9$$

$$L_{51}(3) = l_3 + L_{31} = 2 + 4 = 6$$

and

$$L_{51}(4) = l_4 + L_{41} = 2 + 7 = 9$$

As there is no entry for node 1 the previous values of probabilistic weights are  $q_{51}^{prev}(2) = q_{51}^{prev}(3) = q_{51}^{prev}(4) = 1$ , similarly the previous values of routing probabilities are  $p_{51}^{prev}(2) = p_{51}^{prev}(3) = p_{51}^{prev}(4) = 1/3$ .

These values are substituted in equation 2.2 and estimated cost to node 1 comes out to be

$$E[L_{51}] = \frac{1}{3}[9 + 6 + 9] = 8$$

Using equation 2.3 the probabilistic weights become  $q_{51}(2) = 0.9$ ,  $q_{51}(3) = 1.2$  and  $q_{51}(4) = 0.9$ . Using equation 2.4 the probabilities are computed and we get  $p_{51}(2) = 0.3$ ,  $p_{51}(3) = 0.4$  and  $p_{51}(4) = 0.3$ .

Consider update  $L_{43}$ , node 5 has the direct path to node 3,  $l_3 = 2$ , using equation 2.1 node 5 computes

$$L_{53}(4) = l_4 + L_{43} = 2 + 5 = 7$$

which is more than  $l_3$  hence this update is rejected.

Consider update  $L_{34}$ , node 5 has the direct path to node 4,  $l_4 = 2$ , using equation 2.1 node 5 computes

$$L_{54}(3) = l_3 + L_{34} = 2 + 5 = 7$$

which is more than  $l_4$  hence this update is rejected. The routing table of node 5 becomes:

Dest	(NextHop, Probability)
1	(2, 0.3), (3, 0.4), (4, 0.3)
2	(2, 1)
3	(3, 1)
4	(4, 1)

# Chapter 3

## Simulation and Results

For the purpose of simulation, the routing algorithm was implemented in the Network Simulator ns-2 [1, 11, 28]. Ns-2 is an open source network simulator which is written in OTcl and C++. The parameters which were measured are Convergence Time, Load on the Routers and Queue Size, all these parameters are described below. The study comprised of the effect of the factors route computation delay, events occurring in the network and frequency of updates on the above stated parameters. Extensive simulations were performed to analyse the effects of these factors.

### 3.1 Implementation Details

The implementation of the algorithm on ns-2, comprises of three functional blocks.

- First block discovers a node's neighbors by sending hello packets. Hello packets were sent at a fixed interval. Once a node receives a hello packet from its neighbor it waits for a fixed amount of time called  *Holding Time* , and if the node does not get another hello packet from that neighbor it declares it as down.
- Second block sends updates to its neighbors. Updates are sent after fixed inter-

vals, with the exception when an event occurs then updates are sent immediately. This helps the network to adapt quickly to changes in topology of the network.

- The third block computes the routing table based on the updates received.

The simulations were performed on two different networks. They are shown in figure 3.1 and figure 3.2. In all simulations the networks were given 10 seconds to attain steady state, after the duration all the traffic was started and events were triggered. The events are a link going up or down, or a change in cost of a link. All events were triggered randomly.

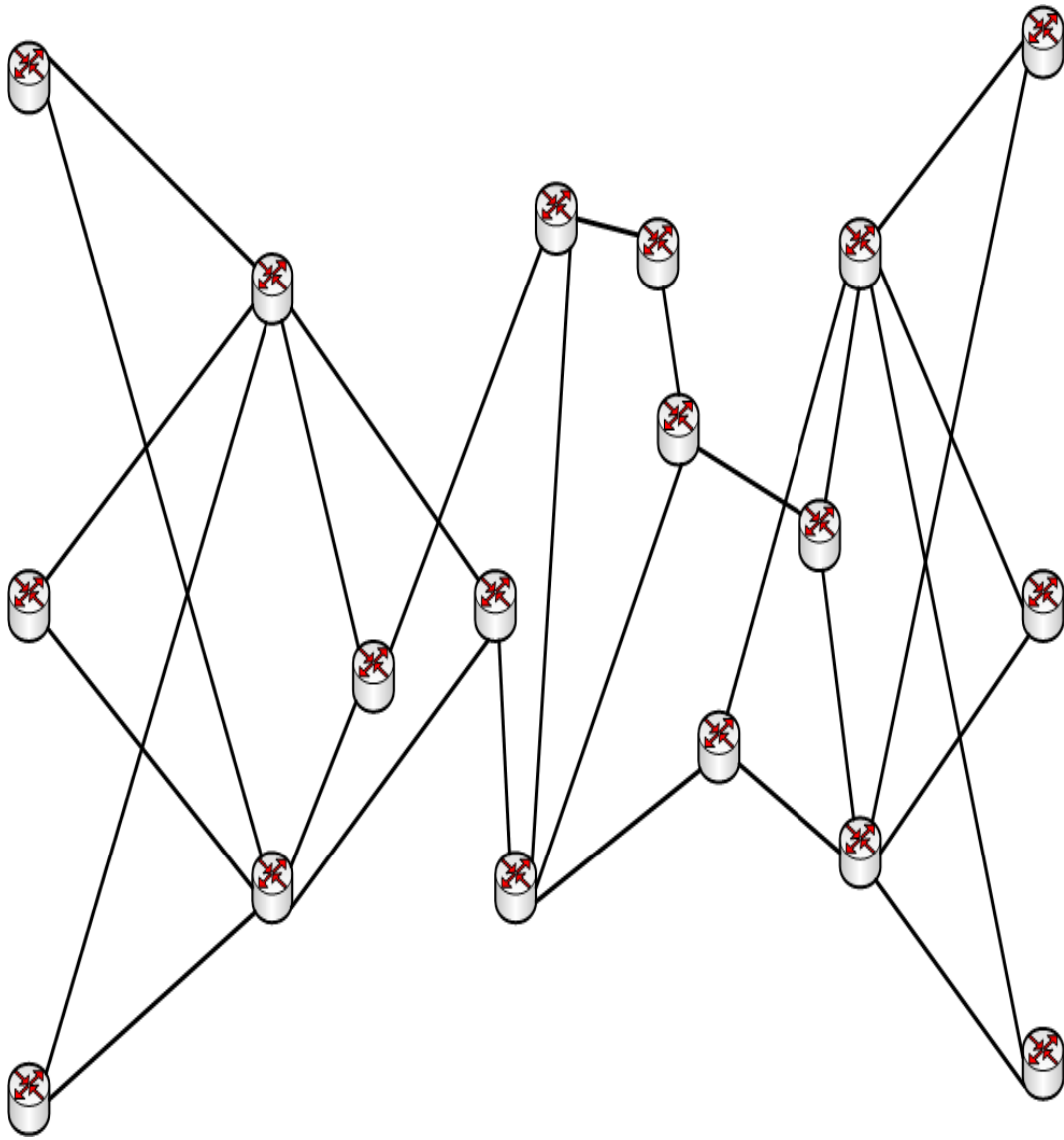


Figure 3.1: Network A



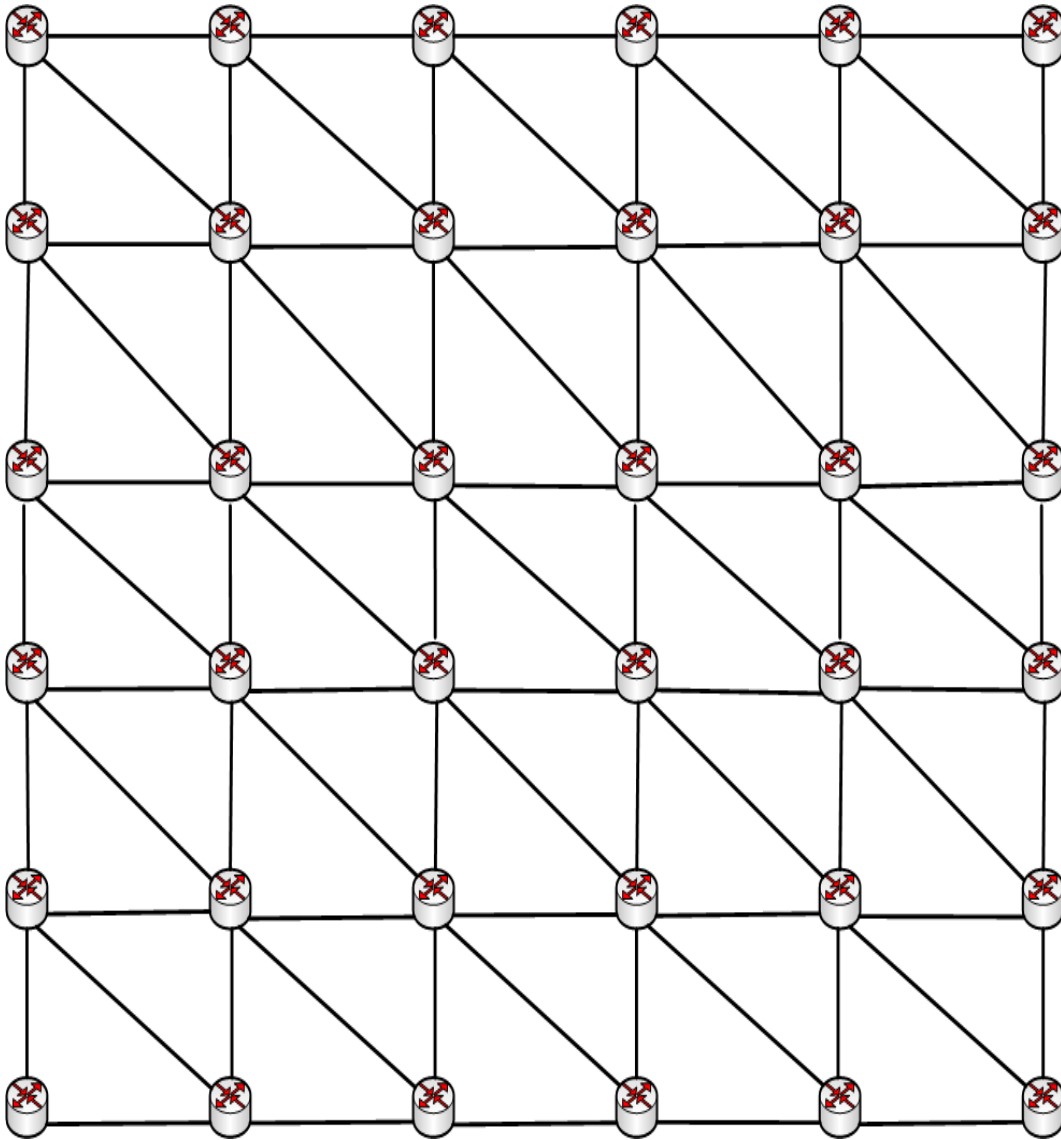


Figure 3.2: Network B

## 3.2 Factors affecting the performance

- **Route Computation Delay:** A router computes the routing table when an event occurs or an update arrives. However it is not efficient if the router computes its routing table after receiving every update. The reason behind this is that

on occurrence of an event more than one updates are generated. Hence if on receiving every update a router computes its routing table, then the load on the router increases. To tackle this problem a Route Computation Delay is employed. As the router receives an update it starts a timer and it computes its routing tables when the time out happens. In this duration router will receive more update packets and all will be used in computation of the routing table. A low value of Route Computation Delay implies that all the updates may not be incorporated and routing table will be computed many times, this increases the load on the router. However a high value of this delay implies that the network convergence time will increase which is undesirable.

- Events: Events as stated above are a link going up or down, or a change in cost. Events were triggered at random instants. Events are used to analyze how the algorithm works in a dynamically changing network like the internet.
- Frequency of Updates: Updates are sent to neighboring nodes to provide a consistent view of the network's topology. The routing algorithm running on each node uses this topology to compute the routing table. It is desirable that updates are sent frequently so as to incorporate the frequent changes occurring in the network. However having a high frequency of updates or sending a high number of updates per unit time increases the latency in the network because it increases the number of queued packets queued on a router. Moreover a high frequency of updates implies that the routing table will be calculated more frequently thus increasing load on the routers.

## 3.3 Results

### 3.3.1 Convergence Time

For analysis convergence time [2] is defined as the time duration between occurrence of an event and the time when each router in the network has updated its routing table with the new information. A low convergence time is desired so that the network can adapt to the changes in a network quickly. The goal of a routing algorithm is to minimize the convergence time while keeping the load on the routers low.

Route computation delay is incorporated to involve several updates for computation of routing table. Several simulations were carried out to calculate average Convergence Time for the values of Route Computation Delay varying from 100 msec. to 2 sec. on both Network A and Network B. Figure 3.3 shows the average convergence times vs route computation delay for network A and figure 3.4 shows the same for network B.

Simulations were carried out for various values of update frequencies. It can be observed from the plots, for higher frequency of updates the algorithm converges quickly.

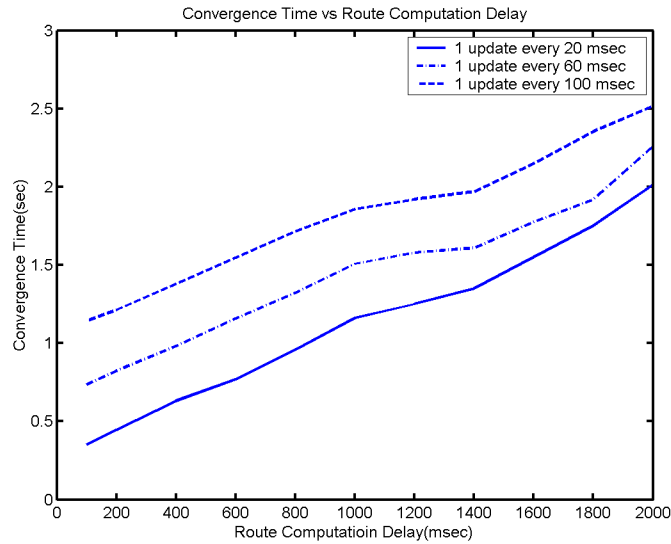


Figure 3.3: Convergence Time vs Route Computation Delay for Network A

During the simulations events were randomly generated in time to observe the behavior of convergence time as the number of events vary. For this purpose links were broken down and brought up again where the time instant when a link is broken down and the duration for which the link remains down were kept random. Also cost of links were changed randomly. Figure 3.5 and figure 3.6 show the variation of convergence time as a function of number of events occurring in the network for network A and network B respectively

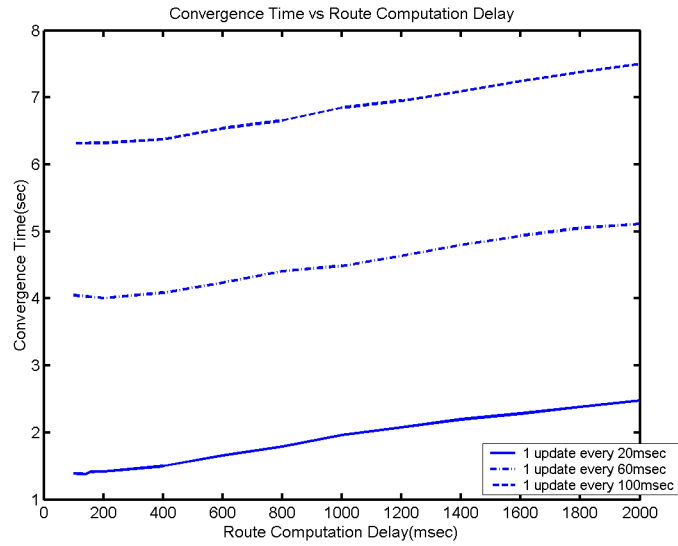


Figure 3.4: Convergence Time vs Route Computation Delay for Network B

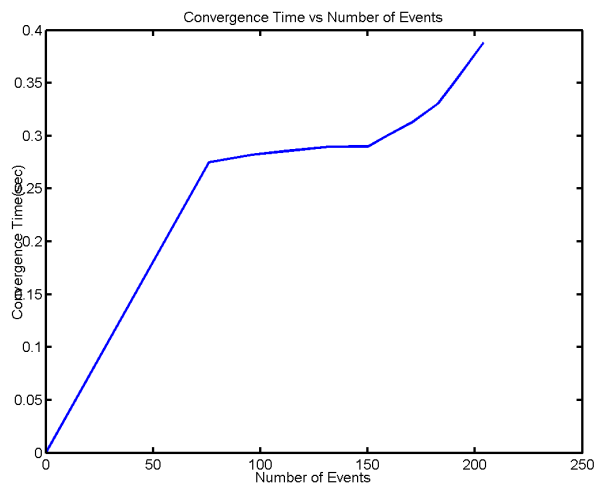


Figure 3.5: Convergence Time vs Number of Events for Network A

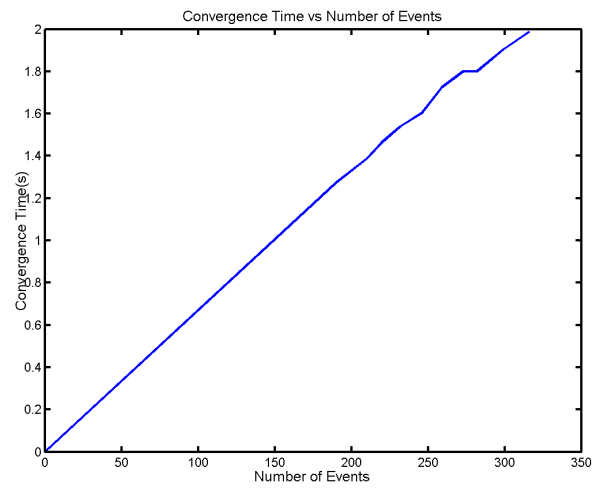


Figure 3.6: Convergence Time vs Number of Events for Network B

### 3.3.2 Load on the Routers

The load on a router is defined as how much percentage of total time it spends in computing the routing table. As parameters are varied to minimize the convergence time of a network, it has to be determined how much load is put on the routers in the process.

As route computation delay is varied to observe the behavior of convergence time, the effect of this variation on router load is shown in figure 3.7 for network A and the same for network B is shown in figure 3.8.

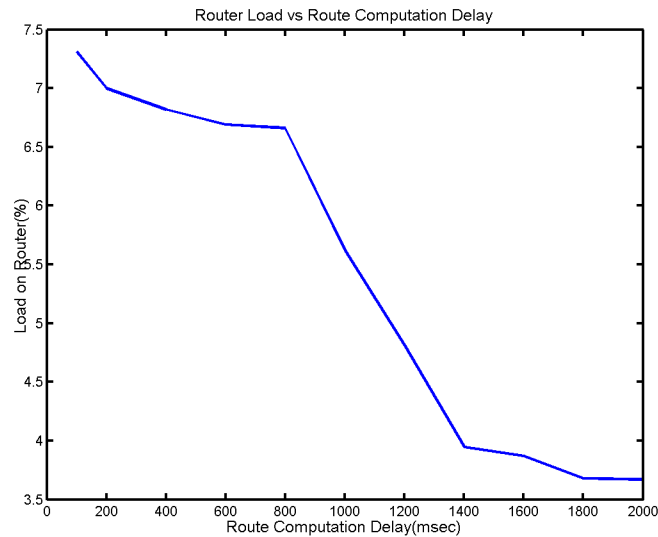


Figure 3.7: Router Load in percentage vs Route Computation Delay for Network A

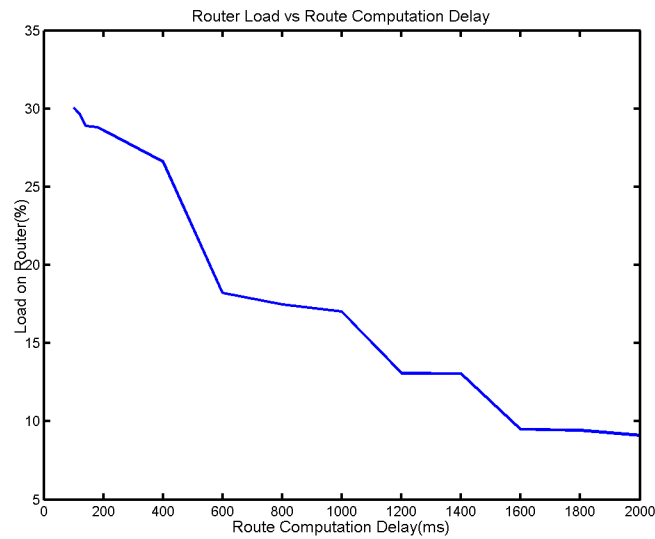


Figure 3.8: Router load in percentage vs Route Computation Delay for Network B

### 3.3.3 Size of the Queue

The size of the queue of any router is indicative of two things, how much load is on the router and the congestion in the networks [10]. To minimize end to end latency in a network the size of queue should be small. Queue size is mainly affected by the frequency of updates. To observe this effect the queue size vs time of a router is plotted for different values of update frequency. This is shown in figure 3.9.

The figure shows that for a high value of update frequency, less packets are queued up. For lower values of update frequency update packets are queued up at the routers hence the maximum size of the queue increases as update frequency is decreased.



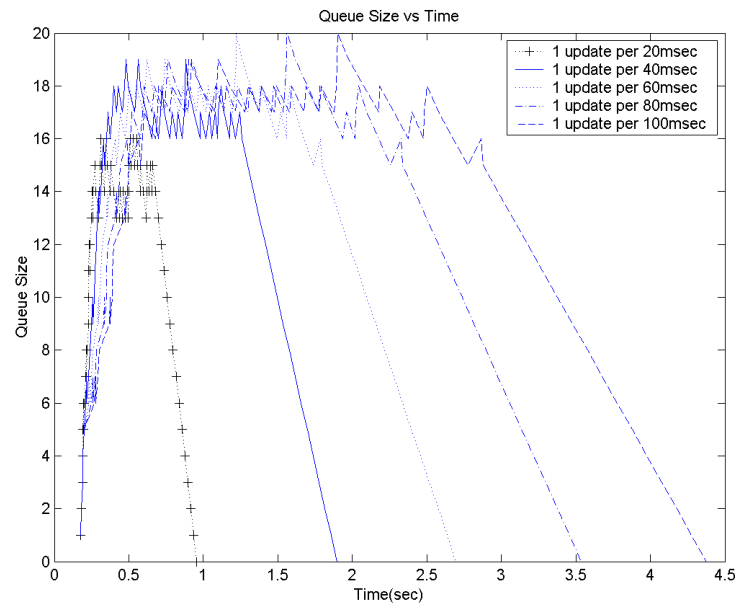


Figure 3.9: Size of Queue on a router vs Time

# Chapter 4

## Conclusion

This thesis presented a probabilistic routing algorithm to overcome the problems faced with selfish routing. For this purpose a new structure for the routing table and a slightly different routing algorithm is proposed. The algorithm deals with the problems by providing multiple paths to a destination, where every path is assigned probability according to the cost to the destination.

Performance of the algorithm was measured in terms of time taken to converge, load on the routers and queue size. Convergence time is desired to be low for a routing algorithm. Variation of convergence time was observed for different values of route computation delay. It was observed that as route computation delay was increased the algorithm took more time to converge. This is expected because the less frequently routing table is computed the more time the network takes to adapt to topology changes.

The performance of the algorithm was also studied in the event of changes occurring. It was measured in terms of variation of convergence time with the number of events. This helps in determining how the algorithm will perform when employed in dynamically changing networks like the internet.

The load on the routers was also analysed in terms of variation of route computation delay. As the figures show load on the routers decreases with decrease in route

computation delay. This is because routers compute their routing tables less frequently.

Queue sizes were analysed for various values of update frequencies. Queue size is indicative of latency, because the number of packets queued at the router implies large queuing delay.

## 4.1 Future Aspects

This algorithm does not support hierarchical routing. For simulations to make the algorithm scalable, entries in the routing table were removed if an update for that destination does not arrive within a fixed interval.

This algorithm does not need a precise view of the network topology, hence it can be applied to wireless networks as well. As of now no simulations have been carried out to study the performance of the algorithm in wireless networks.

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