ASPRS LiDAR Data Exchange Format Standard LAS

Definition: Files conforming to the ASPRS LIDAR data exchange format standard are named with a LAS extension. The LAS file is intended to contain LIDAR point data records.

The format contains binary data in little-endian format.

Mainly data consists:

PUBLIC HEADER BLOCK

VARIABLE LENGTH RECORDS

POINT DATA

Why LAS Format?

- To provide an open standard format for different LiDAR user group.
- •To incorporate all useful informations of LiDAR data collection process in one single compressed file.
- •To provide standard file format for LiDAR data processing softwares.

Data types used in LAS format:

```
char (1 byte)
unsigned char (1 byte)
short (2 bytes)
unsigned short (2 bytes)
long (4 bytes)
unsigned long (4 bytes)
double (8 byte IEEE floating point format)
```

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Details of LAS file format (Version 1.0):

1. Public Header Block

File signature ("LASF") char[4]

Reserved unsigned long

GUID data1 unsigned long

GUID data2 unsigned short

GUID data3 unsigned short

GUID data4 unsigned char[8]

Version major unsigned char

Version major unsigned char

System identifier char[32]

Generating software char[32]

Flight date julian unsigned short

Year unsigned short

Header size unsigned short

Public Header Block Continued...

Offset to data unsigned long

Number of variable length records unsigned long

Point data format ID (0-99 for spec) unsigned char

Point data record length unsigned short

Number of point records unsigned long

Number of points by return unsigned long[5]

X scale factor double

Y scale factor double

Z scale factor double

X offset double

Y offset double

Z offset double

Max X double

Min X double

Max Y double

Min Y double

Max Z double

Min Z double

2. Variable Length Records: The projection information for the point data is required for all data. The projection information will be placed in the variable length records.

Record Signature (0xAABB) unsigned short

User ID char[16]

Record ID unsigned short

Record Length After Header unsigned short

Description char[32]

Variable Length Records Continued...

Record Signature: The record signature is a two byte data field that must contain 0xAABB.

User ID: The user ID field is ASCII character data that identifies the user which created the variable length record.

Record ID: The record ID is dependent upon the User ID. There can be 0 to 65535 record Ids for every User ID.

Record Length after Header: The record length is the number of bytes for the record after the end of the standard part of the header.

Description: Optional null terminated text description of the data. Any remaining characters not used must be null.

Point Data Start Signature:

Two bytes after the last variable length record, and before the point data 0xCCDD.

3.1. Point Data Record Format 0:

X long

Y Iong Z

Intensity unsigned short

Return Number 3 bits

Number of Returns (given pulse) 3 bits

Scan Direction Flag 1 bit

Edge of Flight Line 1 bit

Classification unsigned char

Scan Angle Rank (-90 to +90) char

File Marker unsigned char

User Bit Field unsigned short

3.2. Point Data Record Format 1:

X Iong

Z long

Intensity unsigned short

Return Number 3 bits
Number of Poturns (given pulse) 3 bits

Number of Returns (given pulse) 3 bits

Scan Direction Flag 1 bit Edge of Flight Line 1 bit

Classification unsigned char

Scan Angle Rank (-90 to +90) char

File Marker unsigned char

User Bit Field unsigned short

GPS Time double

Description:

X, Y, and Z: The X, Y, and Z values are stored as long integers.

Intensity: The intensity value is the integer representation of the pulse return magnitude.

Return Number: The return number is the pulse return number for a given output pulse.

Number of Returns (given pulse): The number of returns is the total number of returns for a given pulse. So a laser data point may be return two (return number) with a total number of five returns.

Scan Direction Flag: The scan direction flag denotes the direction at which the scanner mirror. A bit value of 1 is a positive scan direction, and a bit value of 0 is a negative scan direction.

Edge of Flight Line: The edge of flight line data bit has a value of 1 only when the point is at the end of a scan.

Classification: The classification field is a number to signify a given classification during filter processing.

Scan Angle Rank: The scan angle is within 1 degree of accuracy from +90 to –90 degrees.

File Marker: The file marker is an optional field that should be used in conjunction with the variable length records. The file marker allows for the LAS flight-line based files to be combined into single files with more than one flight-line.

User Bit Field: A bit field that is to be used at the users discretion.

GPS Time: The GPS time is the double floating point time tag value at which the point was acquired.

LAS FORMAT VERSION 1.1

1. Public Header Block

File Signature ("LASF")

File Source ID

Reserved

Project ID-GUID data1

Project ID-GUID data2

Project ID-GUID data3

Project ID-GUID data4

Version Major

Version Major

System Identifier

Generating Software

File Creation Day of Year

File Creation Year

Header Size

char[4]

unsigned short

unsigned short

unsigned long

unsigned short

unsigned short

unsigned char[8]

unsigned char

unsigned char

char[32]

char[32]

unsigned short

unsigned short

unsigned short

2. Variable Length Records: The projection information for the point data is required for all data. The projection information will be placed in the variable length records.

(1.1) Reserved unsigned short

User ID char[16]

Record ID unsigned short

Record Length After Header unsigned short

Description char[32]

NOTE: Point Data Start Signature has been removed in LAS Version 1.1.

3. Point Data Record Format 0:

X Iong

Z

Intensity unsigned short

Return Number 3 bits

Number of Returns (given pulse) 3 bits

Scan Direction Flag 1 bit

Edge of Flight Line 1 bit

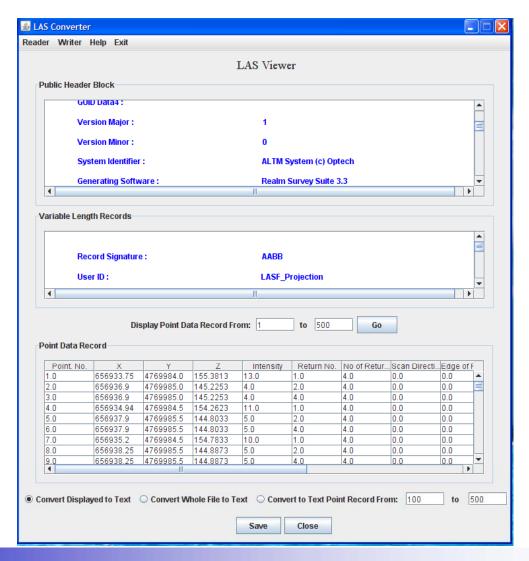
Classification unsigned char

Scan Angle Rank (-90 to +90) char

User Data unsigned char

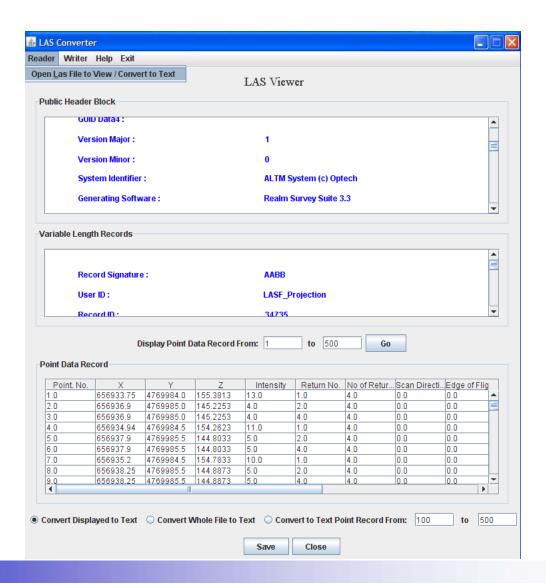
Point Source ID unsigned short

LAS Converter version 1.1 (LAS To Text and Text to LAS Conversion Software)

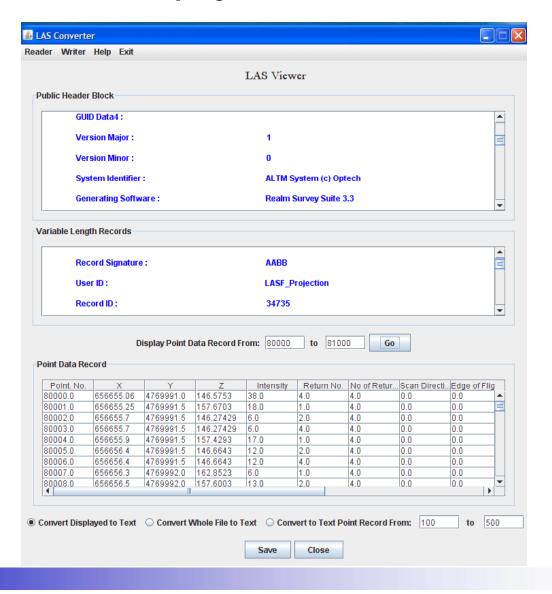


Functions of the software

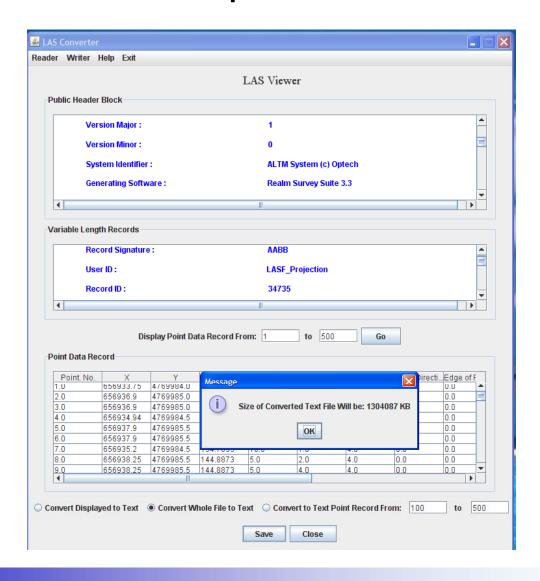
Reader:



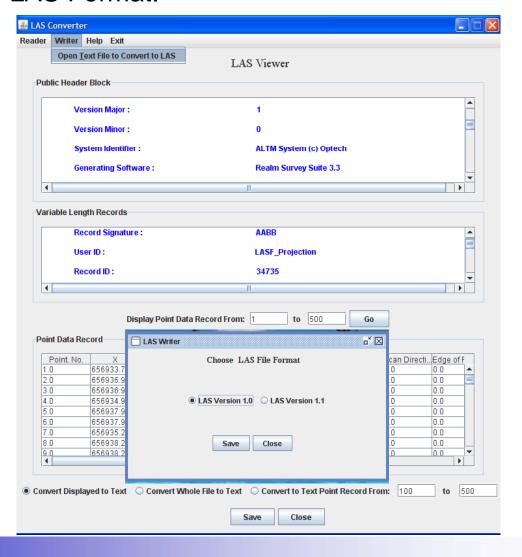
Point data record displayed in the table from 80000 to 81000.



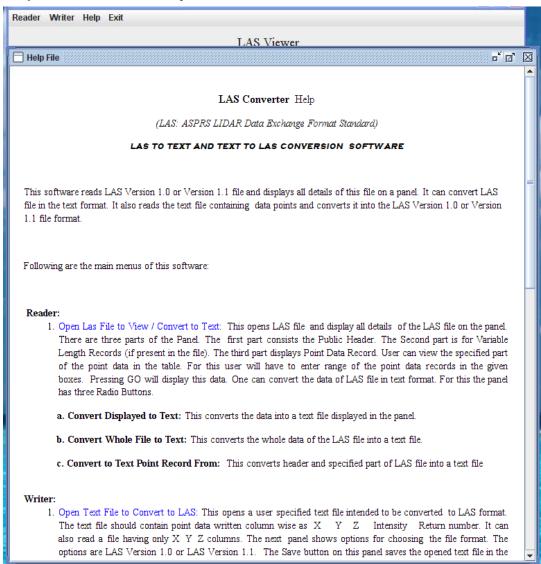
It also shows how much space will be needed for converting files



Writer: It converts text file containing X Y Z Intensity Number of Returns into LAS Format.



Help: Help file assists you to how to use this software efficiently.





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